

# MIC2551A-2.5

**USB Transceiver** 

## **General Description**

The MIC2551A is a single chip transceiver that complies with the physical layer specifications of the Universal Serial Bus (USB) 2.0. It supports both full speed (12Mbps) and low speed (1.5Mbps) operation and introduces superior edge rate control, producing crisper eye diagrams. This in turn, eases the task of passing USB compliance testing.

A unique, patented, dual supply voltage operation allows the MIC2551A to reference the system I/F I/O signals to a supply voltage down to 1.6V while independently powered by the USB V<sub>BUS</sub>. This reduces system operating current and allows the system to operate at its core voltage without additional buffering logic.

MIC2551A-2.5 is differentiated from MIC2551A by a smaller space saving MLF<sup>®</sup> package (2.5mm × 2.5mm) and  $\pm$ 15kV ESD protection which eliminates the need for separate ESD protection devices on the D+, D- data lines.

Data sheets and support documentation can be found on Micrel's web site at www.micrel.com.

## Features

- ±15kV ESD protection on V<sub>BUS</sub>, D+ and D-
- Smaller 2.5mm × 2.5mm MLF<sup>®</sup> package
- USB 1.1 and 2.0 compliant transceiver (full speed 12Mbs and low speed 1.5Mbps) operation
- Separate I/O supply with operation down to 1.6V
- · Integrated speed select termination supply
- Very-low power consumption to meet USB suspend current requirements
- · No power supply sequencing requirements
- Software controlled enumeration

#### **Applications**

- PDAs
- Palmtops
- Cell phones
- · PC peripherals

## **Ordering Information**

Part Number	Junction Temp. Range	Package - Pb Free
MIC2551AYML25	-40°C to +85°C	2.5mm× $2.5$ mm MLF <sup>®</sup>

## **Typical Application**



**Typical Application Circuit** 

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## **Pin Configuration**



## **Pin Description**

Pin Number	Pin Name	I/O	Pin Description		
1	RCV	0	Receive Data: Output for USB differential data.		
2	VP	I/O	If OE# = 1, VP = Receive output (+) If OE# = 0, VP = Driver input (+).		
3	VM	I/O	If OE# = 1, VM = Receive output (-) If OE# = 0, VM = Driver input (-).		
4	CON	I	CONNECT (Input): Controls state of VPU. Refer to VPU pin description for detail.		
5	GND		Ground Reference.		
6	SUS	I	Suspend: Active-High. Turns off internal circuits to reduce supply current.		
7	OE#	I	Output Enable: Active-Low. Enables the transceiver to transmit data onto the bus. When inactive, the trasceiver is in the receive mode.		
8	D-	1/0	Differential data lines conforming to the LISP standard		
9	D+		Differential data lines conforming to the USB standard.		
10	VTRM	0	3.3V Reference Supply Output: Requires a minimum 0.1µF decou capacitor for stability. A 1µF capacitor is recommended.		
11	VPU	0	Pull-up Supply Voltage Output: Used to connect $1.5k\Omega$ pull-up speed detect resistor. If CON = 1, VPU is high impedance. If CON = 0, VPU = 3.3V.		
12	VBUS	I	USB Bus Supply Voltage: Used to power USB transceiver and internal circuitry.		
13	VIF	I	System Interface Supply Voltage: Used to provide reference supply voltage for system I/O interface signaling.		
14	SPD	I	Edge Rate Control: A logic HIGH operates at edge rates for "full speed" operation. A logic LOW operates edge rates for "low-speed" operation.		

SUS	OE#	D+, D–	RCV	VP/VM	Function
0	0	Driving	Active	Active	Normal transmit mode.
0	1	Receiving	Active	Active	Normal receive mode.
1	0	Hi-Z	0	Not Active	Low power state.
1	1	Hi-Z	0 Active Receiving during sus state) (Note 1)		Receiving during suspend (low power state) (Note 1)

Note 1. During suspend, VP and VM are active in order to detect out-of-band signaling conditions.

Table 1.	Function	Selection
		0010001011

OE# = 0:							
Inj	Input		Output				
VP	VM	D+	D-	RCV	Result		
0	0	0	0 0 X		SE0		
0	1	0	1	0	Logic 0		
1	0	1	0	1	Logic 1		
1	1	1 1 X		Undefined			
OE# = 1:							
Inj	out	Output			Beeult		
D+	D–	VP	VM	RCV	Result		
0	0	0	0	Х	SE0		
0	1	0	1	0	Logic 0		
1	0	1	0	1	Logic 1		
1	1	1	1	Х	Undefined		

X - Undefined

Table 2. Truth Table During Normal Mode

	(
Supply Voltage (V <sub>BUS</sub> )	6.5V
All Other Inputs	–0.5V to 5.5V
Ambient Storage Temperature	–65°C to +150°C
Output Current (D+, D–)	± 50mA
Output Current (all others)	±15mA
Input Current	±50mA
ESD, Note 3	
V <sub>BUS</sub> , D+, D– All other pins	±15KV
All other pins	±2KV

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Operating Ratings (Note 2)	-
Supply Voltage (V <sub>BUS</sub> )4.0V to 5.25V	/
Ambient Operating Temperature40°C to +85°C	;
Package Thermal Resistance	

## DC Electrical Characteristics (System and USB Interface) (Note 6)

 $V_{IF}$  = 3.6V,  $V_{BUS}$  = 5V unless otherwise noted;  $T_A$  = 25°C. **Bold** indicates specifications over temperature, -40°C to 85°C.

Symbol	Parameter			Conditions			Min	Тур	Max	Units
V <sub>BUS</sub>	USB Supply Voltage						4.0		5.25	V
V <sub>IF</sub>	System I/F Supply Volt	age							3.6	V
V <sub>IL</sub>	LOW-Level Input Voltag	W-Level Input Voltage, Note 4					V <sub>IF</sub> -0.3		0.15V <sub>IF</sub>	V
V <sub>IH</sub>	HIGH-Level Input Voltage, Note 4						0.85V <sub>IF</sub>		V <sub>IF</sub> +0.3	V
V <sub>OH</sub>	HIGH-Level Output Voltage, Note 4			I <sub>OH</sub> = 2	20µA		0.9V <sub>IF</sub>			V
V <sub>OL</sub>	LOW-Level Output Voltage, Note 4			I <sub>OL</sub> = 2	ΰμΑ				0.1	V
I <sub>IL</sub>	Input Leakage Current, Note 4						-5		5	μA
Symbol	Parameter				Conditions		Min	Тур	Max	Units
		SPD	SUS	OE#	Voltage	Load				
I <sub>IF</sub> VIF Supply Current	1	0	1							
	1	0	0	]						
		0	0	1				1	5	μA
		0	0	0						
	0	1	0	VBUS = 5.25V						
	1	0	0	VIF = 3.6V	f = 6MHz CLOAD = 50pF, <b>Note 6</b>		325	650	μA	
		0	0	0		f = 750MHz CLOAD = 600pF, <b>Note 6</b>		40	75	μA
		1	0	1	1			800	1100	μA
		1	0	0				3000	5000	μA
		0	0	1				230	350	μA
		0	0	0				400	700	μA
VBUS	VBUS Supply Current	0	1	0	VBUS = 5.25V			130	200	μA
	1	0	0	VIF = 3.6V	f = 6MHz CLOAD = 50pF, <b>Note 6</b>		7.3	10	mA	
		0	0	0		f = 750MHz CLOAD = 600pF, <b>Note 6</b>		3.6	5	mA
Symbol	Parameter			Conditions		Min	Тур	Max	Units	
VPULEAK	VPU Leakage Current			CON =	1, V <sub>PU</sub> = 0V		-5		5	μA
VIFLEAK	VIF Leakage Current			V <sub>IF</sub> = 3.6V, V <sub>BUS</sub> = 0V		-5		5	μA	
V <sub>PU</sub>	Pull-Up Output Voltage			I <sub>TERM</sub> = 200μA, V <sub>BUS</sub> = 4.0 to 5.25V		3.0	3.3	3.6	V	
R <sub>SW</sub>	Internal Pull-Up Termin			= 10mA, V <sub>BUS</sub> = 4			10		Ω	

Symbol	Parameter	Conditions	Min	Тур	Мах	Units
ESD Protect	ion	•	•			
IEC-1000-4-2	5	10 pulses		±15		kV
(D+, D-, V <sub>BUS</sub> only)	Contact Discharge	10 pulses		±15		kV
-	ical Characteristics (Trar	Sceiver) (Note 6)				
Leakage Cui	•					
I <sub>LO</sub>	Hi-Z State Data Line Leakage (Suspend Mode)	0V < V <sub>IN</sub> < 3.3V, SUS = 1	-10		10	μA
Input Levels	÷		·			
V <sub>DI</sub>	Differential Input Sensitivity	(D+) - (D-)	0.2			V
V <sub>CM</sub>	Differential Common Mode Range	Includes V <sub>DI</sub> range	0.8		2.5	V
V <sub>SE</sub>	Single-Ended Receiver Threshold		0.8		2.0	V
	Receiver Hysteresis			200		mV
Output Leve	ls					
V <sub>OL</sub>	Static Output Low	$R_L = 1.5k\Omega$ to 3.6V			0.3	V
V <sub>OH</sub>	Static Output High	$R_L = 1.5k\Omega$ to GND	2.8		3.6	V
Capacitance						
C <sub>IN</sub>	Transceiver Capacitance	Pin to GND		10		pF
Z <sub>RDV</sub>	Driver Output Resistance	Steady-state drive	8	16	24	Ω
AC Elect	rical Characteristics (Note	s 5)				
Driver Chara	cteristics (Low Speed)					
T <sub>R</sub>	Transition Rise Time	$C_L = 50$ pF, Figure 2 $C_L = 600$ pF	75		300	ns
T <sub>F</sub>	Transition Fall Time	$C_L = 50$ pF, Figure 2 $C_L = 600$ pF	75		300	ns
T <sub>R</sub> , T <sub>F</sub>	Rise/Fall Time Matching	(T <sub>R</sub> , T <sub>F</sub> )	80		125	%
V <sub>CRS</sub>	Output Signal Crossover Voltage		1.3		2.0	V
CRS	stariation (Full Crossel)					
	cteristics (Full Speed)					
Driver Chara	Transition Rise Time	C <sub>L</sub> = 50pF, Figure 2	4		20	ns
<b>Driver Chara</b> T <sub>R</sub>	1	$C_L$ = 50pF, Figure 2 $C_L$ = 50pF, Figure 2	4		20 20	ns ns
<b>Driver Chara</b> T <sub>R</sub> T <sub>F</sub>	Transition Rise Time					
Driver Chara T <sub>R</sub> T <sub>F</sub> T <sub>R</sub> , T <sub>F</sub>	Transition Rise Time Transition Fall Time	C <sub>L</sub> = 50pF, Figure 2	4		20	ns
Driver Chara T <sub>R</sub> T <sub>F</sub> T <sub>R</sub> , T <sub>F</sub> V <sub>CRS</sub>	Transition Rise TimeTransition Fall TimeRise/Fall Time MatchingOutput Signal Crossover Voltage	C <sub>L</sub> = 50pF, Figure 2	4 90		20 111.11	ns %
Driver Chara T <sub>R</sub> T <sub>F</sub> T <sub>R</sub> , T <sub>F</sub> V <sub>CRS</sub> Transceiver	Transition Rise TimeTransition Fall TimeRise/Fall Time MatchingOutput Signal Crossover Voltage	C <sub>L</sub> = 50pF, Figure 2	4 90		20 111.11	ns %
Driver Chara T <sub>R</sub> T <sub>F</sub> T <sub>R</sub> , T <sub>F</sub> V <sub>CRS</sub> Transceiver	Transition Rise Time     Transition Fall Time     Rise/Fall Time Matching     Output Signal Crossover Voltage     Timing	$C_L = 50$ pF, Figure 2 ( $T_R, T_F$ )	4 90		20 111.11 2.0	ns % V
Driver Chara T <sub>R</sub> T <sub>F</sub> T <sub>R</sub> , T <sub>F</sub> V <sub>CRS</sub> Transceiver	Transition Rise Time     Transition Fall Time     Rise/Fall Time Matching     Output Signal Crossover Voltage     Timing     OE# to RCVR Tri-State Delay     Receiver Tri-State to Transmit	$C_L = 50$ pF, Figure 2 ( $T_R$ , $T_F$ ) Figure 1	4 90 1.3		20 111.11 2.0	ns % V ns
Driver Chara T <sub>R</sub> T <sub>F</sub> T <sub>R</sub> , T <sub>F</sub> V <sub>CRS</sub> Transceiver t <sub>PVZ</sub> t <sub>PZD</sub>	Transition Rise Time     Transition Fall Time     Rise/Fall Time Matching     Output Signal Crossover Voltage     Timing     OE# to RCVR Tri-State Delay     Receiver Tri-State to Transmit     Delay	C <sub>L</sub> = 50pF, Figure 2 (T <sub>R</sub> , T <sub>F</sub> ) Figure 1 Figure 1	4 90 1.3		20 111.11 2.0 15	ns % V ns ns
Driver Chara T <sub>R</sub> T <sub>F</sub> T <sub>R</sub> , T <sub>F</sub> V <sub>CRS</sub> V <sub>CRS</sub> Transceiver t <sub>PVZ</sub> t <sub>PZD</sub>	Transition Rise Time     Transition Fall Time     Rise/Fall Time Matching     Output Signal Crossover Voltage     Timing     OE# to RCVR Tri-State Delay     Receiver Tri-State to Transmit     Delay     OE# to DRVR Tri-State Delay	C <sub>L</sub> = 50pF, Figure 2 (T <sub>R</sub> , T <sub>F</sub> ) Figure 1 Figure 1 Figure 1	4 90 1.3 15		20 111.11 2.0 15	ns % V ns ns
	Transition Rise Time     Transition Fall Time     Rise/Fall Time Matching     Output Signal Crossover Voltage     Timing     OE# to RCVR Tri-State Delay     Receiver Tri-State to Transmit Delay     OE# to DRVR Tri-State Delay     Driver Tri-State to Receiver Delay     VP, VM to D+, D- Propagation	C <sub>L</sub> = 50pF, Figure 2 (T <sub>R</sub> , T <sub>F</sub> ) Figure 1 Figure 1 Figure 1 Figure 1	4 90 1.3 15		20 111.11 2.0 15 15 15	ns % V ns ns ns

Note 3. Devices are ESD sensitive. Handling precautions recommended. Human body model, 1.5k in series with 100pF.

Note 4. Specification applies to the following pins: SUS, SPD, CON, RCV, VP, VM, OE#.

Note 5. All AC parameters guaranteed by design but not production tested.

Note 6. Specification for packaged product only.

### **Timing Diagrams**







Figure 2. Rise and Fall Times



Figure 3. Receiver Propagation Delay



Figure 4. Driver Propagation Delay

## **Test Circuits**



Figure 5. Load for  $V_{P}$ ,  $V_{M}$ , RCV



Figure 6. Load for D+, D-

## **Functional Diagram**



## **Applications Information**

The MIC2551A is designed to provide USB connectivity in mobile systems where available system supply voltages are not able to satisfy USB requirements. The MIC2551A can operate interface supply voltages as low as 1.6V and still meet the USB physical layer specifications. As shown in the circuit above, the MIC2551A takes advantage of the USB supply voltage,  $V_{BUS}$ , to operate the transceiver. The system voltage,  $V_{IF}$ , is used to set the reference voltage used by the digital I/O lines interfacing to the system controller. Internal circuitry provides translation between the USB and system voltage domains.  $V_{IF}$  will typically be the main supply voltage rail for the controller.

In addition, a 3.3V, 10% termination supply voltage, (V<sub>PU</sub>), is provided to support speed selection. V<sub>PU</sub> can be disabled or enabled under software control via the CON input. This allows for software-controlled connect or disconnect states. A 1.5k resistor is required to be connected between this pin and the D+ or D– lines to respectively specify high speed or low speed operation.

#### **Power Supply Configuration**

The MIC2551A can be set up for different power supply configurations which modify the behavior of the device. Both  $V_{BUS}$  and  $V_{IF}$  have special thresholds that detect when they are either removed or grounded. Table 1 depicts the behavior under the different power supply configuration scenarios that are explained below.

#### Normal Mode

 $V_{BUS}$  is connected to the 5.0V USB bus voltage and  $V_{IF}$  is connected to a supply voltage in the range of 1.6V to 3.6V. In this case  $V_{TRM}$  supplies a 3.3V voltage for powering the speed select resistor via  $V_{PU}$  depending on the state of CON pin.

#### Disconnect Mode

 $V_{IF}$  is connected to a supply in a range of 1.6V to 3.6V and  $V_{BUS}$  is open or grounded. If  $V_{BUS}$  is opened while transmitting, the data lines (D+, D–) have sharing capability and may be driven with external devices up to approximately 3.6V if and only if SUSPEND is enabled (SUS = 1). With  $V_{BUS}$  ground, D+, D– sharing mode is not permitted.

#### Disable Mode

 $\rm V_{BUS}$  is connected to the 5.0V USB bus voltage and  $\rm V_{IF}$  is open. All logic controlled inputs become high impedances, thus minimal current will be supplied by  $\rm V_{IF}$  if the input pins are pulled up to an external source.

## Alternate Power Supply Configuration Option

#### I/O Interface Using 3.3V

In systems where the I/O interface utilizes a 3.3V USB controller, an alternate solution is shown in Figure 7. No extra components are required; however, the load on  $V_{TRM}$  must not exceed 10mA.



Figure 7. I/O Interface Using 3.3V

## Signal Amplitude Respective to $\mathbf{V}_{\mathrm{IF}}$

When operating the MIC2551A, it is necessary to provide input signals which do not exceed  $V_{IF}$  + 0.3V.

#### Suspend

When the suspend pin (SUS) is high, power consumption is reduced to a minimum.  $V_{TRM}$  is not disabled. RCV,  $V_P$  and  $V_M$  are still functional to enable the device to detect USB activity. For minimal current consumption in suspend mode, it is recommended that OE# = 1, and SPD = 0.

#### Speed

The speed pin (SPD) sets D+/D- output edge rates by increasing or decreasing biasing current sources within the output drivers. For low speed, SPD = 0. For full speed, SPD = 1. By setting SPD = 0 during idle periods, in conjunction with suspend (SUS), the lowest quiescent current can be obtained. However, designers must provide a 300ns delay between changing SPD from 0 to 1 and transmission of data at full speed. This delay ensures the output drivers have arrived at their proper operating conditions. Failure to do so can result in leading edge distortion on the first few data bits transmitted.

#### Non-Multiplexed Bus

In order to save pin count for the USB logic controller interface, the MIC2551A was designed with  $V_P$  and  $V_M$  as bi-directional pins. To interface the MIC2551A with a non-multiplexed data bus, resistors can be used for low cost isolation, as shown in Figure 8.



Figure 8. MIC2551A Interface to Non-Multiplexed Data Bus

Configuration Mode	VBUS/VTRM	VIF	Notes
Normal	Connected	Connected	Normal supply configuration and operation.
Disconnect (D+/D- sharing)	Open	Connected	VP/VM are HIGH outputs, RCV is LOW. With OE# = 0 and SUS = 1, data lines may be driven with external devices up to 3.6V. With D+, D- floating, I <sub>IF</sub> draws less than 1µA.
Disconnect	Ground	Connected	VP/VM are HIGH outputs, RCV is LOW. With D+, D- floating, I <sub>IF</sub> draws less than 1µA.
Disable Mode	Connected	Open	Logic controlled input pins are Hi-Z. No communication is possible until interface voltage is restored.
Unpowered	Connected	Ground	Inoperative

Table 1. Power Supply Configuration

## **PCB Layout Recommendations**

Although the USB standard and applications are not based in an impedance-controlled environment, a properly designed PCB layout is recommended for optimal transceiver performance. The suggested PCB layout hints are as follows:

- Match signal line traces (VP/VM, D+, D–) to 40ps, approximately one-third inch if possible.
  FR-4 PCB material propagation is about 150ps/ inch, so to minimize skew try to keep VP/VM, D+/D– traces as short as possible.
- For every signal line trace width (w), separate the signal lines by 1.5 – 2 widths. Place all other traces at >2 widths from all signal line traces.
- Maintain the same number of vias on each differential trace, keeping traces approximately at same separation distance along the line.
- Control signal line impedances to ±10%.
- Keep  ${\rm R}_{\rm S}$  as close to the IC as possible, with equal distance between  ${\rm R}_{\rm S}$  and the IC for both D+ and D–.

## **Package Information**



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