

# \_General Description

The MAX127/MAX128 are multirange, 12-bit data acquisition systems (DAS) that require only a single +5V supply for operation, yet accept signals at their analog inputs that may span above the power-supply rail and below ground. These systems provide eight analog input channels that are independently software programmable for a variety of ranges: ±10V, ±5V, 0 to +10V, 0 to +5V for the MAX127; and  $\pm V_{REF}$ ,  $\pm V_{REF}/2$ , 0 to +VREF, 0 to +VREF/2 for the MAX128. This range switching increases the effective dynamic range to 14 bits and provides the flexibility to interface 4-20mA,  $\pm 12V$ , and  $\pm 15V$ -powered sensors directly to a single +5V system. In addition, these converters are fault protected to ±16.5V; a fault condition on any channel will not affect the conversion result of the selected channel. Other features include a 5MHz bandwidth track/hold, an 8ksps throughput rate, and the option of an internal 4.096V or external reference.

The MAX127/MAX128 feature a 2-wire, I<sup>2</sup>C-compatible serial interface that allows communication among multiple devices using SDA and SCL lines.

A hardware shutdown input (SHDN) and two softwareprogrammable power-down modes (standby and full power-down) are provided for low-current shutdown between conversions. In standby mode, the referencebuffer remains active, eliminating start-up delays.

The MAX127/MAX128 are available in 24-pin DIP or space-saving 28-pin SSOP packages.

Industrial Control Systems Data-Acquisition Systems Robotics Automatic Testing Battery-Powered Instruments Medical Instruments

# **Ordering Information**

**Applications** 

PART	TEMP. RANGE	PIN-PACKAGE	INL (LSB)
MAX127ACNG	$0^{\circ}C$ to $+70^{\circ}C$	24 Narrow Plastic DIP	±1/2
MAX127ACNG	$0^{\circ}C$ to $+70^{\circ}C$	24 Narrow Plastic DIP	±1

Ordering Information continued at end of data sheet.

# M/IXI/M

\_Features

- 12-Bit Resolution, 1/2 LSB Linearity
- +5V Single-Supply Operation
- I<sup>2</sup>C-Compatible, 2-Wire Serial Interface
- Four Software-Selectable Input Ranges MAX127: 0 to +10V, 0 to +5V, ±10V, ±5V MAX128: 0 to +VREF, 0 to +VREF/2, ±VREF, ±VREF/2
- ♦ 8 Analog Input Channels
- Sksps Sampling Rate
- + ±16.5V Overvoltage-Tolerant Input Multiplexer
- Internal 4.096V or External Reference
- Two Power-Down Modes
- ♦ 24-Pin Narrow DIP or 28-Pin SSOP Packages

# **Typical Operating Circuit**



Pin Configurations appear at end of data sheet.

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# **ABSOLUTE MAXIMUM RATINGS**

V <sub>DD</sub> to AGND	Continuous Power Dissipation ( $T_A = +70^{\circ}$ C) 24-Pin Narrow DIP (derate 13.33mW/°C above +70°C)1067mW 28-Pin SSOP (derate 9.52mW/°C above +70°C)
Max Current into Any Pin50mA	Lead Temperature (soldering, 10sec)+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

# **ELECTRICAL CHARACTERISTICS**

 $(V_{DD} = +5V \pm 5\%; unipolar/bipolar range; external reference mode, V_{REF} = 4.096V; 4.7\mu F at REF; external clock, f_{CLK} = 400 kHz; T_A = T_{MIN} to T_{MAX}; unless otherwise noted. Typical values are at T_A = +25°C.)$ 

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS	
ACCURACY (Note 1)	1	1					1	
Resolution				12			Bits	
Integral Nonlinearity	INL	MAX127A	/MAX128A			±1/2	LSB	
Integral Nonlinearity		MAX127B	/MAX128B			±1	LJD	
Differential Nonlinearity	DNL					±1	LSB	
		Unipolar	MAX127A/MAX128A			±3		
Offset Frror		Unipolai	MAX127B/MAX128B			±5	LSB	
Oliset Elloi		Bipolar	MAX127A/MAX128A			±5	LJD	
		ырыа	MAX127B/MAX128B			±10		
Channel-to-Channel Offset		Unipolar			±0.1		LSB	
Error Matching		Bipolar			±0.3		LSD	
Gain Error (Note 2)		Unipolar	MAX127A/MAX128A			±7		
		Unipulai	MAX127B/MAX128B			±10	LSB	
		Bipolar	MAX127A/MAX128A			±7	LJD	
		ырыа	MAX127B/MAX128B			±10		
Gain Tempco (Note 2)		Unipolar			3		ppm/°C	
		Bipolar			5			
DYNAMIC SPECIFICATIONS (80	0Hz sine-wa	ive input, ±1	0Vp-p (MAX127) or ±4.096Vp-	p (MAX128), f <sub>SA</sub>	MPLE = 8	ksps)		
Signal-to-Noise plus Distortion Ratio	SINAD			70			dB	
Total Harmonic Distortion	THD	Up to the	5th harmonic		-87	-80	dB	
Spurious-Free Dynamic Range	SFDR			81			dB	
Channel-to-Channel Crosstalk		4kHz, Vin	= ±5V (Note 3)		-86			
Channel-to-Channel Crosstalk		DC, VIN =	±16.5V		-96		dB	
Aperture Delay					200		ns	
Aperture Jitter					10		ns	

# **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{DD} = +5V \pm 5\%)$ ; unipolar/bipolar range; external reference mode,  $V_{REF} = 4.096V$ ;  $4.7\mu F$  at REF pin; external clock,  $f_{CLK} = 400 kHz$ ;  $T_A = T_{MIN}$  to  $T_{MAX}$ ; unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS		
ANALOG INPUT					I				
Track/Hold Acquisition Time							3	μs	
			±10V or ±	VREF range		5			
Small-Signal Bandwidth		-3dB	±5V or ±V <sub>REF</sub> /2 range			2.5			
		rolloff	0 to 10V c	or 0 to V <sub>REF</sub> range		2.5		MHz	
			0 to 5V or	0 to V <sub>REF</sub> /2 range		1.25			
					0		10		
Input Voltage Range		Unipolar,	MAX127		0		5	1	
		Table 3	MAX100		0		VREF		
			MAX128		0		V <sub>REF</sub> /2		
	VIN				-10		10	V	
		Bipolar,	MAX127		-5		5		
		Table 3	1441/100		-V <sub>REF</sub>		VREF		
			MAX128	-V <sub>REF</sub> /2		V <sub>REF</sub> /2	1		
			Unipolar MAX127	0 to 10V range	-10		720		
Input Current		Unipolar		0 to 5V range	-10		360		
			MAX128		-10	0.1	10		
	lin B	Bipolar	MAX(107	±10V range	-1200		720	μΑ 	
			MAX127	±5V range	-600		360		
			1441/100	±V <sub>REF</sub> range	-1200		10		
			MAX128	±V <sub>REF</sub> /2 range	-600		10		
	$\Delta V_{IN}$	Unipolar				21			
Input Resistance	$\Delta I_{\rm IN}$	Bipolar				16		kΩ	
Input Capacitance		(Note 4)					40	pF	
INTERNAL REFERENCE		1							
REFOUT Voltage	VREF	$T_{A} = +25^{\circ}$	°C		4.076	4.096	4.116	V	
			C/MAX128_	С		±15			
REFOUT Tempco	TC V <sub>REF</sub>		E/MAX128_			±30		ppm/°C	
Output Short-Circuit Current							30	mA	
Load Regulation (Note 5)		0 to 0.5mA output current				10	mV		
Capacitive Bypass at REF					4.7			μF	
REFADJ Output Voltage					2.465	2.500	2.535	V	
REFADJ Adjustment Range		Figure 12				±1.5		%	
Buffer Voltage Gain						1.638		V/V	

# **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{DD} = +5V \pm 5\%)$ ; unipolar/bipolar range; external reference mode,  $V_{REF} = 4.096V$ ;  $4.7\mu$ F at REF pin; external clock,  $f_{CLK} = 400$ kHz; T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>; unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS		
<b>REFERENCE INPUT</b> (buffer disa	bled, refere	nce input ap	oplied to REF)					1	
Input Voltage Range					2.4		4.18	V	
Input Current		V <sub>REF</sub> = 4.18V	Normal, or ST power-down				400	μA	
		4.IOV	FULL power-o	down mode			1		
Input Resistance		Normal or	STANDBY powe	er-down mode	10			kΩ	
		FULL pow	er-down mode		5			MΩ	
REFADJ Threshold for Buffer Disable					V <sub>DD</sub> - 0.5			V	
POWER REQUIREMENTS					÷				
Supply Voltage	V <sub>DD</sub>				4.75		5.25	V	
		Normal m	ode, bipolar ran	ges			18	mA	
Supply Current	IDD	Normal mode, unipolar ranges			6	10			
Supply Current	עטי	STANDBY power-down mode (Note 6)			700	850	μA		
			er-down mode			120	220	20	
Power-Supply Rejection Ratio	PSRR	External re	eference = $4.09$	6V		±0.1	±0.5	LSB	
(Note 7)	FJKK	Internal re	ference			±0.5		LJD	
TIMING									
External Clock Frequency Range	fclk						0.4	MHz	
Conversion Time	tconv				6.0	7.7	10.0	μs	
Throughput Rate							8	ksps	
Bandgap Reference Start-Up Time		Power-up	(Note 8)			200		μs	
		To 0.1mV,	REF bypass	$C_{REF} = 4.7 \mu F$		8			
Reference Buffer Settling Time		capacitor fully discharged $C_{REF} = 33\mu F$			60		ms		
DIGITAL INPUTS (SHDN, A2, A1	, A0)	1							
Input High Threshold Voltage	Vih						2.4	V	
Input Low Threshold Voltage	VIL				0.8			V	
Input Leakage Current	lin	VIN = 0 or	VDD			±0.1	±10	μA	
Input Capacitance	CIN	(Note 4)					15	pF	
Input Hysteresis	V <sub>HYS</sub>					0.2		V	

# **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{DD} = +5V \pm 5\%)$ ; unipolar/bipolar range; external reference mode,  $V_{REF} = 4.096V$ ;  $4.7\mu$ F at REF pin; external clock,  $f_{CLK} = 400$ kHz;  $T_A = T_{MIN}$  to  $T_{MAX}$ ; unless otherwise noted. Typical values are at  $T_A = +25^{\circ}$ C.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DIGITAL INPUTS (SDA, SCL)						
Input High Threshold Voltage	VIH				0.7 x V <sub>DD</sub>	V
Input Low Threshold Voltage	VIL		0.3 x V <sub>DD</sub>			V
Input Hysteresis	Vhys		0.05 x V <sub>DD</sub>			V
Input Leakage Current	I <sub>IN</sub>	$V_{IN} = 0 \text{ or } V_{DD}$		±0.1	±10	μΑ
Input Capacitance	CIN	(Note 4)			15	рF
DIGITAL OUTPUTS (SDA)						
Output Low Voltage	Vol	I <sub>SINK</sub> = 3mA			0.4	V
	VOL	Isink = 6mA			0.6	v
Three-State Output Capacitance	Cout	(Note 4)			15	pF

# TIMING CHARACTERISTICS

 $(V_{DD} = +4.75V \text{ to } +5.25V; \text{ unipolar/bipolar range; external reference mode, } V_{REF} = 4.096V; 4.7\mu\text{F at REF pin}; T_A = T_{MIN} \text{ to } T_{MAX}; \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}\text{C.})$ 

PARAMETERS	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
2-WIRE FAST MODE			-			
SCL Clock Frequency	f <sub>SCL</sub>				400	kHz
Bus Free Time Between a STOP and START Condition	tBUF		1.3			μs
Hold Time (Repeated) START Condition	thd,sta		0.6			μs
Low Period of the SCL Clock	tLOW		1.3			μs
High Period of the SCL Clock	thigh		0.6			μs
Set-Up Time for a Repeated START Condition	tsu,sta		0.6			μs
Data Hold Time	thd,dat		0		0.9	μs
Data Setup Time	t <sub>SU,DAT</sub>		100			ns
Rise Time for Both SDA and SCL Signals (Receiving)	t <sub>R</sub>	C <sub>b</sub> = Total capacitance of one bus line in pF	20 + 0.1 x C <sub>b</sub>		300	ns
Fall Time for Both SDA and SCL Signals (Receiving)	tF	C <sub>b</sub> = Total capacitance of one bus line in pF	20 + 0.1 x C <sub>b</sub>		300	ns
Fall Time for Both SDA and SCL Signals (Transmitting)	tF	C <sub>b</sub> = Total capacitance of one bus line in pF	20 + 0.1 x C <sub>b</sub>		250	ns
Set-Up Time for STOP Condition	tsu,sto		0.6			μs
Capacitive Load for Each Bus Line	Cb				400	pF
Pulse Width of Spike Suppressed	tsp		0		50	ns



# TIMING CHARACTERISTICS (continued)

 $(V_{DD} = +4.75V \text{ to } +5.25V; \text{ unipolar/bipolar range; external reference mode, } V_{REF} = 4.096V; 4.7\mu\text{F at REF pin; } T_A = T_{MIN} \text{ to } T_{MAX}; \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}\text{C.})$ 

PARAMETERS	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
2-WIRE STANDARD MODE			1			1
SCL Clock Frequency	fscl				100	kHz
Bus Free Time Between a STOP and START Condition	<sup>t</sup> BUF		4.7			μs
Hold Time (Repeated) START Condition	thd,sta		4.0			μs
Low Period of the SCL Clock	tLOW		4.7			μs
High Period of the SCL Clock	thigh		4.0			μs
Setup Time for a Repeated START Condition	t <sub>SU, STA</sub>		4.7			μs
Data Hold Time	thd, dat		0		0.9	μs
Data Setup Time	tsu, dat		250			ns
Rise Time for Both SDA and SCL Signals (Receiving)	t <sub>R</sub>				1000	ns
Fall Time for Both SDA and SCL Signals (Receiving)	tF				300	ns
Fall Time for Both SDA and SCL Signals (Transmitting)	t <sub>F</sub>	$C_b$ = total capacitance of one bus line in pF, up to 6mA sink	20 + 0.1 x C <sub>b</sub>		250	ns
Setup Time for STOP Condition	tsu, sto		4.0			μs
Capacitive Load for Each Bus Line	Cb				400	pF
Pulse Width of Spike Suppressed	tsp		0		50	ns

**Note 1:** Accuracy specifications tested at  $V_{DD} = 5.0V$ . Performance at power-supply tolerance limits is guaranteed by Power-Supply Rejection test.

Note 2: External reference: V<sub>REF</sub> = 4.096V, offset error nulled, ideal last-code transition = FS - 3/2LSB.

Note 3: Ground "on" channel, sine wave applied to all "off" channels.

Note 4: Guaranteed by design. Not tested.

Note 5: Use static external load during conversion for specified accuracy.

Note 6: Tested using internal reference.

Note 7: PSRR measured at full scale. Tested for the ±10V (MAX127) and ±4.096V (MAX128) input ranges.

**Note 8:** Not subject to production testing. Provided for design guidance only.

# \_Typical Operating Characteristics

 $(V_{DD} = +5V)$ , external reference mode,  $V_{REF} = 4.096V$ ;  $4.7\mu$ F at REF; external clock,  $f_{CLK} = 400$ kHz;  $T_A = +25^{\circ}$ C; unless otherwise noted.)

SUPPLY CURRENT vs. TEMPERATURE

# STANDBY SUPPLY CURRENT vs. temperature

**MAX127/MAX128** 



SUPPLY CURRENT vs. SUPPLY VOLTAGE

# Pin Description

PII	N	NAME	FUNCTION
DIP	SSOP	NAME	FUNCTION
1, 2	1, 2	V <sub>DD</sub>	+5V Supply. Bypass with a 0.1µF capacitor to AGND.
3, 9, 22, 24	4, 7, 8, 11, 22, 24, 25, 28	N.C.	No Connect. No internal connection.
4	3	DGND	Digital Ground
5	5	SCL	Serial Clock Input
6, 8, 10	6, 10, 12	A0, A2, A1	Address Select Inputs
7	9	SDA	Open-Drain Serial Data I/O. Input data is clocked in on the rising edge of SCL, and output data is clocked out on the falling edge of SCL. External pull-up resistor required.
11	13	SHDN	Shutdown Input. When low, device is in full power-down (FULLPD) mode. Connect high for normal operation.
12	14	AGND	Analog Ground
13–20	15–21, 23	CH0-CH7	Analog Input Channels
21	26	REFADJ	Bandgap Voltage-Reference Output/External Adjust Pin. Bypass with a $0.01 \mu F$ capacitor to AGND. Connect to $V_{DD}$ when using an external reference at REF.
23	27	REF	Reference Buffer Output/ADC Reference Input. In internal reference mode, the reference buffer provides a 4.096V nominal output, externally adjustable at REFADJ. In external reference mode, disable the internal reference by pulling REFADJ to $V_{DD}$ and applying the external reference to REF.



Figure 1. Block Diagram

# **Detailed Description**

# **Converter Operation**

The MAX127/MAX128 multirange, fault-tolerant ADCs use successive approximation and internal track/hold (T/H) circuitry to convert an analog signal to a 12-bit digital output. Figure 1 shows the block diagram for these devices.

# Analog-Input Track/Hold

The T/H circuitry enters its tracking/acquisition mode on the falling edge of the sixth clock in the 8-bit input control word and enters its hold/conversion mode when the master issues a STOP condition. For timing information, see the *Start a Conversion* section.

## Input Range and Protection

The MAX127/MAX128 have software-selectable input ranges. Each analog input channel can be independently programmed to one of four ranges by setting the appropriate control bits (RNG, BIP) in the control byte (Table 1). The MAX127 has selectable input ranges extending to  $\pm 10V (\pm V_{REF} \times 2.441)$ , while the MAX128 has selectable input ranges extending to  $\pm 10V (\pm V_{REF} \times 2.441)$ , while the MAX128 has selectable input ranges extending to  $\pm V_{REF}$ . Note that when an external reference is applied at REFADJ, the voltage at REF is given by  $V_{REF} = 1.638 \times V_{REF}ADJ$  (2.4 <  $V_{REF} < 4.18$ ). Figure 2 shows the equivalent input circuit.

A resistor network on each analog input provides a  $\pm 16.5$ V fault protection for all channels. This circuit limits the current going into or out of the pin to less than 1.2mA, whether or not the channel is on. This provides an added layer of protection when momentary overvoltages occur at the selected input channel, and when a negative signal is applied at the input even though





Figure 2. Equivalent Input Circuit

the device may be configured for unipolar mode. Overvoltage protection is active even if the device is in power-down mode or  $V_{DD} = 0$ .

## **Digital Interface**

The MAX127/MAX128 feature a 2-wire serial interface consisting of the SDA and SCL pins. SDA is the data I/O and SCL is the serial clock input, controlled by the master device. A2–A0 are used to program the MAX127/MAX128 to different slave addresses. (The MAX127/MAX128 only work as slaves.) The two bus lines (SDA and SCL) must be high when the bus is not in use. External pull-up resistors (1k $\Omega$ or greater) are required on SDA and SCL to maintain I<sup>2</sup>C compatibility. Table 1 shows the input control-byte format.

MAX127/MAX128

# Table 1. Control-Byte Format

BIT 7 (MSB)	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0 (LSB)		
START	SEL2	SEL1	SEL0	RNG	BIP	PD1	PD0		
BIT	NAME		DESCRIPTION						
7 (MSB)	START	U U	The logic "1" received after acknowledge of a write bit ( $R/\overline{W} = 0$ ) defines the beginning of the control byte.						
6, 5, 4	SEL2, SEL1, SEL0	These three t	These three bits select the desired "ON" channel (Table 2).						
3	RNG	Selects the fu	Selects the full-scale input voltage range (Table 3).						
2	BIP	Selects unipo	Selects unipolar or bipolar conversion mode (Table 3).						
1, 0 (LSB)	PD1, PD0	These two bit	These two bits select the power-down modes (Table 4).						

# **Table 2. Channel Selection**

SEL2	SEL1	SEL0	CHANNEL
0	0	0	CH0
0	0	1	CH1
0	1	0	CH2
0	1	1	CH3
1	0	0	CH4
1	0	1	CH5
1	1	0	CH6
1	1	1	CH7

# Table 4. Power-Down and ClockSelection

PD1	PD0 MODE				
0	Х	Normal Operation (always on)			
1	0	Standby Power-Down Mode (STBYPD)			
1	1	Full Power-Down Mode (FULLPD)			

# Table 3. Range and Polarity Selection

INPUT RANGE (V)	RNG	BIP	NEGATIVE FULL SCALE (V)	ZERO SCALE (V)	FULL SCALE (V)
MAX127					
0 to 5	0	0	_	0	V <sub>REF</sub> x 1.2207
0 to 10	1	0	_	0	VREF x 2.4414
±5	0	1	-V <sub>REF</sub> x 1.2207	0	V <sub>REF</sub> x 1.2207
±10	1	1	-VREF x 2.4414	0	V <sub>REF</sub> x 2.4414
MAX128					
0 to V <sub>REF</sub> /2	0	0	_	0	V <sub>REF</sub> /2
0 to V <sub>REF</sub>	1	0	-	0	V <sub>REF</sub>
±V <sub>REF</sub> /2	0	1	-V <sub>REF</sub> /2	0	V <sub>REF</sub> /2
±V <sub>REF</sub>	1	1	-V <sub>REF</sub>	0	V <sub>REF</sub>



# MAX127/MAX128

# Multirange, +5V, 12-Bit DAS with 2-Wire Serial Interface

### **Conversion Control**

The master signals the beginning of a transmission with a START condition (S), which is a high-to-low transition on SDA while SCL is high. When the master has finished communicating with the slave, the master issues a STOP condition (P), which is a low-to-high transition on SDA while SCL is high (Figure 4). The bus is then free for another transmission. Figure 5 shows the timing diagram for signals on the 2-wire interface. The address-byte, control-byte, and data-byte are transmitted between the START and STOP conditions. The SDA state is allowed to change only while SCL is low, except for the START and STOP conditions. Data is transmitted in 8-bit words. Nine clock cycles are required to transfer the data in or out of the MAX127/MAX128. (Figures 9 and 10).



The MAX127/MAX128 have a 7-bit-long slave address.

The first four bits (MSBs) of the slave address have

been factory programmed and are always 0101. The

logic state of the address input pins (A2-A0) determine

the three LSBs of the device address (Figure 3). A max-

imum of eight MAX127/MAX128 devices can therefore

A2-A0 may be connected to V<sub>DD</sub> or DGND, or they

The eighth bit of the address byte determines whether

the master is writing to or reading from the MAX127/

MAX128 (R/ $\overline{W}$  = 0 selects a write condition. R/ $\overline{W}$  = 1

may be actively driven by TTL or CMOS logic levels.

be connected on the same bus at one time.

selects a read condition).

Figure 3. Address Byte

**Slave Address** 



Figure 4. START and STOP Conditions



Figure 5. 2-Wire Serial-Interface Timing Diagram



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## Start a Conversion (Write Cycle)

A conversion cycle begins with the master issuing a START condition followed by seven address bits (Figure 3) and a write bit (R/W = 0). Once the eighth bit has been received and the address matches, the MAX127/MAX128 (the slave) issues an acknowledge by pulling SDA low for one clock cycle (A = 0). The master then writes the input control byte to the slave (Figure 8). After this byte of data, the slave issues another acknowledge, pulling SDA low for one clock cycle. The master ends the write cycle by issuing a STOP condition (Figure 6).

When the write bit is set (R/W = 0), acquisition starts as soon as Bit 2 (BIP) of the input control-byte has been latched and ends when a STOP condition has been issued. Conversion starts immediately after acquisition. The MAX127/MAX128's internal conversion clock frequency is 1.56MHz, resulting in a typical conversion time of 7.7µs. Figure 9 shows a complete write cycle.

## Read a Conversion (Read Cycle)

Once a conversion starts, the master does not need to wait for the conversion to end before attempting to read the data from the slave. Data access begins with the master issuing a START condition followed by a 7-bit address (Figure 3) and a read bit ( $R/\overline{W} = 1$ ). Once the eighth bit has been received and the address matches, the slave issues an acknowledge by pulling low on SDA for one clock cycle (A = 0) followed by the first byte of serial data (D11-D4, MSB first). After the first byte has been issued by the slave, it releases the bus for the master to issue an acknowledge (A = 0). After receiving the acknowledge, the slave issues the second byte (D3-D0 and four zeros) followed by a NOT acknowledge ( $\overline{A}$  = 1) from the master to indicate that the last data byte has been received. Finally, the master issues a STOP condition (P), ending the read cycle (Figure 7).







Figure 7. Read Cycle







Figure 9. Complete 2-Wire Serial Write Transmission



Figure 10. Complete 2-Wire Serial Read Transmission

The MAX127/MAX128 ignore acknowledge and NOTacknowledge conditions issued by the master during the read cycle. The device waits for the master to read the output data or waits until a STOP condition is issued. Figure 10 shows a complete read cycle.

In unipolar input mode, the output is straight binary. For bipolar input mode, the output is two's complement. For output binary codes see the *Transfer Function* section.

# Applications Information

## **Power-On Reset**

The MAX127/MAX128 power up in normal operating mode, waiting for a START condition followed by the appropriate slave address. The contents of the input and output data registers are cleared at power-up.

## Internal or External Reference

The MAX127/MAX128 operate with either an internal or an external reference (Figures 11a–11c). An external reference is connected to either REF or to REFADJ.

The REFADJ internal buffer gain is trimmed to 1.6384 to provide 4.096V at REF from a 2.5V reference.

### Internal Reference

The internally trimmed 2.50V reference is amplified through the REFADJ buffer to provide 4.096V at REF. Bypass REF with a 4.7 $\mu$ F capacitor to AGND and bypass REFADJ with a 0.01 $\mu$ F capacitor to AGND (Figure 11a). The internal reference voltage is adjustable to ±1.5% (±65 LSBs) with the reference-adjust circuit of Figure 12.

### External Reference

To use the REF input directly, disable the internal buffer by connecting REFADJ to V<sub>DD</sub> (Figure 11b). Using the REFADJ input eliminates the need to buffer the reference externally. When the reference is applied at REFADJ, bypass REFADJ with a  $0.01\mu$ F capacitor to AGND (Figure 11c).

At REF and REFADJ, the input impedance is a minimum of 10k $\Omega$  for DC currents. During conversions, an external reference at REF must be able to drive a 400  $\mu$ A DC load, and must have an output impedance of 10 $\Omega$  or less. If the reference has higher input impedance or is noisy, bypass REF with a 4.7  $\mu$ F capacitor to AGND as close to the chip as possible.

With an external reference voltage of less than 4.096V at REF or less than 2.5V at REFADJ, the increase in RMS noise to the LSB value (full-scale voltage/4096) results in performance degradation and loss of effective bits.

### Power-Down Mode

To save power, put the converter into low-current shutdown mode between conversions. Two programmable power-down modes are available, in addition to the hardware shutdown. Select STBYPD or FULLPD by programming PD0 and PD1 in the input control byte (Table 4). When software power-down is asserted, it becomes effective only after the end of conversion. In all powerdown modes, the interface remains active and conversion results may be read. Input overvoltage protection is active in all power-down modes.





Figure 11a. Internal Reference



Figure 11b. External Reference, Reference at REF



Figure 11c. External Reference, Reference at REFADJ



Figure 12. Reference-Adjust Circuit

To power-up from a software initiated power-down, a START condition followed by the correct slave address must be received (with R/W = 0). The MAX127/MAX128 power-up after receiving the next bit.

For hardware-controlled power-down (FULLPD), pull SHDN low. When hardware shutdown is asserted, it becomes effective immediately and any conversion in progress is aborted.

# **Choosing Power-Down Modes**

The bandgap reference and reference buffer remain active in STBYPD mode, maintaining the voltage on the  $4.7\mu$ F capacitor at REF. This is a "DC" state that does not degrade after standby power-down of any duration.

In FULLPD mode, only the bandgap reference is active. Connect a 33µF capacitor between REF and AGND to maintain the reference voltage between conversions and to reduce transients when the buffer is enabled and disabled. Throughput rates down to 1ksps can be achieved without allotting extra acquisition time for reference recovery prior to conversion. This allows conversion to begin immediately after power-down ends. If the discharge of the REF capacitor during FULLPD exceeds the desired limits for accuracy (less than a fraction of an LSB), run a STBYPD power-down cycle prior to starting conversions. Take into account that the reference buffer recharges the bypass capacitor at an 80mV/ms slew rate, and add 50µs for settling time.

# Auto-Shutdown

///XI//

Selecting STBYPD on every conversion automatically shuts the MAX127/MAX128 down after each conversion without requiring any start-up time on the next conversion.

# MAX127/MAX128

# Multirange, +5V, 12-Bit DAS with 2-Wire Serial Interface

# **Transfer Function**

Output data coding for the MAX127/MAX128 is binary in unipolar mode with 1LSB = (FS/4096) and two's complement binary in bipolar mode with 1LSB = $[(2 \times |FS|)/4096]$ . Code transitions occur halfway between successive-integer LSB values. Figures 13a and 13b show the input/output (I/O) transfer functions for unipolar and bipolar operations, respectively. For full-scale (FS) values, refer to Table 3.



Figure 13a. Unipolar Transfer Function



Figure 13b. Bipolar Transfer Function

## Layout, Grounding, and Bypassing

Careful printed circuit board layout is essential for best system performance. For best performance, use a ground plane. To reduce crosstalk and noise injection, keep analog and digital signals separate. Connect analog grounds and DGND in a star configuration to AGND. For noise-free operation, ensure the ground return from AGND to the supply ground is low impedance and as short as possible. Connect the logic grounds directly to the supply ground. Bypass V<sub>DD</sub> with 0.1µF and 4.7µF capacitors to AGND to minimize high-and low-frequency fluctuations. If the supply is excessively noisy, connect a 5 $\Omega$  resistor between the supply and V<sub>DD</sub>, as shown in Figure 14.



Figure 14. Power-Supply Grounding Connection

# MAX127/MAX128

# Ordering Information (continued)

PART	TEMP. RANGE	PIN-PACKAGE	INL (LSB)
MAX127ACAI	$0^{\circ}C$ to $+70^{\circ}C$	28 SSOP	±1/2
MAX127BCAI	$0^{\circ}C$ to $+70^{\circ}C$	28 SSOP	±1
MAX127AENG	-40°C to +85°C	24 Narrow Plastic DIP	±1/2
MAX127BENG	-40°C to +85°C	24 Narrow Plastic DIP	±1
MAX127AEAI	-40°C to +85°C	28 SSOP	±1/2
MAX127BEAI	-40°C to +85°C	28 SSOP	±1
MAX128ACNG	$0^{\circ}C$ to $+70^{\circ}C$	24 Narrow Plastic DIP	±1/2
MAX128BCNG	$0^{\circ}C$ to $+70^{\circ}C$	24 Narrow Plastic DIP	±1
MAX128ACAI	$0^{\circ}C$ to $+70^{\circ}C$	28 SSOP	±1/2
MAX128BCAI	$0^{\circ}C$ to $+70^{\circ}C$	28 SSOP	±1
MAX128AENG	-40°C to +85°C	24 Narrow Plastic DIP	±1/2
MAX128BENG	-40°C to +85°C	24 Narrow Plastic DIP	±1
MAX128AEAI	-40°C to +85°C	28 SSOP	±1/2
MAX128BEAI	-40°C to +85°C	28 SSOP	±1

Chip Information

TRANSISTOR COUNT: 4219 SUBSTRATE CONNECTED to AGND

# **Pin Configurations**



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