# $2 \times 12$ A Digital Dual Output MicroDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current



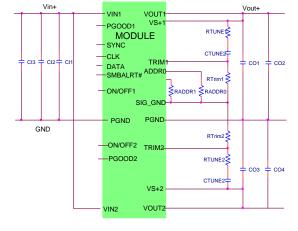




## **RoHS Compliant**

### **Applications**

- Distributed power architectures
- Intermediate bus voltage applications
- Telecommunications equipment
- Servers and storage applications
- Networking equipment
- Industrial equipment



#### **Features**

- Compliant to RoHS II EU "Directive 2011/65/EU"
- Compatible in a Pb-free or SnPb reflow environment
- Compliant to REACH Directive (EC) No 1907/2006
- Compliant to IPC-9592 (September 2008), Category 2, Class II
- Wide Input voltage range (4.5Vdc-14.4Vdc)
- Each Output voltage programmable from 0.6Vdc to 5.5Vdc via external resistor. Digitally adjustable down to 0.51Vdc
- Small size: 20.32 mm x 11.43 mm x 8.5 mm (0.8 in x 0.45 in x 0.335 in)
- Wide operating temperature range -40°C to 85°C
- Digital interface through the PMBus™ # protocol
- Tunable Loop<sup>™</sup> to optimize dynamic output voltage response
- Power Good signal for each output
- Fixed switching frequency with capability of external synchronization
- 180° Out-of-phase to reduce input ripple
- Output overcurrent protection (non-latching)
- Output Overvoltage protection
- Over temperature protection
- Remote On/Off
- Ability to sink and source current
- Start up into Pre-biased output
- Cost efficient open frame design
- UL\* 60950-1 2<sup>nd</sup> Ed. Recognized, CSA<sup>†</sup> C22.2 No. 60950-1-07 Certified, and VDE<sup>‡</sup> (EN60950-1 2<sup>nd</sup> Ed.) Licensed
- ISO\*\* 9001 and ISO 14001 certified manufacturing facilities

#### **Description**

The  $2 \times 12A$  Digital Dual MicroDlynx<sup>TM</sup> power modules are non-isolated dc-dc converters that can deliver up to  $2 \times 12A$  of output current. These modules operate over a wide range of input voltage ( $V_{IN} = 4.5 \text{Vdc} - 14.4 \text{Vdc}$ ) and provide precisely regulated output voltages from 0.51Vdc to 5.5Vdc, programmable via an external resistor and PMBus control. Features include a digital interface using the PMBus protocol, remote On/Off, adjustable output voltage, over current and over temperature protection. The PMBus interface supports a range of commands to both control and monitor the module. The module also includes the Tunable Loop<sup>TM</sup> feature that allows the user to optimize the dynamic response of the converter to match the load with reduced amount of output capacitance leading to savings on cost and PWB area.

- \* UL is a registered trademark of Underwriters Laboratories, Inc.
- † CSA is a registered trademark of Canadian Standards Association.
- <sup>‡</sup> *VDE* is a trademark of Verband Deutscher Elektrotechniker e.V.
- $^{\star\star}$  ISO is a registered trademark of the International Organization of Standards
- # The PMBus name and logo are registered trademarks of the System Management Interface Forum (SMIF)



# $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

### **Absolute Maximum Ratings**

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage	All	$V_{\text{IN1}}$ and $V_{\text{IN2}}$	-0.3	15	V
Continuous					
VS+1, VS+2, SMBALERT#	All		-0.3	7	V
CLK, DATA, SYNC,	All		-0.3	3.6	V
Operating Ambient Temperature	All	T <sub>A</sub>	-40	85	°C
(see Thermal Considerations section)					
Storage Temperature	All	T <sub>stg</sub>	-55	125	°C

### **Electrical Specifications**

 $Unless \ otherwise \ indicated, specifications \ apply \ over \ all \ operating \ input \ voltage, \ resistive \ load, \ and \ temperature \ conditions.$ 

Parameter	Device	Symbol	Min	Тур	Max	Unit
Operating Input Voltage	All	V <sub>IN1</sub> and V <sub>IN2</sub>	4.5	_	14.4	Vdc
Maximum Input Current	All	liN1,max & liN2,max			23	Adc
$(V_{IN}=4.5V \text{ to } 14.4V, I_{O}=I_{O, max})$						
Input No Load Current	$V_{O,set} = 0.6 \text{ Vdc}$	I <sub>IN1,No</sub> load & I <sub>IN2,No</sub> load		72		mA
$(V_{IN} = 12Vdc, I_O = 0, module enabled)$	V <sub>O,set</sub> = 5.5Vdc	I <sub>IN,1No load</sub> & I <sub>IN2,No load</sub>		210		mA
Input Stand-by Current (V <sub>IN</sub> = 12Vdc, module disabled)	All	I <sub>IN1,stand-by</sub> & I <sub>IN2,stand-by</sub>		14		mA
Inrush Transient	All	I <sub>1</sub> <sup>2</sup> t & I <sub>2</sub> <sup>2</sup> t			1	A <sup>2</sup> s
Input Reflected Ripple Current, peak-to-peak (5Hz to 20MHz, 1µH source impedance; V <sub>IN</sub> =4.5 to 14V, Io= I <sub>Omax</sub> ; See Test Configurations)	All	Both Inputs		25		mAp-p
Input Ripple Rejection (120Hz)	All	Both Inputs		-68		dB

# $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

## **Electrical Specifications** (continued)

Parameter	Device	Symbol	Min	Тур	Max	Unit
Output Voltage Set-point (with 0.1% tolerance for external resistor used to set output voltage)	All	VO1, set & VO2, set	-1.0		+1.0	% VO, set
Output Voltage (Over all operating input voltage, resistive load, and temperature conditions until end of life)	All	Vo1, set & VO2, set	-3.0	_	+3.0	% VO, set
Adjustment Range (selected by an external resistor) (Some output voltages may not be possible depending on the input voltage – see Feature Descriptions Section) *0.51V possible through PMBus command	All	VO1 & VO2	0.6*		5.5	Vdc
PMBus Adjustable Output Voltage Range	All	V <sub>01</sub> ,adj, V <sub>02</sub> ,adj	-15	0	+10	%V <sub>O,set</sub>
PMBus Output Voltage Adjustment Step Size	All	Both outputs	0.4			%V <sub>O,set</sub>
Remote Sense Range	All	Both outputs			0.5	Vdc
Output Regulation (for $V_0 \ge 2.5 \text{Vdc}$ )		Both Outputs				
Line ( $V_{IN}=V_{IN, min}$ to $V_{IN, max}$ )	All	Both Outputs			+0.4	$\% V_{0,  set}$
Load (I <sub>O</sub> =I <sub>O, min</sub> to I <sub>O, max</sub> )	All	Both Outputs			10	mV
Output Regulation (for $V_0 < 2.5Vdc$ )						
Line ( $V_{IN}=V_{IN, min}$ to $V_{IN, max}$ )	All	Both Outputs			5	mV
Load (Io=Io, min to Io, max)	All	Both Outputs		_	10	mV
Temperature (T <sub>ref</sub> =T <sub>A, min</sub> to T <sub>A, max</sub> )	All	Both Outputs		_	0.4	$\% V_{0,  set}$
Output Ripple and Noise on nominal output at 25°C						
(V <sub>IN</sub> =V <sub>IN, nom</sub> and I <sub>O</sub> =I <sub>O, min</sub> to I <sub>O, max</sub> Co = 2×0.1 + 2×47uF per output)						
Peak-to-Peak (5Hz to 20MHz bandwidth)	All		_	50	100	$mV_{pk-pk}$
RMS (5Hz to 20MHz bandwidth)	All			20	38	$mV_{rms}$
External Capacitance <sup>1</sup>						
Without the Tunable Loop $^{\text{TM}}$						
ESR ≥ 1 mΩ	All	C <sub>O, max</sub>	2×47	_	2×47	μF
With the Tunable Loop™						
ESR ≥ 0.15 mΩ	All	Co, max			1000	μF
ESR ≥ 10 mΩ	All	Co, max		_	5000	μF
Output Current (in either sink or source mode)	All	l <sub>o</sub>	0		12×2	Adc
Output Current Limit Inception (Hiccup Mode) (current limit does not operate in sink mode)	All	I <sub>O, lim</sub>		150		% I <sub>o,max</sub>
Output Short-Circuit Current	All	l <sub>01, s/c</sub> , l <sub>01, s/c</sub>		6		Arms
(Vo≤250mV) ( Hiccup Mode )						
Efficiency	V <sub>O,set</sub> = 0.6Vdc	η 1, η 2		79		%
V <sub>IN</sub> = 12Vdc, T <sub>A</sub> =25°C	V <sub>O, set</sub> = 1.2Vdc	η 1, η 2		88		%
I <sub>O</sub> =I <sub>O, max</sub> , V <sub>O</sub> = V <sub>O,set</sub>	V <sub>O,set</sub> = 1.8Vdc	η 1, η 2		91		%
	V <sub>0,set</sub> = 2.5Vdc	η 1, η 2		93		%
	V <sub>0, set</sub> = 3.3Vdc	η 1, η 2		94		%
	$V_{0,set} = 5.0Vdc$	η 1, η 2		95		%
Switching Frequency	All	f <sub>sw</sub>	_	500	_	kHz
<b>∀</b> 1111 7/	<u> </u>	344		1		

<sup>&</sup>lt;sup>1</sup> External capacitors may require using the new Tunable Loop<sup>™</sup> feature to ensure that the module is stable as well as getting the best transient response. See the Tunable Loop<sup>™</sup> section for details.

# $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12AOutput Current

## **Electrical Specifications** (continued)

Parameter	Device	Symbol	Min	Тур	Max	Unit
Frequency Synchronization	All					
Synch Frequency (2 x f <sub>switch</sub> )				1000		kHz
Synchronization Frequency Range	All		-5%		+5%	kHz
High-Level Input Voltage	All	VIH	2.0			V
Low-Level Input Voltage	All	VIL			0.4	V
Minimum Pulse Width, SYNC	All	tSYNC	100			ns
Maximum SYNC rise time	All	tSYNC_SH			100	ns

## **General Specifications**

Parameter	Device	Min	Тур	Max	Unit
Calculated MTBF (I <sub>O</sub> =0.8I <sub>O, max</sub> , T <sub>A</sub> =40°C) Telecordia Issue 3 Method 1 Case 3	All		75,767,425		Hours
Weight		_	4.5 (0.16)	_	g (oz.)

## **Feature Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Тур	Max	Unit
On/Off Signal Interface						
$(V_{IN}=V_{IN,min}$ to $V_{IN,max}$ ; open collector or equivalent, Signal referenced to GND)						
Device Code with no suffix – Negative Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with external pull-up resistor; signal referenced to GND)						
Logic High (Module OFF)  Input High Current  Input High Voltage	All All	lih1, lih2 Vih1, Vih2	_ 2	_	1 V <sub>IN, max</sub>	mA Vdc
Logic Low (Module ON)		,				
Input low Current Input Low Voltage	All All	IIL1, IIL2 VIL1, VIL2	-0.2	_	20 0.6	μA Vdc
Turn-On Delay and Rise Times						
$(V_{IN}=V_{IN,nom}, I_O=I_{O,max}, V_O)$ to within $\pm 1\%$ of steady state)  Case 1: On/Off input is enabled and then input power is applied (delay from instant at which $V_{IN}=V_{IN,min}$ until $V_O=10\%$ of $V_O$ , set)	All	Tdelay1, Tdelay2	_	2	_	msec
Case 2: Input power is applied for at least one second and then the On/Off input is enabled (delay from instant at which Von/Off is enabled until Vo = 10% of Vo, set)	All	Tdelay1, Tdelay2	_	800	_	µsec
Output voltage Rise time (time for $V_0$ to rise from 10% of $V_0$ , set to 90% of $V_0$ , set)	All	Trise1, Trise2	_	6	_	msec
Output voltage overshoot ( $T_A = 25^{\circ}C$ $V_{IN} = V_{IN, min}$ to $V_{IN, max}$ , $I_O = I_{O, min}$ to $I_{O, max}$ ) With or without maximum external capacitance		Both Outputs			3.0	% V <sub>O, set</sub>

# $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

## Feature Specifications (cont.)

Parameter	Device	Symbol	Min	Тур	Max	Units
Over Temperature Protection (See Thermal Considerations section)		$T_{ref}$		135		°C
PMBus Over Temperature Warning Threshold*	All	Twarn		125		°C
Input Undervoltage Lockout						
Turn-on Threshold	All	Both Inputs			4.5	Vdc
Turn-off Threshold	All	Both Inputs			4.25	Vdc
Hysteresis	All	Both Inputs	0.15	0.2		Vdc
PMBus Adjustable Input Under Voltage Lockout Thresholds	All	Both Inputs	4		14	Vdc
Resolution of Adjustable Input Under Voltage Threshold	All	Both Inputs			250	mV
PGOOD (Power Good)						
Signal Interface Open Drain, $V_{supply} \le 5VDC$						
Overvoltage threshold for PGOOD ON	All	Both Outputs		108.33		%V <sub>O, set</sub>
Overvoltage threshold for PGOOD OFF	All	Both Outputs		112.5		$%V_{O,set}$
Undervoltage threshold for PGOOD ON	All	Both Outputs		91.67		$%V_{O,set}$
Undervoltage threshold for PGOOD OFF	All	Both Outputs		87.5		$%V_{O,set}$
Pulldown resistance of PGOOD pin	All	Both Outputs		40	70	Ω
Sink current capability into PGOOD pin	All	Both Outputs			5	mA

<sup>\*</sup> Over temperature Warning – Warning may not activate before alarm and unit may shutdown before warning

# $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12AOutput Current

## **Digital Interface Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Conditions	Symbol	Min	Тур	Max	Unit
PMBus Signal Interface Characteristics				•		•
Input High Voltage (CLK, DATA)		VIH	2.1			V
Input Low Voltage (CLK, DATA)		VIL			0.8	V
Input high level current (CLK, DATA)		I <sub>IH</sub>	-10		10	μΑ
Input low level current (CLK, DATA)		I <sub>IL</sub>	-10		10	mA
Output Low Voltage (CLK, DATA, SMBALERT#)	I <sub>оит</sub> =2mA	Vol			0.4?	V
Output high level open drain leakage current (DATA, SMBALERT#)	V <sub>OUT</sub> =3.6V	Іон	0		10	μΑ
Pin capacitance		Co		0	1	pF
PMBus Operating frequency range	Slave Mode	FРMВ	10		400	kHz
Data hold time	Receive Mode Transmit Mode	thd:dat	0 300			ns
Data setup time		tsu:dat	250			ns
Measurement System Characteristics						
Output current measurement range		I <sub>RNG</sub>	0		18	А
Output current measurement gain accuracy (at 25°C)		lacc			±1	А
V <sub>OUT</sub> measurement range		V <sub>OUT(rng)</sub>	0.5		5.8	V
V <sub>OUT</sub> measurement accuracy			-2		2	%

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4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

#### **Characteristic Curves**

The following figures provide typical characteristics for the  $2 \times 12A$  Digital Dual MicroDlynx<sup>TM</sup> at 0.6Vo and 25°C.

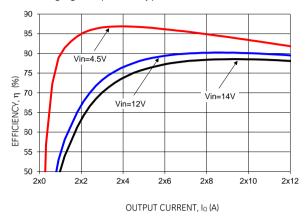


Figure 1. Converter Efficiency versus Output Current.

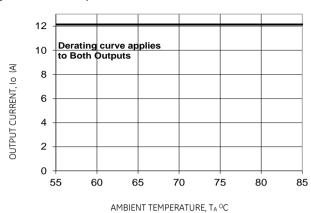


Figure 2. Derating Output Current versus Ambient Temperature and Airflow.

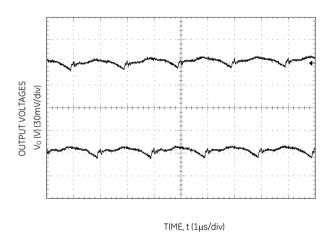
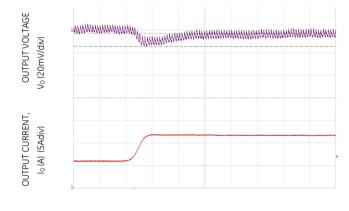


Figure 3. Typical output ripple and noise ( $C_0=2\times0.1uF+2\times47uF$  ceramic,  $V_{IN}=12V$ ,  $I_0=I_{01,max}$ ,  $I_{02,max}$ ,  $I_0=I_{01,max}$ ,  $I_0=I_0$ ,



TIME, t (20µs /div)

Figure 4. Transient Response to Dynamic Load Change from 50% to 100% on one output at 12Vin, Cout=2x47uF+7x330uF, CTune=12nF, RTune=300 $\Omega$ 

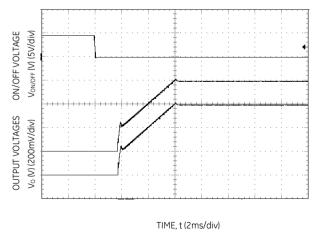


Figure 5. Typical Start-up Using On/Off Voltage (Vin=12V, Io = Io1,max, Io2,max,).

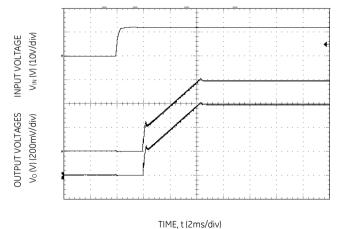


Figure 6. Typical Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_0 = I_{01,max}$ ,  $I_{02,max}$ ).

# 2 × 12A Digital Dual MicroDlynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12AOutput Current

#### **Characteristic Curves**

The following figures provide typical characteristics for the  $2 \times 12A$  Digital Dual MicroDlynx<sup>TM</sup> at 1.2Vo and 25°C.

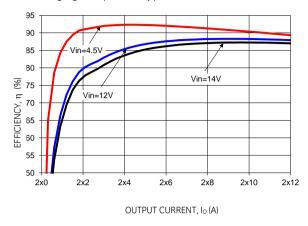


Figure 7. Converter Efficiency versus Output Current.

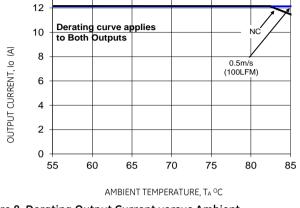


Figure 8. Derating Output Current versus Ambient Temperature and Airflow.

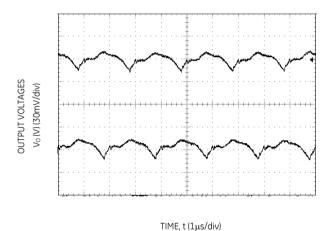


Figure 9. Typical output ripple and noise ( $C_0$ =  $2\times0.1$ uF+ $2\times47$ uF ceramic,  $V_{IN}$  = 12V,  $I_0$  =  $I_01$ , $I_0$ , $I_0$ 2, $I_0$ 3.

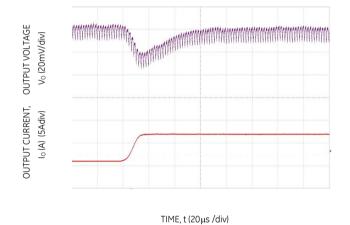


Figure 10. Transient Response to Dynamic Load Change on one output from 50% to 100% at 12Vin, Cout=3x47uF+3x330uF, CTune=2700pF & RTune=300 $\Omega$ 



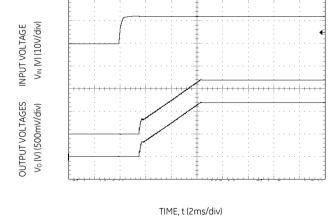


Figure 12. Typical Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_0 = I_{01,max}$ ,  $I_{02,max}$ ).

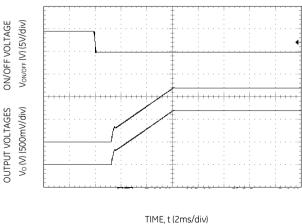


Figure 1. Typical Start-up Using On/Off Voltage ( $V_{IN} = 12V$ ,  $I_0 = I_{01,max}$ ,  $I_{02,max}$ ).

# 2 × 12A Digital Dual MicroDlynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

#### **Characteristic Curves**

The following figures provide typical characteristics for the  $2 \times 12A$  Digital Dual MicroDlynx<sup>TM</sup> at 1.8Vo and 25°C.

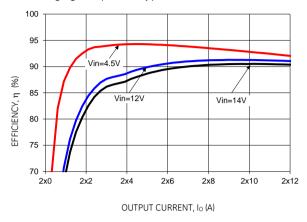


Figure 13. Converter Efficiency versus Output Current.

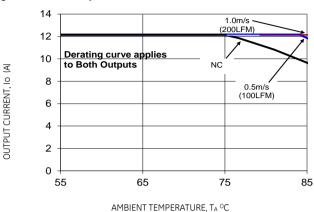


Figure 14. Derating Output Current versus Ambient Temperature and Airflow.

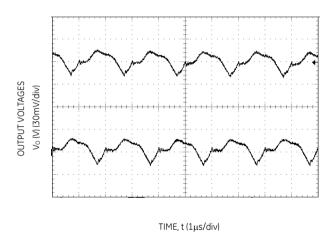


Figure 15. Typical output ripple and noise ( $C_0$ =  $2\times0.1$ uF+ $2\times47$ uF ceramic, VIN = 12V, Io = Io1,max, Io2,max).

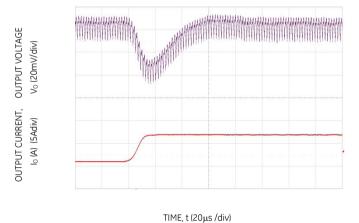


Figure 16. Transient Response to Dynamic Load Change on one output from 50% to 100% at 12Vin, Cout =

3x47uF+2x330uF, CTune = 1800pF & RTune =  $300\Omega$ 



Figure 17. Typical Start-up Using On/Off Voltage (VIN = 12V,  $l_0 = l_{01,max}, l_{02,max}$ ).

TIME, t (2ms/div)

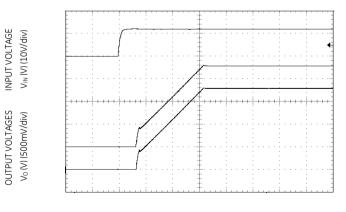


Figure 18. Typical Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_0 =$ lo1,max, lo2,max).

ON/OFF VOLTAGE Von/OFF (V) (5V/div)

**OUTPUT VOLTAGES** 

V<sub>o</sub> (V) (500mV/div)

# 2 × 12A Digital Dual MicroDlynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 x 12AOutput Current

#### **Characteristic Curves**

The following figures provide typical characteristics for the  $2 \times 12A$  Digital Dual MicroDlynx<sup>TM</sup> at 2.5Vo and 25°C.

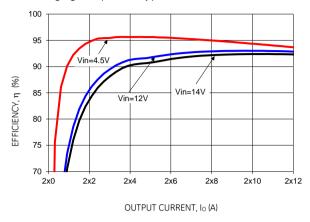


Figure 19. Converter Efficiency versus Output Current.

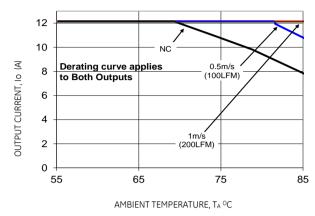


Figure 20. Derating Output Current versus Ambient Temperature and Airflow.

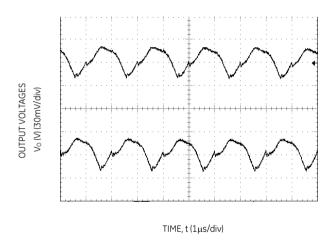


Figure 21. Typical output ripple and noise ( $C_0$ = 2x0.1uF+2x47uF ceramic,  $V_{IN}$  = 12V,  $I_0$  =  $I_{01,max}$ ,  $I_{02,max}$ ).

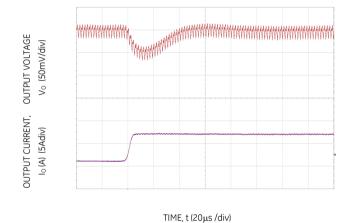


Figure 22. Transient Response to Dynamic Load Change on one output from 50% to 100% at 12Vin, Cout=3x47uF+2x330uF, CTune=1500pF & RTune =  $300\Omega$ 

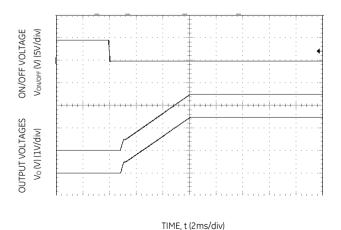


Figure 23. Typical Start-up Using On/Off Voltage ( $V_{IN} = 12V$ ,  $I_0 = I_{01,max}$ ,  $I_{02,max}$ ).

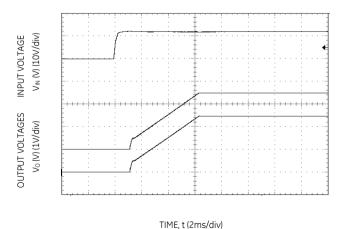


Figure 24. Typical Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_0 = I_{01,max}$ ,  $I_{02,max}$ ).

# 2 × 12A Digital Dual MicroDlynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

#### **Characteristic Curves**

The following figures provide typical characteristics for the  $2 \times 12A$  Digital Dual MicroDlynx<sup>TM</sup> at 3.3Vo and 25°C.

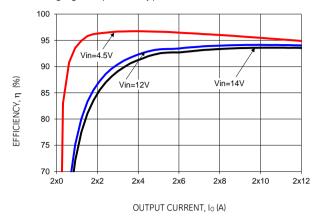


Figure 25. Converter Efficiency versus Output Current.

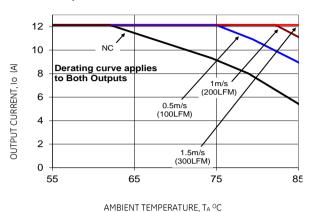


Figure 26. Derating Output Current versus Ambient

Temperature and Airflow.

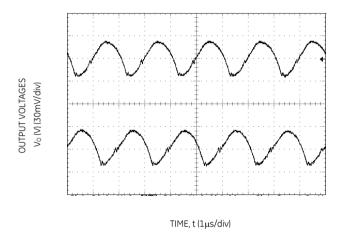


Figure 27. Typical output ripple and noise ( $C_0$ = 2x0.1uF+2x47uF ceramic,  $V_{IN}$  = 12V,  $I_0$  =  $I_{01,max}$ ,  $I_{02,max}$ ).

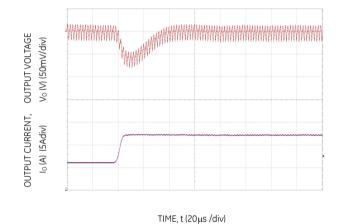


Figure 28 Transient Response to Dynamic Load Change on one output from 50% to 100% at 12Vin, Cout=3x47uF+1x330uF, CTune = 1200pF & RTune =  $300\Omega$ 

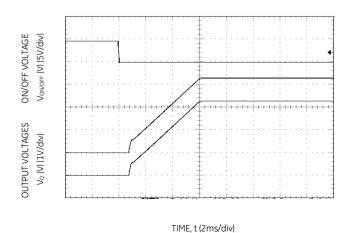


Figure 29. Typical Start-up Using On/Off Voltage ( $V_{IN} = 12V$ ,  $I_0 = I_{01,max}$ ,  $I_{02,max}$ ).

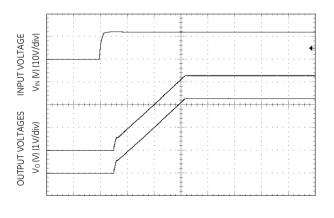


Figure 30. Typical Start-up Using Input Voltage ( $V_{IN}=12V$ ,  $I_0=I_{01,max},I_{02,max}$ ).

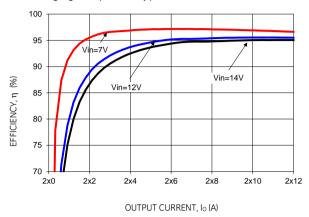
# 2 × 12A Digital Dual MicroDlynx™: Non-Isolated DC-DC Power Modules

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4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 x 12AOutput Current

#### **Characteristic Curves**

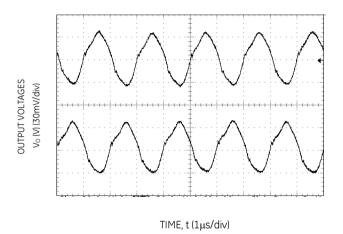
The following figures provide typical characteristics for the  $2 \times 12A$  Digital Dual MicroDlynx<sup>TM</sup> at 5Vo and 25°C.



3.0m/s (600LFM) 12 10 OUTPUT CURRENT, Io (A) 8 Derating curve applies 6 to Both Outputs (300LFM) 4 1m/s (200LFM) 0.5m/s 2 (100LFM) 2m/s (400LFM) O 75 45 55 65 85 AMBIENT TEMPERATURE, TA °C

Figure 31. Converter Efficiency versus Output Current.

Figure 32. Derating Output Current versus Ambient Temperature and Airflow.



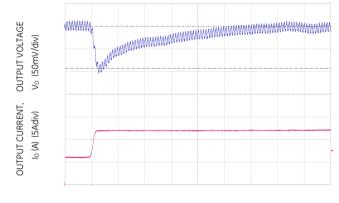
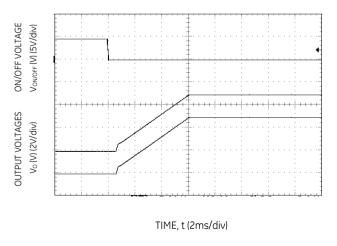


Figure 33. Typical output ripple and noise ( $C_0 = 2 \times 0.1 uF + 2 \times 47 uF$  ceramic,  $V_{IN} = 12 V$ ,  $I_0 = I_{01,max}$ ,  $I_{02,max}$ ).

Figure 34. Transient Response to Dynamic Load Change on one output from 50% to 100% at 12Vin, Cout=6x47uF, CTune=470pF & RTune=300 $\Omega$ 

TIME, t (20µs /div)



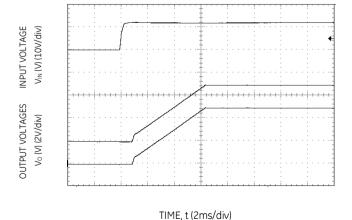


Figure 35. Typical Start-up Using On/Off Voltage ( $V_{IN} = 12V$ ,  $I_0 = I_{01,max}$ ,  $I_{02,max}$ ).

Figure 36. Typical Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_0 = I_{01,max}$ ,  $I_{02,max}$ ).

## 2 × 12A Digital Dual MicroDlynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

### **Design Considerations**

#### **Input Filtering**

The 2 × 12A Digital Dual MicroDlynx<sup>TM</sup> module should be connected to a low ac-impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pin of the module, to minimize input ripple voltage and ensure module stability.

To minimize input voltage ripple, ceramic capacitors are recommended at the input of the module. Figure 37 shows the input ripple voltage for various output voltages at2 x 12A of load current with 2x22  $\mu F$  or 3x22  $\mu F$  ceramic capacitors and an input of 12V.

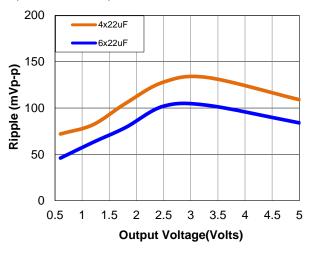


Figure 37. Input ripple voltage for various output voltages with 4x22  $\mu F$  or 6x22  $\mu F$  ceramic capacitors at the input (2 x 12A load). Input voltage is 12V.

#### **Output Filtering**

These modules are designed for low output ripple voltage and will meet the maximum output ripple specification with 0.1  $\mu\text{F}$  ceramic and 22  $\mu\text{F}$  ceramic capacitors at the output of the module. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR polymer and ceramic capacitors are recommended to improve the dynamic response of the module. Figure 38 provides output ripple information for different external capacitance values at various Vo and a full load current of  $2\times12A$ . For stable operation of the module, limit the capacitance to less than the maximum output capacitance as specified in the electrical specification table. Optimal performance of the module can be achieved by using the Tunable Loop  $^{\text{TM}}$  feature described later in this data sheet.

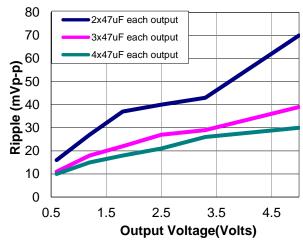


Figure 38. Output ripple voltage for various output voltages with total external 4x47  $\mu$ F, 6x47  $\mu$ F or 8x47  $\mu$ F ceramic capacitors at the output (2 x 12A load). Input voltage is 12V.

#### **Safety Considerations**

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., UL 60950-1 2nd, CSA C22.2 No. 60950-1-07, DIN EN 60950-1:2006 + A11 (VDE0805 Teil 1 + A11):2009-11; EN 60950-1:2006 + A11:2009-03.

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV), the input must meet SELV requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

The input to these units is to be provided with a fast-acting fuse with a maximum rating of 30A (voltage rating 125Vac) in the positive input lead. (Littelfuse 456 Series or equivalent)

## 2 × 12A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 x 12AOutput Current

### **Analog Feature Descriptions**

#### Remote On/Off

The module can be turned ON and OFF either by using the ON/OFF pin (Analog interface) or through the PMBus interface (Digital). The module can be configured in a number of ways through the PMBus interface to react to the two ON/OFF inputs:

- Module ON/OFF can be controlled only through the analog interface (digital interface ON/OFF commands are ignored)
- Module ON/OFF can be controlled only through the PMBus interface (analog interface is ignored)
- Module ON/OFF can be controlled by either the analog or digital interface

The default state of the module (as shipped from the factory) is to be controlled by the analog interface only. If the digital interface is to be enabled, or the module is to be controlled only through the digital interface, this change must be made through the PMBus. These changes can be made and written to non-volatile memory on the module so that it is remembered for subsequent use.

#### **Analog On/Off**

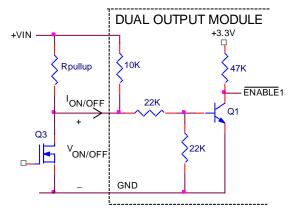
The2 × 12A Digital Dual MicroDlynx™ power modules feature an On/Off pin for remote On/Off operation. Two On/Off logic options are available. In the Positive Logic On/Off option, (device code suffix "4" – see Ordering Information), the module turns ON during a logic High on the On/Off pin and turns OFF during a logic Low. With the Negative Logic On/Off option, (no device code suffix, see Ordering Information), the module turns OFF during logic High and ON during logic Low. The On/Off signal should be always referenced to ground. For either On/Off logic option, leaving the On/Off pin disconnected will turn the module ON when input voltage is present.

For positive logic modules, the circuit configuration for using the On/Off pin is shown in Figure 39. When the external transistor is in the OFF state, the internal transistor Q1 is turned ON, and the internal PWM Enable# signal(normally low) is pulled low causing the module to be ON. When ext. transistor is turned ON, the On/Off pin is pulled low, and the internal PWM Enable# signal(normally low) is pulled high and the module is OFF. For negative logic On/Off modules, the circuit configuration is shown in Fig. 40. When external transistor is in the OFF state, the On/Off pin is pulled high, transistor Q1 is turned ON and the internal PWM Enable signal is pulled low and the module is OFF. To turn the module ON, the external transistor is turned ON pulling the On/Off pin low, turning transistor Q1 OFF resulting in the PWM Enable pin going high and the module turns ON

#### Digital On/Off

Please see the Digital Feature Descriptions section.

#### Output 1



Output 2

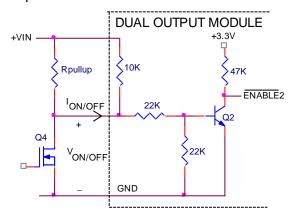
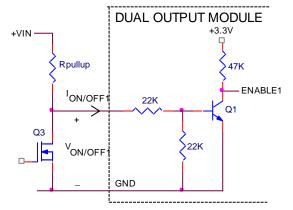


Figure 39. Circuit configuration for using positive On/Off logic.

#### Output 1



## 2 × 12A Digital Dual MicroDlynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

#### Output 2

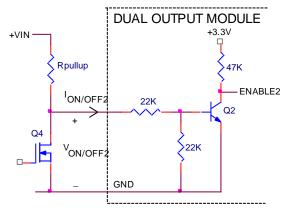


Figure 40. Circuit configuration for using negative On/Off logic.

#### **Monotonic Start-up and Shutdown**

The module has monotonic start-up and shutdown behavior for any combination of rated input voltage, output current and operating temperature range.

#### **Startup into Pre-biased Output**

The module can start into a prebiased output on either or both outputs as long as the prebias voltage is 0.5V less than the set output voltage.

#### **Analog Output Voltage Programming**

The voltage of each output can be programmed to any voltage from 0.6dc to 5.5Vdc by connecting a resistor between the 2 Trims and SIG\_GND pins of the module. Restrictions on the output voltage set point depending on the input voltage are shown in the Output Voltage vs. Input Voltage Set Point Area plot in Fig. 41. The Upper Limit curve shows that for output voltages lower than 1V, the input voltage must be lower than the maximum of 14.4V. When the output voltage is trimmed lower than 0.6V, then the max input voltage shall be reduced by the same factor. Currently the max input voltage for 0.6Vout is 13V. The Lower Limit curve shows that for output voltages higher than 0.6V, the input voltage needs to be larger than the minimum of 4.5V.

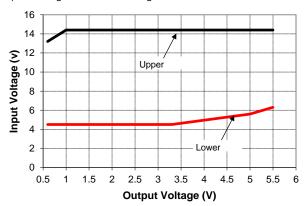
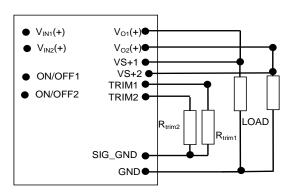


Figure 41. Output Voltage vs. Input Voltage Set Point Area plot showing limits where the output voltage can be set for different input voltages.



Caution – Do not connect SIG\_GND to GND elsewhere in the layout

Figure 42. Circuit configuration for programming output voltage using an external resistor.

Without an external resistor between Trim and SIG\_GND pins, each output of the module will be 0.6Vdc.To calculate the value of the trim resistor, *Rtrim* for a desired output voltage, should be as per the following equation:

$$Rtrim = \left[\frac{12}{(Vo - 0.6)}\right] k\Omega$$

Rtrim is the external resistor in  $k\Omega$ 

Vo is the desired output voltage.

Table 1 provides Rtrim values required for some common output voltages.

Table 1

Vo, set (V)	Rtrim (KΩ)
0.6	Open
0.9	40
1.0	30
1.2	20
1.5	13.33
1.8	10
2.5	6.316
3.3	4.444
5.0	2.727

#### **Digital Output Voltage Adjustment**

Please see the Digital Feature Descriptions section.

#### **Remote Sense**

The power module has a Remote Sense feature to minimize the effects of distribution losses by regulating the voltage between the sense pins (VS+ and VS-) for each of the 2 outputs. The voltage drop between the sense pins and the VOUT and GND pins of the module should not exceed 0.5V. If there is an inductor being used on the module output, then the tunable loop feature of the module should be used to ensure module stability with the proposed sense point

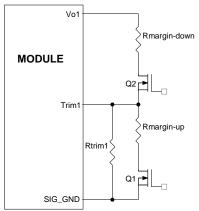
## $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 x 12AOutput Current

location. If the simulation tools and loop feature of the module are not being used, then the remote sense should always be connected before the inductor. The sense trace should also be kept away from potentially noisy areas of the board

#### **Analog Voltage Margining**

Output voltage margining can be implemented in the module by connecting a resistor, R<sub>margin-up</sub>, from the Trim pin to the ground pin for margining-up the output voltage and by connecting a resistor, R<sub>margin-down</sub>, from the Trim pin to output pin for margining-down. Figure 43 shows the circuit configuration for output voltage margining. The POL Programming Tool, available at www.gecriticalpower.com in the Embedded Power group, also calculates the values of R<sub>margin-up</sub> and R<sub>margin-down</sub> for a specific output voltage and % margin. Please consult your local GE technical representative for additional details.



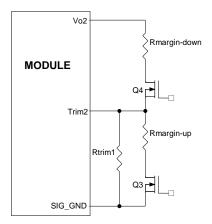


Figure 43. Circuit Configuration for margining Output voltage.

### **Digital Output Voltage Margining**

Please see the Digital Feature Descriptions section.

#### **Overcurrent Protection**

To provide protection in a fault (output overload) condition, the unit is equipped with internal current-limiting circuitry on both outputs and can endure current limiting continuously.

At the point of current-limit inception, the unit enters hiccup mode. The unit operates normally once the output current is brought back into its specified range.

#### **Digital Adjustable Overcurrent Warning**

Please see the Digital Feature Descriptions section.

#### **Overtemperature Protection**

To provide protection in a fault condition, the unit is equipped with a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of  $135^{\circ}C(typ)$  is exceeded at the thermal reference point  $T_{ref}$ . Once the unit goes into thermal shutdown it will then wait to cool before attempting to restart.

#### **Digital Temperature Status via PMBus**

Please see the Digital Feature Descriptions section.

# Digitally Adjustable Output Over and Under Voltage Protection

Please see the Digital Feature Descriptions section.

#### Input Undervoltage Lockout

At input voltages below the input undervoltage lockout limit, the module operation is disabled. The module will begin to operate at an input voltage above the undervoltage lockout turn-on threshold.

#### Digitally Adjustable Input Undervoltage Lockout

Please see the Digital Feature Descriptions section.

#### **Digitally Adjustable Power Good Thresholds**

Please see the Digital Feature Descriptions section.

#### **Synchronization**

The module switching frequency can be synchronized to a signal with an external frequency within a specified range. Synchronization can be done by using the external signal applied to the SYNC pin of the module as shown in Fig. 45, with the converter being synchronized by the rising edge of the external signal. The Electrical Specifications table specifies the requirements of the external SYNC signal. If the SYNC pin is not used, the module should free run at the default switching frequency. If synchronization is not being used, connect the SYNC pin to GND.

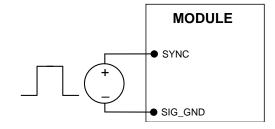


Figure 45. External source connections to synchronize switching frequency of the module.

Measuring Output Current, Output Voltage and Temperature

# $2 \times 12A$ Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules 4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

Please see the Digital Feature Descriptions section.

#### Tunable Loop™

The module has a feature that optimizes transient response of the module called Tunable Loop<sup>TM</sup>.

External capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise (see Figure 38) and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable.

The Tunable Loop<sup>TM</sup> allows the user to externally adjust the voltage control loop to match the filter network connected to the output of the module. The Tunable Loop<sup>TM</sup> is implemented by connecting a series R-C between the VS+ and TRIM pins of the module, as shown in Fig. 47. This R-C allows the user to externally adjust the voltage loop feedback compensation of the module.

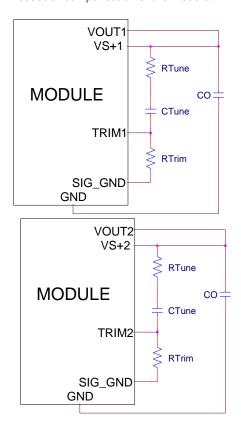


Figure. 47. Circuit diagram showing connection of  $R_{\text{TUNE}}$  and  $C_{\text{TUNE}}$  to tune the control loop of the module.

Recommended values of  $R_{TUNE}$  and  $C_{TUNE}$  for different output capacitor combinations are given in Table 2. Table 2 shows the recommended values of  $R_{TUNE}$  and  $C_{TUNE}$  for different values of ceramic output capacitors up to 1000uF that might be needed for an application to meet output ripple and noise requirements. Selecting  $R_{TUNE}$  and  $C_{TUNE}$  according to Table 2 will ensure stable operation of the module. In applications with tight output voltage limits in the presence of dynamic current loading, additional output capacitance will be required. Table 3 lists recommended values of  $R_{TUNE}$  and  $C_{TUNE}$  in order to meet 2% output voltage deviation limits for some common output voltages in the presence of a 6A to 12A step change (50% of full load), with an input voltage of 12V.

Please contact your GE technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external R-C to tune the module for best transient performance and stable operation for other output capacitance values.

Table 2. General recommended values of of  $R_{\text{TUNE}}$  and  $C_{\text{TUNE}}$  for Vin=12V and various external ceramic capacitor combinations.

Со	3x47μF	4x47μF	6x47μF	10x47μF	20x47μF
R <sub>TUNE</sub>	300	300	300	300	300
C <sub>TUNE</sub>	220pF	330pF	1000pF	1800pF	3900pF

Table 3. Recommended values of R<sub>TUNE</sub> and C<sub>TUNE</sub> to obtain transient deviation of 2% of Vout for a 6A step load with Vin=12V.

Vo	5V	3.3V	2.5V	1.8V	1.2V	0.6V
Co	6x47μF	3x47μF + 330μF Polymer	+ 2×330μF	2422011	3x47μF + 3x330μF Polymer	2x47μF + 7x330μF Polymer
R <sub>TUNE</sub>	300	300	300	300	300	300
CTUNE	470pF	1200pF	1500pF	1800pF	2700pF	12nF
ΔV	84mV	39mV	30mV	27mV	20mV	10mV

Note: The capacitors used in the Tunable Loop tables are 47  $\mu$ F/2 m $\Omega$  ESR ceramic and 330  $\mu$ F/12 m $\Omega$  ESR polymer capacitors.

## 2 × 12A Digital Dual MicroDlynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 x 12AOutput Current

### **Digital Feature Descriptions**

#### **PMBus Interface Capability**

The 2 × 12A Digital Dual MicroDlynx<sup>TM</sup> power modules have a PMBus interface that supports both communication and control. The PMBus Power Management Protocol Specification can be obtained from <a href="https://www.pmbus.org">www.pmbus.org</a>. The modules support a subset of version 1.1 of the specification (see Table 6 for a list of the specific commands supported). Most module parameters can be programmed using PMBus and stored as defaults for later use.

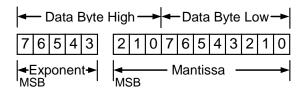
All communication over the module PMBus interface must support the Packet Error Checking (PEC) scheme. The PMBus master must generate the correct PEC byte for all transactions, and check the PEC byte returned by the module.

The module also supports the SMBALERT# response protocol whereby the module can alert the bus master if it wants to talk. For more information on the SMBus alert response protocol, see the System Management Bus (SMBus) specification.

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored can be saved (see Table 6 for which command parameters can be saved to non-volatile storage).

#### **PMBus Data Format**

For commands that set thresholds, voltages or report such quantities, the module supports the "Linear" data format among the three data formats supported by PMBus. The Linear Data Format is a two byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent. The format of the two data bytes is shown below:



The value is of the number is then given by

Value = Mantissa x 2 Exponent

#### **PMBus Addressing**

The power module can be addressed through the PMBus using a device address. The module has 64 possible addresses (0 to 63 in decimal) which can be set using resistors connected from the ADDR0 and ADDR1 pins to SIG\_GND. Note that some of these addresses (0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11 12, 40, 44, 45, 55 in decimal) are reserved according to the SMBus specifications and may not be useable. The address is set in the form of two octal (0 to 7) digits, with each pin setting one digit. The ADDR1 pin sets the high order digit and ADDR0 sets the low order digit. The resistor values suggested for each digit are shown in Table 4 (1% tolerance resistors are recommended). Note that if

either address resistor value is outside the range specified in Table 4, the module will respond to address 127.

Table 4

Digit	Resistor Value (KΩ)
0	11
1	18.7
2	27.4
3	38.3
4	53.6
5	82.5
6	127
7	187

The user must know which I<sup>2</sup>C addresses are reserved in a system for special functions and set the address of the module to avoid interfering with other system operations. Both 100kHz and 400kHz bus speeds are supported by the module. Connection for the PMBus interface should follow the High Power DC specifications given in section 3.1.3 in the SMBus specification V2.0 for the 400kHz bus speed or the Low Power DC specifications in section 3.1.2. The complete SMBus specification is available from the SMBus web site, smbus.org.

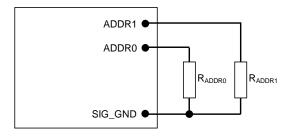


Figure 48. Circuit showing connection of resistors used to set the PMBus address of the module.

#### **PAGE**

Both the outputs of the module can be configured, controlled and monitored through only one physical address

Format	Unsigned Binary							
Bit Position	7	6	5	4	3	2	1	0
Access	r/w	r	r	r	r	r	r	r/w
Function	PA	Χ	Χ	Χ	Χ	Χ	Χ	P0
Default Value	0	Χ	X	Χ	Х	X	Χ	0

#### **PAGE Command Truth Table**

PA	P0	Logic Results	
0	0	All Commands address first output	
0	1	All Commands address second output	
1	0	Illegal input, Ignore write	
1	1	All Commands address both outputs	

If PAGE=11, then any read commands affect the first channel. Any value to ready-only registers is ignored.

## $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

#### Operation (01h)

This is a paged register. The OPERATION command can be use to turn the module on or off in conjunction with the ON/OFF pin input. It is also used to margin up or margin down the output voltage

#### PMBus Enabled On/Off

The module can also be turned on and off via the PMBus interface. The OPERATION command is used to actually turn the module on and off via the PMBus, while the ON\_OFF\_CONFIG command configures the combination of analog ON/OFF pin input and PMBus commands needed to turn the module on and off. Bit [7] in the OPERATION command data byte enables the module, with the following functions:

0 : Output is disabled 1 : Output is enabled

This module uses the lower five bits of the ON\_OFF\_CONFIG data byte to set various ON/OFF options as follows:

Bit Position	4	3	2	1	0
Access	r/w	r/w	r/w	r	r
Function	PU	CMD	CPR	POL	CPA
Default Value	1	0	1	1	0

PU: Sets the default to either operate any time input power is present or for the ON/OFF to be controlled by the analog ON/OFF input and the PMBus OPERATION command. This bit is used together with the CP, CMD and ON bits to determine startup.

Bit Value	Action
0	Module powers up any time power is present regardless of state of the analog ON/OFF pin
1	Module does not power up until commanded by the analog ON/OFF pin and the OPERATION command as programmed in bits [2:0] of the ON_OFF_CONFIG register.

CMD: The CMD bit controls how the device responds to the OPERATION command.

Bit Value	Action
0	Module ignores the ON bit in the OPERATION command
1	Module responds to the ON bit in the OPERATION command

CPR: Sets the response of the analog ON/OFF pin. This bit is used together with the CMD, PU and ON bits to determine startup.

Bit Value	Action

	Module ignores the analog ON/OFF pin, i.e. ON/OFF is only controlled through the PMBUS via the OPERATION command
1	Module requires the analog ON/OFF pin to be asserted to start the unit

CPA: Sets the action of the analog ON/OFF pin when turning the controller OFF. This bit is internally read and cannot be modified by the user

#### **PMBus Adjustable Soft Start Rise Time**

The soft start rise time can be adjusted in the module via PMBus. When setting this parameter, make sure that the charging current for output capacitors can be delivered by the module in addition to any load current to avoid nuisance tripping of the overcurrent protection circuitry during startup. The TON\_RISE command sets the rise time in ms, and allows choosing soft start times between  $600\mu$ s and 9ms, with possible values listed in Table 5. Note that the exponent is fixed at -4 (decimal) and the upper two bits of the mantissa are also fixed at 0.

Table 5

Rise Time	Exponent	Mantissa
600µs	11100	0000001010
900µs	11100	0000001110
1.2ms	11100	00000010011
1.8ms	11100	00000011101
2.7ms	11100	00000101011
4.2ms	11100	00001000011
6.0ms	11100	00001100000
9.0ms	11100	00010010000

### **Output Voltage Adjustment Using the PMBus**

The VREF\_TRIM parameter is important for a number of PMBus commands related to output voltage trimming, and margining. Each of the 2 output voltages of the module can be set as the combination of the voltage divider formed by RTrim and a  $20k\Omega$  upper divider resistor inside the module, and the internal reference voltage of the module. The reference voltage  $V_{\text{REF}}$  is be nominally set at 600mV, and the output regulation voltage is then given by

$$V_{OUT.1} = \left[\frac{20000 + RTrim1}{RTrim1}\right] \times V_{REF}$$

$$\left[20000 + RTrim2\right]$$

$$V_{OUT.2} = \left[\frac{20000 + RTrim2}{RTrim2}\right] \times V_{REF}$$

Hence the module output voltages is dependent on the value of RTrim1 and Rtrim2 which are connected external to the module.

The VREF\_TRIM parameter is used to apply a fixed offset voltage to the reference voltage canbe specified using the "Linear" format and two bytes. The exponent is fixed at –9 (decimal). The resolution of the adjustment is 7 bits, with a

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resulting step size of approximately 0.4%. The maximum trim range is -20% to +10% of the nominal reference voltage(600mV) in 2mV steps. Possible values range from -120mV to +60mV. The exception is at 0.6Vout where the allowable trim range is only -90mV to +60mV to prevent the module from operating at lower than 0.51Vdc. When trimming the voltage below 0.6V, the module max. input voltage operating point also reduces proportionally. As shown earlier in Fig.41, the maximum permissible input voltage is 13V. For any voltage trimmed below 0.6V, the maximum input voltage will have to be reduced by the same factor.

When PMBus commands are used to trim or margin the output voltage, the value of  $V_{\text{REF}}$  is what is changed inside the module, which in turn changes the regulated output voltage of the module.

The nominal output voltage of the module is adjustable with a minimum step size of 0.4% over a +10% to -20% range from nominal using the VREF\_TRIM command over the PMBus.

The VREF\_TRIM command can be used to apply a fixed offset voltage to either of the output voltage command value using the "Linear" mode with the exponent fixed at -9 (decimal). The value of the offset voltage is given by

$$V_{REF\ (offset)} = VREF\ \_TRIM \times 2^{-9}$$

This offset voltage is added to the voltage set through the divider ratio and nominal  $V_{REF}$  to produce the trimmed output voltage. If a value outside of the +10%/-20% adjustment range is given with this command, the module will set it's output voltage to the upper or lower limit value (as if VOUT\_TRIM, assert SMBALRT#, set the CML bit in STATUS\_BYTE and the invalid data bit in STATUS\_CML.

#### **Applications Example**

For a design where the output voltage is 1.8V and the output needs to be trimmed down by 20mV.

- The internal reference voltage is 0.6V. So we need to determine how the 20mV translates to a change in the internal reference voltage.
- Divider Ratio = Vref/Vout = 0.6/1.8 = 0.33
- Hence a 20mV change at 1.8Vo requires a 0.33x20mV = 6.6mV change in the reference voltage.
- Vref(offset) = (6.6)/1000 = 0.0066 Volts (- sign since we are trimming down)
- Vref(offset) = Vref\_Trim x 2 -9
- $V_{ref\_Trim} = V_{ref(offset)} x 512$
- $V_{ref\_Trim} = -0.0066 \times 512 = -3.3 = -3$  (rounded to nearest integer

#### **Output Voltage Margining Using the PMBus**

Each output of the module can also have its output voltage margined via PMBus commands. The command STEP\_VREF\_MARGIN\_HIGH will set the margin high voltage, while the command STEP\_VREF\_MARGIN\_LOW sets the margin low voltage. Both the STEP\_VREF\_MARGIN\_HIGH and STEP\_VREF\_MARGIN\_LOW commands will use the "Linear" mode with the exponent fixed at -9 (decimal). Two bytes are used for the mantissa with the upper bit [7] of the

high byte fixed at 0. The actual margined output voltage is a combination of the STEP\_VREF\_MARGIN\_HIGH or STEP\_VREF\_MARGIN\_LOW and the VREF\_TRIM values as shown below. The net permissible voltage range change is -30% to +10% for the margin high command and -20% to 0% for the margin low command

$$V_{REF\,(MH)} =$$

 $(STEP\_VREF\_MARGIN\_HIGH+VREF\_TRIM) \times 2^{-9}$ 

#### **Applications Example**

For a design where the output voltage is 1.2V and the output needs to be trimmed up by 100mV (within 10% of Vo).

- The internal reference voltage is 0.6V. So we need to determine how the 100mV translates to a change in the internal reference voltage.
- Divider Ratio = Vref/Vout = 0.6/1.2 = 0.5
- Hence a 100mV change at 1.2Vo requires a 0.5x100mV = 50mV change in the reference voltage.
- $V_{REF(MH)} = (50)/1000 = 0.05 \text{ Volts}$
- VREF(MH) = (Step\_Vref\_margin\_high + Vref\_trim) x 2 -9
- Assume V<sub>ref Trim</sub> = 0 here
- Step\_Vref\_margin\_high = VREF(MH) x 512
- Step\_V<sub>ref\_margin\_high</sub> = 0.05 x 25.6 = 26 (rounded to nearest integer

$$V_{REF(ML)} =$$

 $(STEP\_VREF\_MARGIN\_LOW+VREF\_TRIM) \times 2^{-9}$ 

#### **Applications Example**

For a design where the output voltage is 1.8V and the output needs to be trimmed down by 100mV (within -20% of Vo).

- The internal reference voltage is 0.6V. So we need to determine how the 100mV translates to a change in the internal reference voltage.
- Divider Ratio = Vref/Vout = 0.6/1.8 = 0.33
- Hence a 100mV change at 1.2Vo requires a 0.33x100mV = 33mV change in the reference voltage.
- $V_{REF(MH)} = -(33)/1000 = -0.033$  Volts (- sign since we are margining down)
- V<sub>REF(ML)</sub> = (Step V<sub>ref margin low</sub> + V<sub>ref trim</sub>) x 2 -9
- Assume V<sub>ref\_Trim</sub> = 3 here (from V <sub>Ref\_Trim</sub> example earlier)
- Step\_V<sub>ref\_margin\_low</sub> = V<sub>REF(ML)</sub> x 512 V<sub>ref\_trim</sub>
- Step\_ $V_{ref\_margin\_low}$  = -0.033 × 512 (-3) = -16.9+3 = -13.9 = -14 (rounded to nearest integer

The module will support the margined high or low voltages using the OPERATION command. Bits [5:2] are used to enable margining as follows:

00XX: Margin Off

0101 : Margin Low (Act on Fault) 0110 : Margin Low (Act on Fault) 1001 : Margin High (Act on Fault) 1010 : Margin High (Act on Fault)

#### **PMBus Adjustable Overcurrent Warning**

The module can provide an overcurrent warning via the PMBus. The threshold for the overcurrent warning can be set using the parameter IOUT\_OC\_WARN\_LIMIT. This

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command uses the "Linear" data format with a two byte data word where the upper five bits [7:3] of the high byte represent the exponent and the remaining three bits of the high byte [2:0] and the eight bits in the low byte represent the mantissa. The exponent is fixed at –1 (decimal). The upper five bits of the mantissa are fixed at 0 while the lower six bits are programmable with a default value of 19A (decimal). The resolution of this warning limit is 500mA. The value of the IOUT\_OC\_WARN\_LIMIT can be stored to non-volatile memory using the STORE\_DEFAULT\_ALL command.

#### **Temperature Status via PMBus**

The module will provide information related to temperature of the module through the READ\_TEMPERATURE\_2 command. The command returns external temperature in degrees Celsius. This command will use the "Linear" data format with a two byte data word where the upper five bits [7:3] of the high byte will represent the exponent and the remaining three bits of the high byte [2:0] and the eight bits in the low byte will represent the mantissa. The exponent is fixed at 0 (decimal). The lower 11 bits are the result of the ADC conversion of the external temperature

# PMBus Adjustable Output Over, Under Voltage Protection and Power Good

The module has a common command to set the PGOOD, VOUT\_UNDER\_VOLTAGE(UV) and VOUT\_OVER\_VOLTAGE (OV) limits as a percentage of nominal. Refer to Table 6 of the next section for the available settings. The PMBus command VOUT\_OVER\_VOLTAGE (OV) is used to set the output over voltage threshold from two possible values: +12.5% or +16.67% of the commanded output voltage for each output.

The module provides a Power Good (PGOOD) for each output signal that is implemented with an open-drain output to indicate that the output voltage is within the regulation limits of the power module. The PGOOD signal is de-asserted to a low state if any condition such as overtemperature, overcurrent or loss of regulation occurs that would result in the output voltage going outside the specified thresholds. The PGOOD thresholds are user selectable via the PMBus (the default values are as shown in the Feature Specifications Section). Each threshold is set up symmetrically above and below the nominal value. The PGL (POWERGOODLOW) command will set the output voltage level above which PGOOD is asserted (lower threshold). The PGH(POWERGOODHIGH) command will set the level above which the PGOOD command is de-asserted. This command will also set two thresholds symmetrically placed around the nominal output voltage. Normally, the PGL threshold is set higher than the PGH threshold.

The PGOOD terminal can be connected through a pullup resistor (suggested value  $100 \mathrm{K}\Omega$ ) to a source of 5VDC or lower. The current through the PGood terminal should be limited to a max value of 5mA

### PMBus Adjustable Input Undervoltage Lockout

The module allows for adjustment of the input under voltage lockout and hysteresis. The command VIN\_ON allows setting the input voltage turn on threshold for each output, while the VIN\_OFF command will set the input voltage turn off

threshold. For the VIN\_ON command, possible values are 4.25V to 16V in variable steps. For the VIN\_OFF command, possible values are 4V to 15.75V in 0.5V steps. If other values are entered for either command, they is mapped to the closest of the allowed values.

Both the VIN\_ON and VIN\_OFF commands use the "Linear" format with two data bytes. The upper five bits will represent the exponent (fixed at -2) and the remaining 11 bits will represent the mantissa. For the mantissa, the four most significant bits are fixed at 0.

#### **Measurement of Output Current and Voltage**

The module is capable of measuring key module parameters such as output current and voltage for each output and providing this information through the PMBus interface.

#### **Measuring Output Current Using the PMBus**

The module measures current by using the inductor winding resistance as a current sense element. The inductor winding resistance is then the current gain factor used to scale the measured voltage into a current reading. This gain factor is the argument of the IOUT\_CAL\_GAIN command, and consists of two bytes in the linear data format. The exponent uses the upper five bits [7:3] of the high data byte in two-s complement format and is fixed at –15 (decimal). The remaining 11 bits in two's complement binary format represent the mantissa. During manufacture, each module is calibrated by measuring and storing the current gain factor into non-volatile storage.

The current measurement accuracy is also improved by each module being calibrated during manufacture with the offset in the current reading. The IOUT\_CAL\_OFFSET command is used to store and read the current offset. The argument for this command consists of two bytes composed of a 5-bit exponent (fixed at -4d) and a 11-bit mantissa. This command has a resolution of 62.5mA and a range of -4000mA to +3937.5mA.

The READ\_IOUT command provides module average output current information. This command only supports positive or current sourced from the module. If the converter is sinking current a reading of 0 is provided. The READ\_IOUT command returns two bytes of data in the linear data format. The exponent uses the upper five bits [7:3] of the high data byte in two-s complement format and is fixed at – 4 (decimal). The remaining 11 bits in two's complement binary format represent the mantissa with the 11<sup>th</sup> bit fixed at 0 since only positive numbers are considered valid.

### **Measuring Output Voltage Using the PMBus**

The module provides output voltage information using the READ\_VOUT command for each output. In this module the output voltage is sensed at the remote sense amplifier output pin so voltage drop to the load is not accounted for. The command will return two bytes of data all representing the mantissa while the exponent is fixed at -9 (decimal).

#### Reading the Status of the Module using the PMBus

GF Datasheet

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The module supports a number of status information commands implemented in PMBus. However, not all features are supported in these commands. A 1 in the bit position indicates the fault that is flagged.

STATUS BYTE: Returns one byte of information with a summary of the most critical device faults

Bit Position	Flag	Default Value
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

STATUS WORD: Returns two bytes of information with a summary of the module's fault/warning conditions.

#### Low Byte

Bit Position	Flag	Default Value
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

#### High Byte

Bit Position	Flag	Default Value
7	VOUT fault or warning	0
6	IOUT fault or warning	0
5	X	0
4	MFR	0
3	POWER_GOOD# (is negated)	0
2	X	0
1	X	0
0	X	0

STATUS\_VOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	VOUT OV Fault	0
6	X	0
5	X	0
4	VOUT UV Fault	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS\_IOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	IOUT OC Fault	0
6	X	0
5	IOUT OC Warning	0
4	X	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS\_TEMPERATURE: Returns one byte of information relating to the status of the module's temperature related

Bit Position	Flag	Default Value
7	OT Fault	0
6	OT Warning	0
5	X	0
4	X	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS\_CML: Returns one byte of information relating to the status of the module's communication related faults.

Bit Position	Flag	Default Value
7	Invalid/Unsupported Command	0
6	Invalid/Unsupported Command	0
5	Packet Error Check Failed	0
4	Memory Fault Detected	0
3	X	0
2	X	0
1	Other Communication Fault	0
0	X	0

MFR\_VIN\_MIN: Returns minimum input voltage as two data bytes of information in Linear format (upper five bits are exponent - fixed at -2, and lower 11 bits are mantissa in two's complement format – fixed at 12)

MFR VOUT MIN: Returns minimum output voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -10, and lower 11 bits are mantissa in two's complement format - fixed at 614)

MFR\_SPECIFIC\_00: Returns information related to the type of module and revision number. Bits [7:2] in the Low Byte indicate the module type (000011 corresponds to the UDXS1212 series of module), while bits [7:3] indicate the revision number of the module.

Low Byte

Bit Position	Flag	Default Value
7:2	Module Name	000011

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1:0	Reserved	10

### High Byte

Bit Position	Flag	Default Value
7:3	Module Revision Number	None
2:0	Reserved	000

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**Summary of Supported PMBus Commands**Please refer to the PMBus 1.1 specification for more details of these commands.

#### Table 6

Hex Code	Command		Brief Description									
			oility to configure, control and monitor each output by using only one physical ddress of the module									
		Format			1	Insigne	d Binar	V				
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r	r	r	r	r	r	r/w		
		Function	PA	X	X	X	X	X	X	PO		
		Default Value	0	X	X	X	X	X	X	0		
00	PAGE	PAGE Command Tr	uth Tab	le			ı	ı	1			
		PA PO			Log	gic Resi	ults					
		0 0		All Co	mmand	s addre	ss first	output				
		0 1		All Com	mands	addres	s secon	d outpu	ıt			
		1 0			legal in			•				
		1 1			nmands	_			S			
		Turn Module on or	off. Also	used to	o margir	the ou	tput vo	ltage				
		Format					d Binar					
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r	r/w	r/w	r/w	r/w	r	r		
		Function	On	Χ	ļ.,		rgin		X	X		
01	OPERATION	Default Value	0	0	0	0	0	0	Χ	X		
01	OI ENATION	Bit 7: 0 Output swit	ching d	isabled	اما							
		1 Output s Margin: 00XX Marg		g enab	iea							
		0101 Marg		Act on	fault)							
		0110 Marg										
		1001 Marg										
		1010 Marg										
		Configures the ON/	OFF fun	ctional	ity as a d	combin	ation of	analog	ON/OF	F pin		
		and PMBus commo	ınds									
		Format			l	Jnsigne	d Binar	У				
02	ON_OFF_CONFIG	Bit Position	7	6	5	4	3	2	1	0	YES	
02	01 <u>4_</u> 011_0014110	Access	r	r	r	r/w	r/w	r/w	r/w	r	123	
		Function	X 0	X	X	pu	cmd	cpr	pol	сра		
		Default Value	·	0	0	L	0	1	1	0		
		Refer to Page 19 fo										
03	CLEAR_FAULTS	Clear any fault bits if the device has be				t, also r	eleases	s the SM	IBALERI	# signal		
		Used to control wri										
		setting in the modu						e value	in the d	ata byte		
		into non-volatile me	emory (I	LEPRON								
		Format Dit Docition	7				d Binar		1 1			
		Bit Position	7	6	5	4	3	2	1	0		
		Access Function	r/w bit7	r/w bit6	r/w bit5	X	X	X	X	X		
		Default Value	0	0	0	X	X	X	X	X		
10	WRITE_PROTECT	Bit5: 0 – Enables all									YES	
	_	1 – Disables all						AGE OP	ERATION	٧		
		and ON_OF	F_CONF	FIG (bit	6 and bi	t7 must	be 0)					
		Bit 6: 0 – Enables al										
		1 – Disables al							and			
		OPERATION										
		Bit7: 0 – Enables all						Γ 00:	and.			
		1 – Disables all (bit5 and bit			ior the V	vKIIE_F	KUIEC	comm	iund			
-		(DIES GIIG DI	io must	nc ()								
		Stores all of the arm	ront cto	vrabla =	naictor o	ottings	in tha F		momer	v ac tha		
15	STORE_USER_ALL	Stores all of the cur new defaults on po		n uble f	egistei S	ettiilgs	iii ule E	LPRUIY	memor	y us the		
		Thew deliduits on po	wci up									
		L										

# $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules 4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

Hex Code	Command			Bri	ief Desc	ription					Non-Volatile Memory Storage	
16	RESTORE_USER_ALL											
		This command help module	os the h	ost syst					abilities	s of the		
		Format		•		Jnsigne						
		Bit Position	7	6	5	4	3	2	1	0		
19	CAPABILITY	Access Function	r PEC	r	r PD	r ALRT	r	r	r	r		
		Default Value	1	0	1 1	ALKI 1	0	0	rved 0	0		
		PEC – 1 Supported SPD -01 – max of 4 ALRT – 1 – SMBALE	00kHZ		1 1	1 1	0	<u> </u>	U			
		The module has MO		to Line	ar and E	xponen	t set to	-10. The	ese valu	ies		
		cannot be changed	1						1			
		Bit Position	7	6	5	4	3	2	1	0		
20	VOUT MODE	Access	r	r	r	r	r	r	r	r		
-		Function	_	Mode		1		Exponer				
		Default Value Mode: Value fixed of Exponent: Value fix	ed at 10	0111, Ex	ponent				is -9	1		
		Sets the value of in		age at v	which th	ie modu	le turn:	s on				
		Format						ent binar				
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function			Exponer				1antiss			
		Default Value	1	1	1	1	0	0	0	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
35	VIN_ON	Function Default Value	0	0	0	1	tissa 0	0	0	1	YES	
		Exponent -2 (dec), f Mantissa The upper four bits The lower seven ar corresponds to a d • 4.25, in • 9.5V to • 13V to 1	are fixe e progre efault o steps of 13V in i L6V in ir	ammab f 4.25V. f 0.25V u ncreme acremer	Allowab upto 9.5 ents of 0 ats of 10	ole value V. .5V	es are		:). This			
		Sets the value of in										
		Format		1	1							
		Bit Position	7	6	5	4	3	2	1	0		
		Access Function	r	r	r	r	r	r	r 1antiss	r		
		Default Value	1	1	Exponer 1	1 1	0	0	0	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	Ė				tissa			<del></del>		
		Default Value	0	0	0	0	1	0	0	0		
		Exponent -2 (dec), f	ixed									
36	VIN_OFF	Mantissa The upper four bits The lower seven ar corresponds to a d Allowable values ar 4.00, in 10.25V 12V 13.75V	are fixe e progre efault o re steps of to 11.75	ammab f 4.0V. f 0.25V u	upto 9.7 crement	5V. s of 0.5\		of 8(dec	:). This		YES	

# $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules 4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12AOutput Current

Hex Code	Command		Brief Description								
		Returns the value o	of the go	iin corre	ection te	rm use	d to cor	rect the	e measu	red	
		Format			inear, tv	vo's cor	mpleme	nt hina	rv		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r/w	
38	IOUT_CAL_GAIN	Function		[	xponen	it	•		Mantiss	o c	YES
		Default Value	1	0	0	0	1	0	0	V	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function Default Value		11.11	ariable b		tissa o factor	u calibr	ation		
		Returns the value of current	of the off							output	
		Format			inear, tv.						
		Bit Position	7	6	5	4	3	2	1	0	
70	IOUT CAL OFFCET	Access Function	r	r	r	r	r	r/w	r Mantiss	r	VEC
39	IOUT_CAL_OFFSET	Default Value	1	1	Exponen 1	0	0	V	V	V	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	<u> </u>		, .,		tissa	, .,	1 ., **		
		Default Value		V: Vo	ariable b			y calibr	ation		
		Cote the output sur	reurran								
		Sets the output ove	curren		evel in A inear, tv				rv		
		Bit Position	7	6	.iriear, tv	4	<u> 3</u>	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Function			xponen		<u>'</u>		Mantiss		
46	IOUT_OC_FAULT_LIMIT	Default Value	1	1	1	1	1	0	0	0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function		•	•	Man	tissa	•			
	Value maybe locked	Default Value	0	0	1	0	1	0	0	0	
		Determines module undervoltage (UV) f		in resp					MIT or a	VOUT	
		Format				Jnsigne					
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r/w	r/w	r/w	r	r	r	
		Function	X	Χ	RS [2]	RS [1]	RS [0]	Х	X	X	
47	IOUT_OC_FAULT_RESPONSE	Default Value	0	0	1	1	1	1	0	0	YES
									<u> </u>		
		RS[2:0] – Retry Sett 000 Unit do 111 Unit go Any other v	pes not opes thro	ugh no	rmal sof	t start o	continue	ously			
		Sets the output over	ercurren 7		ng level inear, tv		mpleme	ent bina 2	ry 1	0	
		Access	r	r	r	r	r	r	r	r	
/. ^	IOUT OC MARKI LINIT	Function			xponen	it			Mantiss	<u> </u>	
4A	IOUT_OC_WARN_LIMIT	Default Value	1	1	1	1	1	0	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	_				tissa	-	1 -		
	Value may be locked	Default Value	0	0	1	0	0	1	1	0	
		•									•

# $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules 4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

Hex Code	Command	Brief Description										Non-Volatile Memory Storage			
		Sets the overtempe	eratur	≏ fault le	evel in	ı °C									
		Format	ratar	c radic i			vo's con	nplemer	nt bin	arv			1		
		Bit Position	7	6	_	5	4	3	2		1	0			
		Access	r	r	1	r	r	r	r	ı	r	r			
<b>4.</b> F	OT SALUT LIMIT	Function			Ехро	ner	nt			Man	tissa				YES
4F	OT_FAULT_LIMIT	Default Value	0	0	(	0	0	0	0	(	)	0			YES
		Bit Position	7	6		5	4	3	2		l	0			
		Access	r/w	r/w	r/	/w	r/w	r/w	r/w	r/	w	r/w			
		Function					Mant								
	Value may be locked	Default Value	1	0	(	0	0	0	1	] ]	l	1			
		Sets the over tempor	eratur	e warn											
		Format					wo's com			_		_			
		Bit Position	7	6		5	4	3	2	_	l	0			
		Access	r	r	_ !	r	r	r	r	1		r			
51	OT LUADAL LIMIT	Function	_		Expo			0	^	Man		^			YES
	OT_WARN_LIMIT	Default Value Bit Position	7	6		0 5	0 4	3	2	_	)	0			
		Access	r/w			о /w	r/w	r/w	r/w	r/	1	r/w			
		Function	I/W	1/W	17	W	Mant		I/W	17	W	I/W			
	Value may be locked	Default Value	0	1		1	1	1	1		)	1			
		<u> </u>									,				
		Sets the rise time of Supported Values –							Value	of O	inctr	icto i in	nit to		
		bring its output to p	· v.o, t	ımmed	1.0, Z. Value	1,4.	. 2, 0.0, 9. mickly a	omsec. s naccih	vuiut de	: 01 0	ii iSti U	เบเร นใ	iit tO		
		Format	, ogic	EU			vo's con			arv					
		Bit Position	7	6	_	5	4	3	2		l I	0			
		Access	r	r		r	r	r	r			r/w			
61	TON_RISE	Function		- 1	Expo					Man					YES
		Default Value	1	1		1	0	0	0	(	)	0			
		Bit Position	7	6	Ĺ	5	4	3	2	1	l	0			
		Access	r/w	r/w	r/	/w	r/w	r/w	r/w	r/	W	r/w			
		Function					Mant	issa							
		Default Value	0	1		1	0	0	0	(		0			
		Returns one byte of	f infor	mation	with c					itical	modu	ıle fau	ılts		
		Format			<u> </u>		Unsigned			1	<del></del>				
		Bit Position	7	6	_	5	4	3	2	_	l	0			
78	STATUS_BYTE	Access	r	r		r	r	r	r	1		r None			
		Flag	Х	OFF				VIN_U	TEM	CN		of the			
					_(	VC	OC	V				bove			
		Default Value	0	0		0	0	0	0	(		0			
		Returns two bytes of	ot info	rmatior	n with	a sı	ummary	of the r	nodu	ie's fa	ult/w	arning	9		
		conditions Format						Uncian	od Di	nary					
		Bit Position		7	6		5	Unsign 4			2		1		
					r		r	r	_	3 r		-		$\vdash$	
		Access	-+	r	IOUT	·/p	1		+-		r	-	r	H	
		Flag		VOUT	0U		Χ	MFR	PG	OOD	Χ		Χ		
79	STATUS_WORD	Default Value		0	0		0	0		0	0		0		
		Bit Position		7	6		5	4		3	2		1		
		Access		r	r		r	r		r	r		r		
							VOUT	IOUT_C						No	
		Flag		Χ	OFF		OV _	C	VIN	I_UV	TEM	IP	CML	1	
		Default Value		0	X	$\dashv$	0	0	-	0	0		0	al	
														Н	
		Returns one byte of	f infor	mation	with t	he s	status of	the mo	dule's	outp	ut vol	ltage ı	related	ł	
		faults					Ingigue	d Dinam	,				Ì		
7^	CTATUS VOUT	Format Bit Position		7	6		Unsigned		3	2	1	0			
7A	STATUS_VOUT	Access		r	r	5 r	_	4 r	r	2 r	r	0 r			
		Flag	\/\I	JT_OV	X	\ \		IT_UV	Х	Х	Х	X			
		Default Value	VOI	0	0	0		0	0	0	0	0			
							<u> </u>	·	~	~	<u> </u>	<u> </u>			

# $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules 4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12AOutput Current

Hex Code	Command				B	Brief De	scripti	on						Non-Volatile Memory Storage
			eturns one byte of information with the status of the module's output current related											
		faults Format					Unsig	ned	Binary	/				
7B	STATUS_IOUT	Bit Position Access		7 r		6 r		5 r		- 4	+ 3 - r		1 0 r r	
		Flag	IOU	T_OC	Fault	Х	IOUT C	C W	/arnin	g >	X Χ	Х	XX	
		Default Value	6: 6	0	**1	0		0		(			0 0	
		Returns one byte of faults	of infor	matic	on with					e's ter	nperatu	ıre rel	ated	
7D	STATUS_TEMPERATURE	Format Bit Position		7		Un 6	signed 5			3 2	1	0		
70	STATOS_TEMPERATORE	Access		r		r	r		r	r r	r	r		
		Flag Default Value	OT_	FAUL 0	_T O	T_WAR 0	N X	_		\ \ \ \		X 0		
		Returns one byte	of infor	matic	on with	the sta	itus of 1	the r	modul	e's co	mmunio	cation	related	
		faults Format					Insigne	d Ri	narv					
		Bit Position	7		6	5	4	a Di	3	2	1		0	
7E	STATUS_CML	Access	r		r	r	r Memo	)ru	r	r	r Othe	ır	r	
		Flag	Invo Comm			d PEC ı Fail	faul	ť	Х	Χ	Comr	m	X	
		Default Value	0		0	0	detect 0	.ea	0	0	Faul 0	t	0	
		Returns one byte	of infor	matio	on with					e spe	cific fau	lts or	warning	
		Format Bit Position	7	6	I - I	Unsig	ned Bir 3		1	l	^			
		Access	r	r	5 r	r	r	2 r	r		0 R	<u> </u> 		
80	STATUS_MFR_SPECIFIC	Flag	OTFI	×	Х	IVADDF	R X	Х	Х	TWC	PH_EN			
		Default Value	0	0	0	0	0	0	0		0			
		OTFI – Internal Ter IVADDR – PMBUs o TWOPH_EN – Mod	address	s is no	ot valid	l	Shutdo	own	thres	nold				
		Returns the value	of the	outpu	ıt volta	ige of th	ne mod	ule.	Ехроі	nent is	s fixed a	ıt -9.		
		Format			Line	ear, two	's com	pler	nent b	inary				
		Bit Position Access	7 r	_	6 r	5 r	4 r	3 r		<u>2</u>	1 r	0 r		
8B	READ_VOUT	Function			Λ I	Λ I	Manti			\ T	Λ I	^		
		Default Value Bit Position	7		6	5	4	3		2	1	0		
		Access	r		r	r	r	r		r	r	r		
		Function Default Value	0		0	0	Manti 0	ssa 0	(	)	0	0		
		Returns the value	of the	outpu	ıt curre	ent of th	ne mod	ule						
		Format			Line	ear, two	's com	plen	_		4			
		Bit Position Access	7 r	_	6 r	5 r	4 r	3 R	_	2	1 r	0 r		
		Function			Exp	onent				Мс	ıntissa			
8C	READ_IOUT	Default Value Bit Position	7		6	5	0	3	١	2	V 1	V 0		
		Access	r		r	r	r	r		- -	r	r		
		Function Default Value	V		V	V	Manti V	ssa V	١	/	v T	0		
		V - Variable	ı v		, l	•	*	•		·	•	,		

# $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules 4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

### Table 6 (Continued)

Code	Command				Brief D	escript	ion					Non-Volatile Memory Storage
		Returns the value o	f the ex	ternal t	empera	ture in o	degree (	Celsius				, j
		Format		l	inear, tu	vo's cor	npleme	nt bina	ry			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	R	r	r	r		
		Function			Exponer	it			Mantiss	מ		
8E	READ TEMPERATURE 2	Default Value	0	0	0	0	0	V	V	V		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function	•		<u> </u>	Man			<u> </u>	·		
		Default Value	V	V	V	V	V	V	V	0		
		V - Variable	•	· ·	· ·	•	_ •	· ·	· ·	U		
		v variable										
		Returns one byte in	dicatino	the m	odule is	compli	ant to P	MBus S	pec. 1.1	(read or	nly)	
		Format				Jnsigne					'	
98	PMBUS REVISION	Bit Position	7	6	5	4	3	2	1	0		
30	111865_112181614	Access	r	r	r	r	r	r	r	r		
		Default Value	0	0	0	1	0	0	0	1		
		Delaut Value	O		Ů	_	U		·	_		
		Returns module na	me info	rmatior	1							
		Format				Jnsigne	d Binar	V				
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function	-	'	'	Rese		'	'			
D0	MFR_SPECIFIC_00	Default Value	0	0	0	0	0	0	0	0		YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access		r	r	r	r			r		
		Function	r				<u> </u>	r	Page			
		Default Value	0	0		Name	1	1		rved		
ļ					0	0	1	1	1	0		
		Applies a fixed offse										
		steps. Permissible v					and +6	0mV. Tr	ne offset	is calcu	ulated	
		as VREF_TRIMx2-9. E	xponer									
		Format			inear, tu							
		Bit Position	7	6	5	4	3	2	1	0		
D4	VREF TRIM	Access	r/w	r	r	r	r	r	r	r		YES
D4	VIVEI _ I I VII I	Function				Man	tissa					TLS
		Default Value	V	V	V	V	V	V	V	V		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Man	tissa					
		Default Value	>	V	V	>	>	V	V	V		
		Applies a fixed offse	at to the	refere	nce volt	امم ۸ط	iistmer	nt ic ∩0/-	to _ 100.	6 in 2m1	/ ctons	
		Permissible values									sieps.	
		(STEP_VREF_MARGI									nut	
		voltage includes VR								ivet out	put	
		Format			inear, tu							
		Bit Position	7	6	5 5	4	3	2	1	0		
D.	CTED VIDEE MARCINI LIICU	Access	r	r	r	r	r	r	r	r		VEC
D5	STEP_VREF_MARGIN_HIGH	Function	- 1		_ '	Man			_ '	'		YES
			V	V	V	V		V	V	V		
		Default Value					7					
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r/w	r/w	r/w	r/w	r/w		
		Function				Man						
		Default Value	V	V	V	V	V	V	V	V	<u> </u>	

# $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules 4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12AOutput Current

### Table 6 (Continued)

Hex Code	Command	Brief Description								Non-Volatile Memory Storage					
	STEP_VREF_MARGIN_LOW	Applies a fixed negative offset to the reference voltage. Adjustment is -20% to 0% in 2mV steps. Permissible values range between -120mV and 0mV). The offset is calculated as (STEP_VREF_MARGIN_LOW + VREF_TRIM)x2-9.Exponent fixed at -9(dec). Net output voltage includes VREF_TRIM adjustment and ranges from -30% to 10%													
D6		Format				Line	ar, tv	vo's co	mplem	ent bin	ary				
		Bit Posit	tion	7	6		5	4	3	2	1	0			
		Acces	s	r	r		r	r	r	r	r	r		YES	
		Function			Mantissa										
		Default V	alue/	V	V		V	V	V	V	V	V	1		
		Bit Posit	tion	7	6		5	4	3	2	1	0			
		Acces	s	r	r	r	/w	r/w	r/w	r/w	r/w	r/w			
		Function					Mantissa			•	•	1			
		Default V		V	V		V	V	V	V	V	V	1		
		Sinale comm	nand to	set PGC	OD. \	/OUT	UND	ER VO	LTAGE	UV) and		1			
	PCT_VOUT_FAULT_PG_LIMIT	Single command to set PGOOD, VOUT_UNDER_VOLTAGE(UV) and VOUT_OVER_VOLTAGE(OV) limits as percentage of nominal													
		Form		Unsigned Bingry											
		Bit Position		7	1		_	-			2	1			
				7		6	5		4	3	2	1	0		
		Acce	SS	r		r	r		r	r	r	r/w	r/w		
		Function		×		X	×	1	x	X	Х	PCT_ MSB	PCT_ LSB		
5.7		Default	Value	0		Х	×	,	Χ	Χ	Х	X	0		
D7		PAGE Comm		Ŭ		^^	,	١	^	^	^		U		
						_									
		PCT_M	PCT_LS	UV	(%)	PG		PG		PGH	PGH		/ (%)		
		SB	В			LO (%		HIG (%		HIGH (%)	LOW (%)				
						19	01	(%	01	(%)	(%)				
		0	0	-16	.67	-12	2.5	-8.3	33	12.5	8.33	16	5.67		
		0	1	-12	2.5	-8.	33	-4.1	17	8.33	4.17	1	2.5		
		1	0	-29	.17	-20	.83	-16.	67	8.33	4.17	1	2.5		
		1	1	-41.67		-37.5		-33.	-33.33 8.33		4.17	1	2.5		
	SEQUENCE_TON_TOFF_DELAY	Used to set delay to turn-on or turn-off modules as a ratio of TON_RISE. Values can range							an range						
		from 0 to 7 and are a multiple of TON_RISE TIME						arrunge							
		Format		a manup	Unsigned Binary										
D8		Bit Position		7	6		5	4	3	2	1	0			
סט		Access		r/w	r/w		/w	r	r/w	r/w	r/w	r	1		
		Function		TON DE			, ,,		TOFF D				1		
		Default Value		0	0_0		0	0	0	011_0	0	0	1		
<u> </u>		Delauit value		U	U		U	U	U	U	U	U			

# 2 × 12A Digital Dual MicroDlynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

#### **Thermal Considerations**

Power modules operate in a variety of thermal environments; however, sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 49. The preferred airflow direction for the module is in Figure 50.

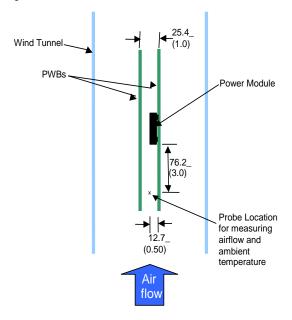


Figure 49. Thermal Test Setup.

The thermal reference points,  $T_{ref}$  used in the specifications are also shown in Figure 50. For reliable operation the

temperatures at these points should not exceed 135°C. The output power of the module should not exceed the rated power of the module (Vo,set x Io,max).

Please refer to the Application Note "Thermal Characterization Process For Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.

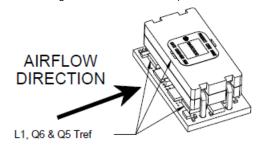


Figure 50. Preferred airflow direction and location of hotspot of the module (Tref).

## 2 × 12A Digital Dual MicroDlynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 x 12AOutput Current

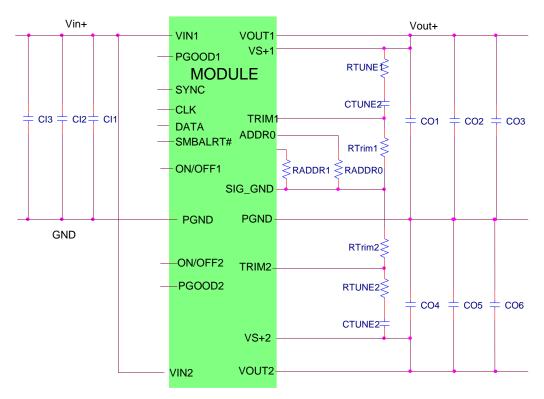
## **Example Application Circuit**

#### **Requirements:**

Vin: 12V Vout: 1.8V

lout:  $2 \times 9A$  max., worst case load transient is from 6A to 9A  $\Delta$ Vout: 1.5% of Vout (27mV) for worst case load transient

Vin, ripple 1.5% of Vin (180mV, p-p)



CI1 Decoupling cap -  $4\times0.1\mu$ F/16V, 0402 size ceramic capacitor
CI2  $4\times22\mu$ F/16V ceramic capacitor (e.g. Murata GRM32ER61C226KE20)

CI3 470µF/16V bulk electrolytic

CO1 Decoupling cap -  $2\times0.1\mu$ F/16V, 0402 size ceramic capacitor

CO2  $3 \times 47 \mu F/6.3 V$  ceramic capacitor (e.g. Murata GRM31CR60J476ME19)

CO3  $1 \times 330 \mu F/6.3 \text{V}$  Polymer (e.g. Sanyo Poscap)

CO4 Decoupling cap -  $2\times0.1\mu\text{F}/16\text{V}$ , 0402 size ceramic capacitor

CO5  $3 \times 47 \mu F/6.3 \text{V}$  ceramic capacitor (e.g. Murata GRM31CR60J476ME19)

CO6  $1 \times 330 \mu F/6.3 V$  Polymer (e.g. Sanyo Poscap)

CTune1 1200pF ceramic capacitor (can be 1206, 0805 or 0603 size)
RTune1 300 ohms SMT resistor (can be 1206, 0805 or 0603 size)

RTrim1  $10k\Omega$  SMT resistor (can be 1206, 0805 or 0603 size, recommended tolerance of 0.1%)

CTune2 1200pF ceramic capacitor (can be 1206, 0805 or 0603 size)
RTune2 300 ohms SMT resistor (can be 1206, 0805 or 0603 size)

RTrim2  $10k\Omega$  SMT resistor (can be 1206, 0805 or 0603 size, recommended tolerance of 0.1%)

<u>Note:</u> The DATA, CLK and SMBALRT pins do not have any pull-up resistors inside the module. Typically, the SMBus master controller will have the pull-up resistors as well as provide the driving source for these signals.

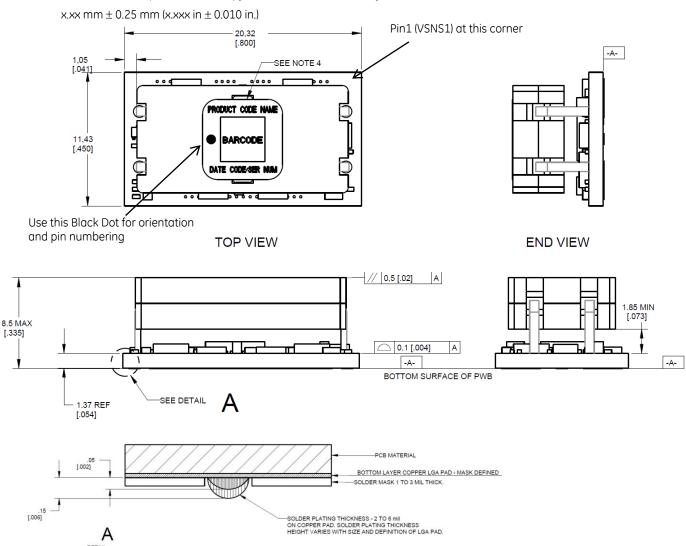
# $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

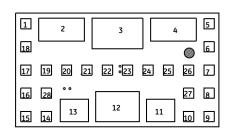
4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

#### **Mechanical Outline**

Dimensions are in millimeters and (inches).

Tolerances: x.x mm  $\pm$  0.5 mm (x.xx in.  $\pm$  0.02 in.) [unless otherwise indicated]





**BOTTOM VIEW** 

PIN	FUNCTION	PIN	FUNCTION
1	VSNS1	15	ADDR1
2	VOUT1	16	TRIM1
3	PGND	17	SIG_GND
4	VOUT2	18	TRIM2
5	VSNS2	19	SYNC
6	SMBALERT#	20	PGND
7	DATA	21	PGND
8	CLK	22	PGND
9	ENABLE1	23	PGND
10	ENABLE2	24	PGND
11	VIN	25	PGND
12	PGND	26	PGND
13	VIN	27	PGOOD2
14	ADDRO	28	PGOOD1

# $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

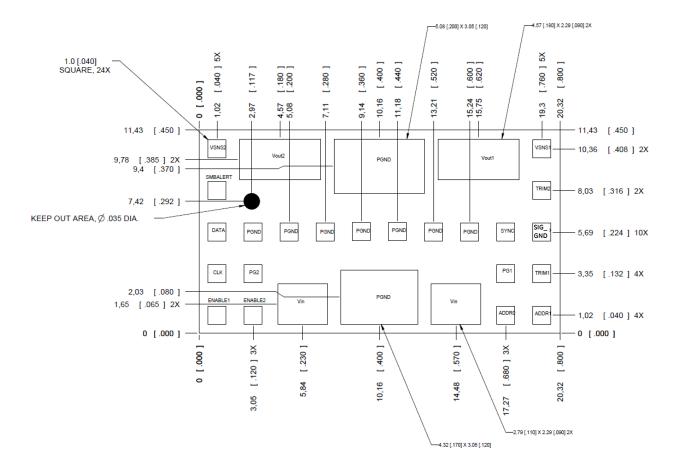
4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12AOutput Current

## **Recommended Pad Layout**

Dimensions are in millimeters and (inches).

Tolerances: x.x mm  $\pm$  0.5 mm (x.xx in.  $\pm$  0.02 in.) [unless otherwise indicated]

x.xx mm  $\pm$  0.25 mm (x.xxx in  $\pm$  0.010 in.)



PIN	FUNCTION	PIN	FUNCTION		
1	VSNS1	15	ADDR1		
2	VOUT1	16	TRIM1		
3	PGND	17	SIG_GND		
4	VOUT2	18	TRIM2		
5	VSNS2	19	SYNC		
6	SMBALERT#	20	PGND		
7	DATA	21	PGND		
8	CLK	22	PGND		
9	ENABLE1	23	PGND		
10	ENABLE2	24	PGND		
11	VIN	25	PGND		
12	PGND	26	PGND		
13	VIN	27	PGOOD2		
14	ADDRO	28	PGOOD1		

# $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

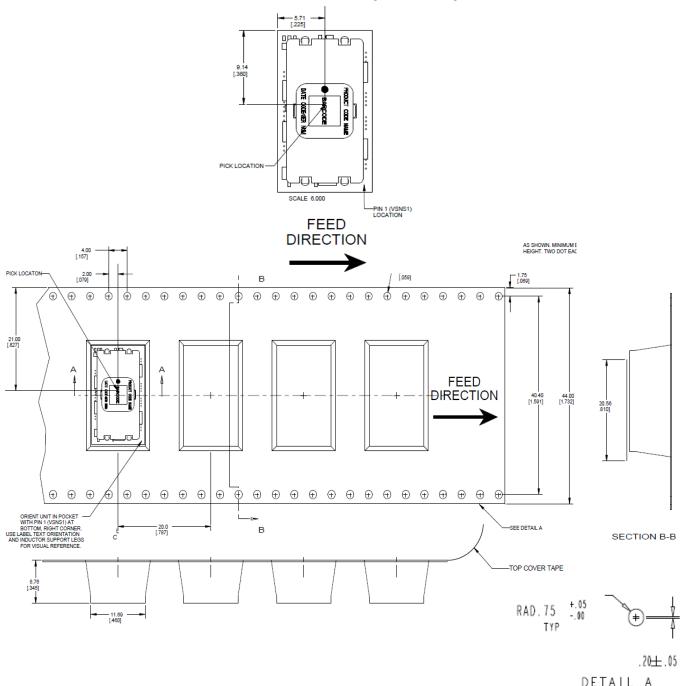
4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

## **Packaging Details**

The 12V Digital Dual MicroDlynx $^{TM}$ 2 × 12A modules are supplied in tape & reel as standard. Modules are shipped in quantities of 200 modules per reel.

All Dimensions are in millimeters and (in inches).

Black Dot on the label is the orientation marker for locating Pin 1 (bottom right corner)



Reel Dimensions:

 Outside Dimensions:
 330.2 mm (13.00)

 Inside Dimensions:
 177.8 mm (7.00")

 Tape Width:
 44.00 mm (1.732")

# $2 \times 12$ A Digital Dual MicroDlynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 x 12AOutput Current

#### **Surface Mount Information**

#### Pick and Place

The2 × 12A Digital Dual MicroDlynx<sup>™</sup> modules use an open frame construction and are designed for a fully automated assembly process. The modules are fitted with a label designed to provide a large surface area for pick and place operations. The label meets all the requirements for surface mount processing, as well as safety standards, and is able to withstand reflow temperatures of up to 300°C. The label also carries product information such as product code, serial number and the location of manufacture.

#### **Nozzle Recommendations**

The module weight has been kept to a minimum by using open frame construction. Variables such as nozzle size, tip style, vacuum pressure and placement speed should be considered to optimize this process. The minimum recommended inside nozzle diameter for reliable operation is 3mm. The maximum nozzle outer diameter, which will safely fit within the allowable component spacing, is 7 mm.

#### **Bottom Side / First Side Assembly**

This module is not recommended for assembly on the bottom side of a customer board. If such an assembly is attempted, components may fall off the module during the second reflow process.

#### **Lead Free Soldering**

The modules are lead-free (Pb-free) and RoHS compliant and fully compatible in a Pb-free soldering process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect long-term reliability.

#### **Pb-free Reflow Profile**

Power Systems will comply with J-STD-020 Rev. D (Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices) for both Pb-free solder profiles and MSL classification procedures. This standard provides a recommended forced-air-convection reflow profile based on the volume and thickness of the package (table 4-2). The suggested Pb-free solder paste is Sn/Ag/Cu (SAC). The recommended linear reflow profile using Sn/Ag/Cu solder is shown in Fig. 50. Soldering outside of the recommended profile requires testing to verify results and performance.

#### **MSL Rating**

The 2 x 12A Digital Dual MicroDlynx  $^{\text{TM}}$  modules have a MSL rating of 3

#### Storage and Handling

The recommended storage environment and handling procedures for moisture-sensitive surface mount packages is detailed in J-STD-033 Rev. A (Handling, Packing, Shipping and Use of Moisture/Reflow Sensitive Surface Mount Devices). Moisture barrier bags (MBB) with desiccant are

required for MSL ratings of 2 or greater. These sealed packages should not be broken until time of use. Once the original package is broken, the floor life of the product at conditions of  $\leq$  30°C and 60% relative humidity varies according to the MSL rating (see J-STD-033A). The shelf life for dry packed SMT packages will be a minimum of 12 months from the bag seal date, when stored at the following conditions: < 40° C, < 90% relative humidity.

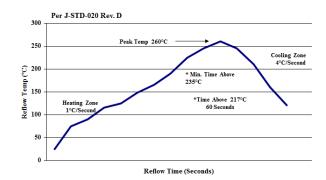


Figure 51. Recommended linear reflow profile using Sn/Ag/Cu solder.

#### **Post Solder Cleaning and Drying Considerations**

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to Board Mounted Power Modules: Soldering and Cleaning Application Note (AN04-001).

## 2 × 12A Digital Dual MicroDlynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

#### **Ordering Information**

Please contact your GE Sales Representative for pricing, availability and optional features.

#### **Table 9. Device Codes**

Device Code	Input Voltage Range	Output Voltage	Output Current	On/Off Logic	Sequencing	Comcodes	
UDXS1212A0X3-SRZ	4.5 – 14.4Vdc	0.51 – 5.5 Vdc	12Ax2	Negative	No	150026732	
UDXS1212A0X43-SRZ	4.5 – 14.4Vdc	0.51 – 5.5 Vdc	12Ax2	Positive	No	150033761	

#### Table 10. Coding Scheme

Package Identifier	Family	Sequencing Option	Input Voltage	Output current	Output voltage	On/Off logic	Remote Sense	Options	ROHS Compliance
U	D	X	S	1212A0	X		3	-SR	Z
P=Pico U=Micro M=Mega	D=Dlynx Digital V = DLynx	T=with EZ Sequence X=without	Special: 4.5 – 14V	2 × 12A	X = programm able output	4 = positive No entry	3 = Remote Sense	S = Surface Mount R = Tape &	Z = ROHS6
G=Giga	Analog.	sequencing				= negative		Reel	

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