#### **Features**

- Fast Read Access Time 120 ns
- Dual Voltage Range Operation
  - Unregulated Battery Power Supply Range, 2.7V to 3.6V or Standard 5V ±10% Supply Range
- Pin Compatible with JEDEC Standard AT27C4096
- Low Power CMOS Operation
  - 20  $\mu$ A Max (Less than 1  $\mu$ A Typical) Standby for  $V_{CC}$  = 3.6V
  - 36 mW Max Active at 5 MHz for V<sub>CC</sub> = 3.6V
- JEDEC Standard Surface Mount Packages
  - 44-lead PLCC
  - 40-lead VSOP
- High Reliability CMOS Technology
  - 2,000V ESD Protection
  - 200 mA Latchup Immunity
- Rapid Programming algorithm 100 µs/Word (Typical)
- CMOS and TTL Compatible Inputs and Outputs
  - JEDEC Standard for LVTTL and LVBO
- Integrated Product Identification Code
- Industrial Temperature Range
- · Green (Pb/Halide-free) Packaging Option

### 1. Description

The AT27BV4096 is a high-performance, low-power, low-voltage 4,194,304-bit one-time programmable read-only memory (OTP EPROM) organized as 256K by 16 bits. It requires only one supply in the range of 2.7V to 3.6V in normal read mode operation. The by-16 organization makes this part ideal for portable and handheld 16 and 32 bit microprocessor based systems using either regulated or unregulated battery power.

Atmel's innovative design techniques provide fast speeds that rival 5V parts while keeping the low power consumption of a 3V supply. At  $V_{\rm CC}$  = 2.7V, any word can be accessed in less than 120 ns. With a typical power dissipation of only 18 mW at 5 MHz and  $V_{\rm CC}$  = 3V, the AT27BV4096 consumes less than one fifth the power of a standard 5V EPROM.

Standby mode supply current is typically less than 1  $\mu$ A at 3V. The AT27BV4096 simplifies system design and stretches battery lifetime even further by eliminating the need for power supply regulation.

The AT27BV4096 is available in industry-standard JEDEC-approved one-time programmable (OTP) plastic PLCC and VSOP packages. All devices feature two-line control ( $\overline{\text{CE}}$ ,  $\overline{\text{OE}}$ ) to give designers the flexibility to prevent bus contention.

The AT27BV4096 operating with  $V_{CC}$  at 3.0V produces TTL level outputs that are compatible with standard TTL logic devices operating at  $V_{CC} = 5.0$ V. At  $V_{CC} = 2.7$ V, the part is compatible with JEDEC approved low voltage battery operation (LVBO) interface specifications. The device is also capable of standard 5-volt operation making it ideally suited for dual supply range systems or card products that are pluggable in both 3-volt and 5-volt hosts.



4-Megabit
(256K x 16)
Unregulated
Battery-Voltage
High-Speed
OTP EPROM

AT27BV4096

Not Recommended for New Designs.

0640E-EPROM-8/07





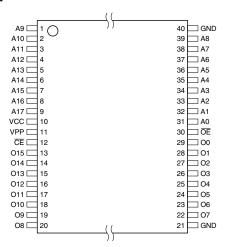
Atmel's AT27BV4096 has additional features to ensure high quality and efficient production use. The Rapid Programming Algorithm reduces the time required to program the part and guarantees reliable programming. Programming time is typically only 100  $\mu$ s/word. The Integrated Product Identification Code electronically identifies the device and manufacturer. This feature is used by industry-standard programming equipment to select the proper programming algorithms and voltages. The AT27BV4096 programs exactly the same way as a standard 5V AT27C4096 and uses the same programming equipment.

## 2. Pin Configurations

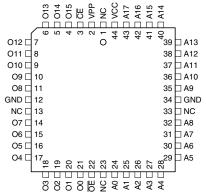
Pin Name	Function
A0 - A17	Addresses
O0 - O15	Outputs
CE	Chip Enable
ŌĒ	Output Enable
NC	No Connect

Note: Both GND pins must be connected.

### 2.1 40-lead VSOP Top View Type 1



### 2.2 44-lead PLCC Top View



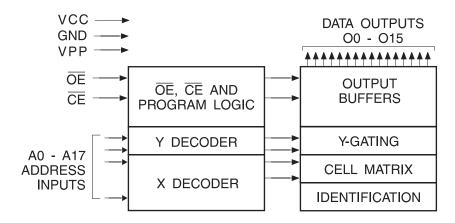
Note: PLCC package pins 1 and 23 are Don't Connect.

2

## 3. System Considerations

Switching between active and standby conditions via the Chip Enable pin may produce transient voltage excursions. Unless accommodated by the system design, these transients may exceed datasheet limits, resulting in device non-conformance. At a minimum, a 0.1  $\mu$ F high frequency, low inherent inductance, ceramic capacitor should be utilized for each device. This capacitor should be connected between the  $V_{CC}$  and Ground terminals of the device, as close to the device as possible. Additionally, to stabilize the supply voltage level on printed circuit boards with large EPROM arrays, a 4.7  $\mu$ F bulk electrolytic capacitor should be utilized, again connected between the  $V_{CC}$  and Ground terminals. This capacitor should be positioned as close as possible to the point where the power supply is connected to the array.

### 4. Block Diagram



## 5. Absolute Maximum Ratings\*

Temperature Under Bias55° C to +125° C
Storage Temperature65° C to +150° C
Voltage on Any Pin with Respect to Ground2.0V to +7.0V <sup>(1)</sup>
Voltage on A9 with Respect to Ground2.0V to +14.0V <sup>(1)</sup>
V <sub>PP</sub> Supply Voltage with Respect to Ground2.0V to +14.0V <sup>(1)</sup>

\*NOTICE:

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability

Note: 1. Minimum voltage is -0.6V DC which may undershoot to -2.0V for pulses of less than 20 ns. Maximum output pin voltage is V<sub>CC</sub> + 0.75V DC which may be exceeded if certain precautions are observed (consult application notes) and which may overshoot to +7.0V for pulses of less than 20 ns.





## 6. Operating Modes

Mode/Pin	CE	ŌĒ	Ai	$V_{PP}$	V <sub>cc</sub>	Outputs
Read <sup>(2)</sup>	V <sub>IL</sub>	V <sub>IL</sub>	Ai	X <sup>(1)</sup>	V <sub>CC</sub>	D <sub>OUT</sub>
Output Disable <sup>(2)</sup>	Х	V <sub>IH</sub>	X	Х	V <sub>CC</sub>	High Z
Standby <sup>(2)</sup>	V <sub>IH</sub>	Х	Х	X <sup>(5)</sup>	V <sub>CC</sub>	High Z
Rapid Program <sup>(3)</sup>	V <sub>IL</sub>	V <sub>IH</sub>	Ai	V <sub>PP</sub>	V <sub>CC</sub>	D <sub>IN</sub>
PGM Verify <sup>(3)</sup>	V <sub>IH</sub>	$V_{IL}$	Ai	$V_{PP}$	V <sub>CC</sub>	D <sub>OUT</sub>
PGM Inhibit <sup>(3)</sup>	V <sub>IH</sub>	V <sub>IH</sub>	Х	V <sub>PP</sub>	V <sub>CC</sub>	High Z
Product Identification <sup>(3)(5)</sup>	V <sub>IL</sub>	V <sub>IL</sub>	$A9 = V_{H}^{(4)}$ $A0 = V_{IH} \text{ or } V_{IL}$ $A1 - A17 = V_{IL}$	V <sub>cc</sub>	V <sub>cc</sub>	Identification Code

Notes: 1. X can be  $V_{IL}$  or  $V_{IH}$ .

- 2. Read, output disable, and standby modes require, 2.7V  $\leq$ V<sub>CC</sub>  $\leq$ 3.6V, or 4.5V  $\leq$ V<sub>CC</sub>  $\leq$ 5.5V.
- 3. Refer to Programming Characteristics. Programming modes require  $V_{CC} = 6.5V$ .
- 4.  $V_H = 12.0 \pm 0.5V$ .
- 5. Two identifier bytes may be selected. All Ai inputs are held low  $(V_{IL})$ , except A9 which is set to  $V_H$  and A0 which is toggled low  $(V_{IL})$  to select the Manufacturer's Identification byte and high  $(V_{IH})$  to select the Device Code byte.

## 7. DC and AC Operating Conditions for Read Operation

	AT27BV4096-12			
Industrial Operating Temperature (Case)	-40° C - 85° C			
V. Dawar Supply	2.7V to 3.6V			
V <sub>CC</sub> Power Supply	5V ±10%			

## 8. DC and Operating Characteristics for Read Operation

Symbol	Parameter	Condition	Min	Max	Units
V <sub>CC</sub> = 2.7	/ to 3.6V				
I <sub>LI</sub>	Input Load Current	V <sub>IN</sub> = 0V to V <sub>CC</sub>		±1	μΑ
I <sub>LO</sub>	Output Leakage Current	V <sub>OUT</sub> = 0V to V <sub>CC</sub>		±5	μA
I <sub>PP1</sub> <sup>(2)</sup>	V <sub>PP</sub> <sup>(1)</sup> Read/Standby Current	$V_{PP} = V_{CC}$		10	μA
	) (1) (1) (1) (1) (1)	$I_{SB1}$ (CMOS), $\overline{CE} = V_{CC \pm} 0.3V$		20	μA
I <sub>SB</sub>	V <sub>CC</sub> <sup>(1)</sup> Standby Current	$I_{SB2}$ (TTL), $\overline{CE}$ = 2.0 to $V_{CC}$ + 0.5V		100	μΑ
I <sub>CC</sub>	V <sub>CC</sub> Active Current	$f = 5 \text{ MHz}, I_{OUT} = 0 \text{ mA}, \overline{CE} = V_{IL}, V_{CC} = 3.6V$		10	mA
.,		V <sub>CC</sub> = 3.0 to 3.6V	-0.6	0.8	V
$V_{IL}$	Input Low Voltage	V <sub>CC</sub> = 2.7 to 3.6V	-0.6	0.2 x V <sub>CC</sub>	V
		V <sub>CC</sub> = 3.0 to 3.6V	2.0	V <sub>CC</sub> + 0.5	V
$V_{IH}$	Input High Voltage	V <sub>CC</sub> = 2.7 to 3.6V	0.7 x V <sub>CC</sub>	V <sub>CC</sub> + 0.5	V
		I <sub>OL</sub> = 2.0 mA		0.4	V
V <sub>OL</sub>	Output Low Voltage	I <sub>OL</sub> = 100 μA		0.2	V
		I <sub>OL</sub> = 20 μA		0.1	V
		I <sub>OH</sub> = -2.0 mA	2.4		V
$V_{OH}$	Output High Voltage	I <sub>OH</sub> = -100 μA	V <sub>CC</sub> - 0.2		V
		I <sub>OH</sub> = -20 μA	V <sub>CC</sub> - 0.1		V
V <sub>CC</sub> = 4.5	/ to 5.5V				
I <sub>LI</sub>	Input Load Current	$V_{IN} = 0V$ to $V_{CC}$		±1	μΑ
I <sub>LO</sub>	Output Leakage Current	V <sub>OUT</sub> = 0V to V <sub>CC</sub>		±5	μΑ
I <sub>PP1</sub> <sup>(2)</sup>	V <sub>PP</sub> <sup>(1)</sup> Read/Standby Current	$V_{PP} = V_{CC}$		10	μΑ
_	), (1) a, , , , ,	$I_{SB1}$ (CMOS), $\overline{CE} = V_{CC} \pm 0.3V$		100	μΑ
I <sub>SB</sub>	V <sub>CC</sub> <sup>(1)</sup> Standby Current	$I_{SB2}$ (TTL), $\overline{CE}$ = 2.0 to $V_{CC}$ + 0.5V		1	mA
I <sub>cc</sub>	V <sub>CC</sub> Active Current	$f = 5 \text{ MHz}, I_{OUT} = 0 \text{ mA}, \overline{CE} = V_{IL}$		40	mA
V <sub>IL</sub>	Input Low Voltage		-0.6	0.8	V
V <sub>IH</sub>	Input High Voltage		2.0	V <sub>CC</sub> + 0.5	V
V <sub>OL</sub>	Output Low Voltage	I <sub>OL</sub> = 2.1 mA		0.4	V
V <sub>OH</sub>	Output High Voltage	I <sub>OH</sub> = -400 μA	2.4		V

Notes: 1.  $V_{CC}$  must be applied simultaneously with or before  $V_{PP}$  and removed simultaneously with or after  $V_{PP}$ 

2.  $V_{PP}$  may be connected directly to  $V_{CC}$ , except during programming. The supply current would then be the sum of  $I_{CC}$  and  $I_{PP}$ 



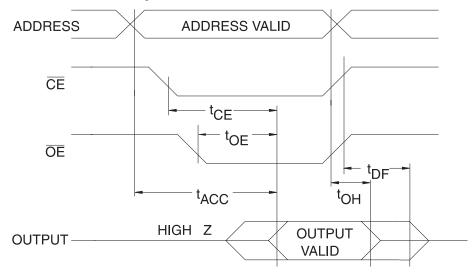


## 9. AC Characteristics for Read Operation

 $V_{CC} = 2.7V$  to 3.6V and 4.5V to 5.5V

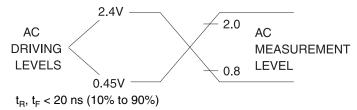
			AT27BV4096-12			
Symbol	Parameter	Condition	Min	Max	Units	
t <sub>ACC</sub> <sup>(3)</sup>	Address to Output Delay	CE = OE = V <sub>IL</sub>		120	ns	
t <sub>CE</sub> <sup>(2)</sup>	CE to Output Delay	OE = V <sub>IL</sub>		120	ns	
t <sub>OE</sub> <sup>(2)(3)</sup>	OE to Output Delay	CE = V <sub>IL</sub>		35	ns	
t <sub>DF</sub> <sup>(4)(5)</sup>	OE or CE High to Output Float, Whichever Occurred First			30	ns	
t <sub>OH</sub>	Output Hold from Address, $\overline{\text{CE}}$ or $\overline{\text{OE}}$ , Whichever Occurred First		0		ns	

# 10. AC Waveforms for Read Operation<sup>(1)</sup>

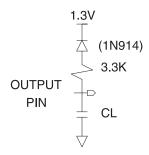


- Notes: 1. Timing measurement references are 0.8V and 2.0V. Input AC drive levels are 0.45V and 2.4V, unless otherwise specified.
  - 2.  $\overline{\text{OE}}$  may be delayed up to  $t_{\text{CE}}$   $t_{\text{OE}}$  after the falling edge of  $\overline{\text{CE}}$  without impact on  $t_{\text{CE}}$ .
  - 3.  $\overline{\text{OE}}$  may be delayed up to  $t_{\text{ACC}}$   $t_{\text{OE}}$  after the address is valid without impact on  $t_{\text{ACC}}$ .
  - 4. This parameter is only sampled and is not 100% tested.
  - 5. Output float is defined as the point when data is no longer driven.
  - 6. When reading a AT27BV4096, a 0.1  $\mu$ F capacitor is required across  $V_{CC}$  and ground to suppress spurious voltage transients.

## 11. Input Test Waveforms and Measurement Levels



## 12. Output Test Load



Note: CL = 100 pF including jig capacitance.

# 13. Pin Capacitance

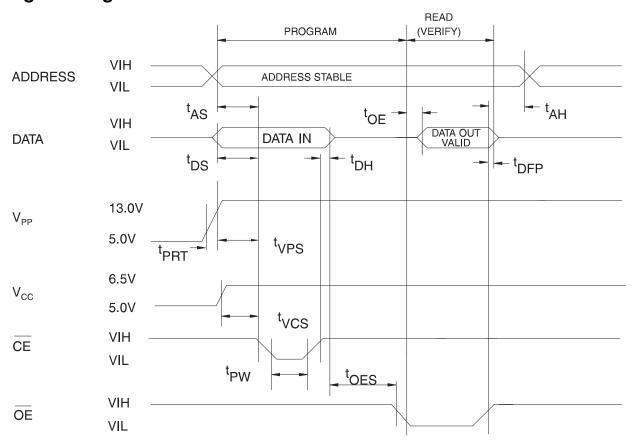
 $f = 1 \text{ MHz } T = 25^{\circ}C^{(1)}$ 

Symbol	Тур Мах		Units	Conditions	
C <sub>IN</sub>	4	10	pF	$V_{IN} = 0V$	
C <sub>OUT</sub>	8	12	pF	V <sub>OUT</sub> = 0V	

Note: 1. Typical values for nominal supply voltage. This parameter is only sampled and is not 100% tested.



# 14. Programming Waveforms<sup>(1)</sup>



Notes:

- 1. The Input Timing Reference is 0.8V for  $V_{\rm IL}$  and 2.0V for  $V_{\rm IH}$ .
- 2.  $t_{\text{OE}}$  and  $t_{\text{DFP}}$  are characteristics of the device but must be accommodated by the programmer.
- 3. When programming the AT27BV4096 a 0.1  $\mu$ F capacitor is required across  $V_{PP}$  and ground to suppress spurious voltage transients.

## 15. DC Programming Characteristics

 $T_A = 25 \pm 5^{\circ} C$ ,  $V_{CC} = 6.5 \pm 0.25 V$ ,  $V_{PP} = 13.0 \pm 0.25 V$ 

			Lin	Limits	
Symbol	Parameter	Test Conditions	Min	Max	Units
ILI	Input Load Current	$V_{IN} = V_{IL}, V_{IH}$		±10	mA
V <sub>IL</sub>	Input Low Level		-0.6	0.8	V
V <sub>IH</sub>	Input High Level		2.0	V <sub>CC</sub> + 0.1	V
V <sub>OL</sub>	Output Low Voltage	I <sub>OL</sub> = 2.1 mA		0.4	V
V <sub>OH</sub>	Output High Voltage	I <sub>OH</sub> = -400 μA	2.4		V
I <sub>CC2</sub>	V <sub>CC</sub> Supply Current (Program and Verify)			50	mA
I <sub>PP2</sub>	V <sub>PP</sub> Supply Current	CE = V <sub>IL</sub>		30	mA
V <sub>ID</sub>	A9 Product Identification Voltage		11.5	12.5	V

## 16. AC Programming Characteristics

 $T_A = 25 \pm 5^{\circ} C$ ,  $V_{CC} = 6.5 \pm 0.25 V$ ,  $V_{PP} = 13.0 \pm 0.25 V$ 

			Lir		
Symbol	Parameter	Test Conditions <sup>(1)</sup>	Min	Min Max	
t <sub>AS</sub>	Address Setup Time		2		μs
t <sub>CES</sub>	CE Setup Time		2		μs
t <sub>OES</sub>	OE Setup Time	Input Rise and Fall Times:	2		μs
t <sub>DS</sub>	Data Setup Time	(10% to 90%) 20 ns	2		μs
t <sub>AH</sub>	Address Hold Time	Input Pulse Levels:	0		μs
t <sub>DH</sub>	Data Hold Time	0.45V to 2.4V	2		μs
t <sub>DFP</sub>	OE High to Output Float Delay <sup>(2)</sup>		0	130	ns
t <sub>VPS</sub>	V <sub>PP</sub> Setup Time	Input Timing Reference Level:  0.8V to 2.0V	2		μs
t <sub>VCS</sub>	V <sub>CC</sub> Setup Time	0.00 10 2.00	2		μs
t <sub>PW</sub>	PGM Program Pulse Width <sup>(3)</sup>	Output Timing Reference Level:	47.5	52.5	μs
t <sub>OE</sub>	Data Valid from OE	0.8V to 2.0V		150	ns
t <sub>PRT</sub>	V <sub>PP</sub> Pulse Rise Time During Programming		50		ns

Notes: 1.  $V_{CC}$  must be applied simultaneously or before  $V_{PP}$  and removed simultaneously or after  $V_{PP}$ 

- 2. This parameter is only sampled and is not 100% tested. Output Float is defined as the point where data is no longer driven see timing diagram.
- 3. Program Pulse width tolerance is 50  $\mu$ sec  $\pm$ 5%.

## 17. Atmel's AT27BV4096 Integrated Product Identification Code<sup>(1)</sup>

		Pins							Hex		
Codes	A0	O15-O8	07	<b>O</b> 6	O5	04	О3	O2	01	00	Data
Manufacturer	0	0	0	0	0	1	1	1	1	0	001E
Device Type	1	0	1	1	1	1	0	1	0	0	00F4

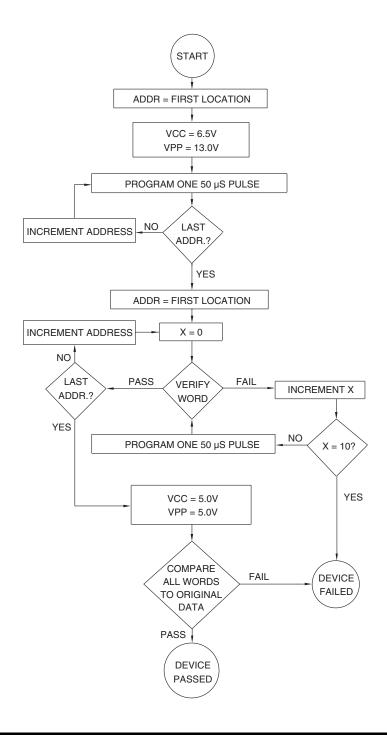
Note: 1. The AT27BV4096 has the same Product Identification Code as the AT27C4096. Both are programming compatible.





### 18. Rapid Programming Algorithm

A 50  $\mu s$   $\overline{CE}$  pulse width is used to program. The address is set to the first location.  $V_{CC}$  is raised to 6.5V and  $V_{PP}$  is raised to 13.0V. Each address is first programmed with one 50  $\mu s$   $\overline{CE}$  pulse without verification. Then a verification/reprogramming loop is executed for each address. In the event a word fails to pass verification, up to 10 successive 50  $\mu s$  pulses are applied with a verification after each pulse. If the word fails to verify after 10 pulses have been applied, the part is considered failed. After the word verifies properly, the next address is selected until all have been checked.  $V_{PP}$  is then lowered to 5.0V and  $V_{CC}$  to 5.0V. All words are read again and compared with the original data to determine if the device passes or fails.



# 19. Ordering Information

## 19.1 Standard Package

t <sub>ACC</sub>	t <sub>ACC</sub> I <sub>CC</sub> (mA) (ns) Active Standby				
(ns)			Ordering Code	Package	<b>Operation Range</b>
120	0	8 0.02	AT27BV4096-12JI	44J	Industrial
120	0		AT27BV4096-12VI	40V	(-40° C to 85° C)

Note: Refer to PCN# SC042702.

## 19.2 Green Package (Pb/Halide-free)

t <sub>ACC</sub>	I <sub>CC</sub> (mA)					
(ns)	Active Standby		Active Standby Ordering Code		Package	Operation Range
120	8	0.02	AT27BV4096-12JU	44J	Industrial (-40° C to 85° C)	

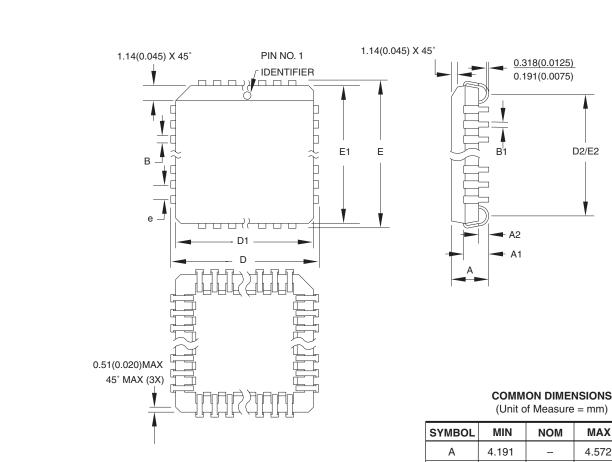
Package Type		
44J	44-lead, Plastic J-leaded Chip Carrier (PLCC)	
40V	40-lead, Plastic Thin Small Outline Package (VSOP)	





## 20. Packaging Information

#### 20.1 44J - PLCC



Notes:

- 1. This package conforms to JEDEC reference MS-018, Variation AC.
- 2. Dimensions D1 and E1 do not include mold protrusion. Allowable protrusion is .010"(0.254 mm) per side. Dimension D1 and E1 include mold mismatch and are measured at the extreme material condition at the upper or lower parting line.
- 3. Lead coplanarity is 0.004" (0.102 mm) maximum.

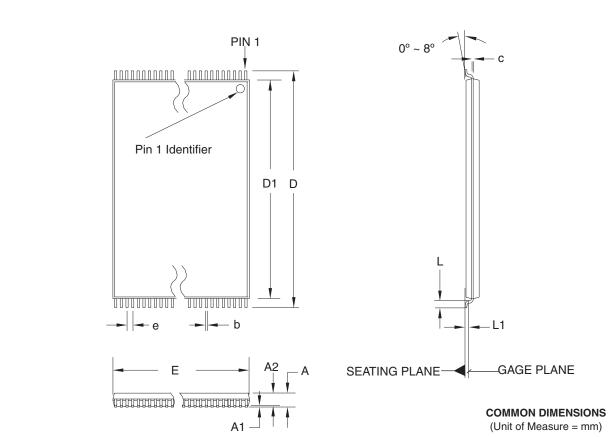
COMMON	DIMENSIONS
/I Init of M	0001180 8080)

NOTE 4.572 Α1 2.286 3.048 0.508 \_ A2 17.399 17.653 D 16.510 D1 16.662 Note 2 Ε 17.399 17.653 16.510 E1 16.662 Note 2 D2/E2 14.986 16.002 В 0.660 0.813 В1 0.330 0.533 1.270 TYP е

10/04/01

	TITLE	DRAWING NO.	REV.
2325 Orchard Parkway San Jose, CA 95131	44J, 44-lead, Plastic J-leaded Chip Carrier (PLCC)	44J	В

### 20.2 40T - VSOP



Notes:

- 1. This package conforms to JEDEC reference MO-142, Variation CA.
- 2. Dimensions D1 and E do not include mold protrusion. Allowable protrusion on E is 0.15 mm per side and on D1 is 0.25 mm per side.
- 3. Lead coplanarity is 0.10 mm maximum.

SYMBOL	MIN	NOM	MAX	NOTE
Α	_	_	1.20	
A1	0.05	_	0.15	
A2	0.95	1.00	1.05	
D	13.80	14.00	14.20	
D1	12.30	12.40	12.50	Note 2
E	9.90	10.00	10.10	Note 2
L	0.50	0.60	0.70	
L1	0.25 BASIC			
b	0.17	0.22	0.27	
С	0.10	_	0.21	
е	0.50 BASIC			

10/18/01

4Imei	2325 Orchard San Jose, CA	Parkway
AIIIEL	San Jose, CA	95131

**TITLE 40V**, 40-lead (10 x 14 mm Package) Plastic Thin Small Outline Package, Type I (VSOP)

DRAWING NO. REV. 40V B





#### Headquarters

Atmel Corporation

2325 Orchard Parkway San Jose, CA 95131 USA

Tel: 1(408) 441-0311 Fax: 1(408) 487-2600

#### International

Atmel Asia

Room 1219 Chinachem Golden Plaza 77 Mody Road Tsimshatsui East Kowloon Hong Kong

Tel: (852) 2721-9778 Fax: (852) 2722-1369 Atmel Europe

France

Le Krebs 8, Rue Jean-Pierre Timbaud BP 309 78054 Saint-Quentin-en-Yvelines Cedex

Tel: (33) 1-30-60-70-00 Fax: (33) 1-30-60-71-11

Atmel Japan

9F, Tonetsu Shinkawa Bldg. 1-24-8 Shinkawa Chuo-ku, Tokyo 104-0033 Japan

Tel: (81) 3-3523-3551 Fax: (81) 3-3523-7581

#### **Product Contact**

Web Site

www.atmel.com

Technical Support eprom@atmel.com

Sales Contact

www.atmel.com/contacts

Literature Requests

www.atmel.com/literature

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