

### **General Description**

The MAX1774 is a complete power-supply solution for

PDAs and other hand-held devices. It integrates two

high-efficiency step-down converters, a boost converter for backup battery regulation, and four voltage detec-

The MAX1774 accepts inputs from +2.7V to +28V and

provides an adjustable main output from 1.25V to 5.5V at over 2A. The secondary core converter delivers an

adjustable voltage from 1V to 5V and can deliver up to

1.5A. Both the main and core regulators have separate

When the AC adapter power is removed, an external P-

channel MOSFET switches input to the main battery. When the main battery is low, the backup step-up con-

verter sustains the main output voltage. When the back-

up battery can no longer deliver the required load, the

system shuts down safely to prevent damage. Four on-

board voltage detectors monitor the status of the AC adapter power, main battery, and backup battery.

The MAX1774 evaluation kit is available to help reduce

tors in a small 32-pin QFN or 28-pin QSOP package.

Features

- Dual, High-Efficiency, Synchronous-Rectified **Step-Down Converters**
- Thin, Small (1mm High) QFN Package
- Step-Up Converter for Backup Battery
- Main Power Adjustable from +1.25V to +5.5V **Over 2A Load Current** Up to 95% Efficiency
- Core Power Adjustable from 1V to 5V **Internal Switches** Up to 1.5A Load Current
- Automatic Main Battery Switchover
- 100% (max) Duty Cycle
- Up to 1.25MHz Switching Frequency
- Input Voltage Range from +2.7V to +28V
- Four Low-Voltage Detectors
- 170µA Quiescent Current
- 8µA Shutdown Current
- Digital Soft-Start
- Independent Shutdown Inputs

### **Ordering Information**

PART	TEMP RANGE	PIN-PACKAGE
MAX1774EEI	-40°C to +85°C	28 QSOP
MAX1774EGJ	-40°C to +85°C	32 7mm x 7mm QFN

### **Functional Diagram**



Pin Configurations continued at end of data sheet.



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Maxim Integrated Products 1

**MAX1774** 

For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642. or visit Maxim's website at www.maxim-ic.com.

**Applications** 

PDAs Internet Access Tablets **POS** Terminals Subnotebooks

Hand-Held Computers

shutdown inputs.

design time.

### **Pin Configurations**

Up to 91% Efficiency

### **ABSOLUTE MAXIMUM RATINGS**

IN, SHDNM, MDRV, DBI, LBI, ACI,

CVH to GND	0.3V to +30V
IN to CVH, PDRV	0.3V to +6V
BIN to CS	0.3V to +6V
LXB to GND	-0.3V to (VBIN+ 0.7V)
PDRV to GND	$(V_{CVH} - 0.3V)$ to $(V_{IN} + 0.3V)$
All Other Pins to GND	0.3V to +6V

PGND to GND0.3V to +0.3V
Continuous Power Dissipation
28-Pin QSOP (derate 10.8mW/°C above +70°C)860mW
32-Pin QFN (derate 23.2mW/°C above +70°C)1860mW
Operating Temperature Range40°C to +85°C
Storage Temperature Range65°C to +150°C
Temperature (soldering, 10s)+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### **ELECTRICAL CHARACTERISTICS**

(Figure 1,  $V_{INS} = V_{INS} + 12V$ ,  $V_{INC} = V_{CS-} = V_{CS+} = +3.3V$ ,  $V_{CORE} = +1.8V$ ,  $T_A = 0^{\circ}C$  to +85°C, unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS
Input Voltage	VIN		2.7		28	V
Input Quiescent Supply Current	l <sub>IN</sub>	$V_{FBM} = +1.5V, V_{FBC} = +1.5V, V_{\overline{SHDNM}} = V_{\overline{SHDNC}} = +3.3V$		18	40	μA
CS- Quiescent Supply Current	ICS-	$V_{FBM} = +1.5V, V_{FBC} = +1.5V, V_{\overline{SHDNM}} = V_{\overline{SHDNC}} = +3.3V$		110	220	μA
Core Regulator Quiescent Supply Current	IINC	$V_{FBM} = +1.5V$ , $V_{FBC} = +1.5V$ , $V_{\overline{SHDNM}} = V \overline{SHDNC} = +3.3V$		60	105	μA
Backup Mode BIN Quiescent Supply Current	I <sub>BIN</sub>	$V_{BIN} = +3.3V, CS- open$ $V_{FBM} = +1.5V, V_{\overline{SHDNM}} = +3.3V,$ $V_{\overline{BKOFF}} = +1.5V, \overline{SHDNC} = GND$		60	105	μA
IN Shutdown Supply Current		$\overline{\text{SHDNM}} = \overline{\text{SHDNC}} = \text{GND}$		8	40	μA
MAIN REGULATOR						
Main Output Voltage Adjust Range			1.25		5.5	V
FBM Regulation Threshold	VFBM	$V_{(CS+ - CS-)} = 0$ to +60mV, $V_{IN} = +3.5V$ to +28V	1.21	1.25	1.29	V
FBM Input Current	IFBM	V <sub>FBM</sub> = +1.3V	-0.1		0.1	μA
Current-Limit Threshold		V <sub>CS+</sub> - V <sub>CS-</sub>	60	80	100	mV
Minimum Current-Limit Threshold		V <sub>CS+</sub> - V <sub>CS-</sub>	5	15	25	mV
Valley Current Threshold		V <sub>CS+</sub> - V <sub>CS-</sub>	40	50	60	mV
Zero Current Threshold		V <sub>CS+</sub> - V <sub>CS-</sub>	0	5	15	mV
PDRV, NDRV Gate Drive Resistance		V <sub>CS-</sub> = +3.3V, I <sub>PDRV</sub> , I <sub>NDRV</sub> = 50mA		2	5.5	Ω
CS- to CVL Switch Resistance		I <sub>CVL</sub> = 50mA		4.5	9.5	Ω
PDRV, NDRV Dead Time				50		ns

### **ELECTRICAL CHARACTERISTICS (continued)**

(Figure 1,  $V_{INS} = V_{INS} = +12V$ ,  $V_{INC} = V_{CS-} = V_{CS+} = +3.3V$ ,  $V_{CORE} = +1.8V$ ,  $T_A = 0^{\circ}C$  to +85°C, unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS
Maximum Duty Cycle			100			%
Minimum On-Time			200	400	650	ns
Minimum Off-Time			200	400	650	ns
CORE REGULATOR						
Input Voltage Range	VINC		2.6		5.5	V
		V <sub>INC</sub> rising	2.40	2.47	2.55	V
INC Undervoltage Lockout		V <sub>INC</sub> falling	2.30	2.37	2.45	v
Core Output Voltage Adjust Range			1.0		5.0	V
Maximum Core Load Current		V <sub>CORE</sub> = 1.8V (Note 1)	1	1.5		А
FBC Regulation Threshold	VFBC	V <sub>INC</sub> = +2.5 to +5.5V, I <sub>OUTC</sub> = 0 to 200mA	0.97	1.0	1.03	V
FBC Input Current	IFBC	$V_{FBC} = +1.3V$	-0.1		0.1	μΑ
Dropout Voltage		I <sub>OUTC</sub> = 400mA		0.1	0.25	V
LXC Leakage Current	I <sub>LXC</sub>	$V_{INC} = +5.5V, V_{LXC} = 0 \text{ to } +5.5V$	-10		10	μΑ
LXC P-Channel, N-Channel On- Resistance				0.25	0.5	Ω
LXC P-Channel Current Limit	ICLC		1200	1800	3000	mA
LXC P-Channel Minimum Current			100	250	400	mA
LXC N-Channel Valley Current			900	1400	2400	mA
LXC N-Channel Zero-Crossing Current			40	110	170	mA
LXC Dead Time				50		ns
Max Duty Cycle			100			%
Minimum On-Time			170	400	690	ns
Minimum Off-Time			170	400	690	ns
BACKUP REGULATOR						
Backup Battery Input Voltage	VBBATT		0.9		5.5	V
LXB N-Channel On-Resistance		$V_{CS-} = +3.3V, I_{LXB} = 50mA$		1.9	3.5	Ω
LXB Current Limit			200	350	600	mA
LXB Leakage Current		$V_{LXB} = +5.5V, V_{FBM} = +1.3V$			1	μΑ
BIN Leakage Current IBIN		$V_{BIN} = +5.5V, CS = \overline{BKOFF} =$ SHDNC = SHDNM = GND			1	μΑ
BIN, CS- Switch Resistance		$V_{CS-} = +3.3V, \overline{BKOFF} = GND, \overline{SHDNM} = CVL$		7.5	15	Ω
BIN Switch Zero-Crossing Threshold		$V_{BIN} = +2.5V, \overline{BKOFF} = \overline{SHDNC} = \overline{SHDNM} = CVL$		17	35	mV
LXB Maximum On-Time			2.8	5.6	9.2	μs
Zero Crossing Detector Timeout				40		μS



### **ELECTRICAL CHARACTERISTICS (continued)**

(Figure 1,  $V_{IN} = V_{INS} = +12V$ ,  $V_{INC} = V_{CS-} = V_{CS+} = +3.3V$ ,  $V_{CORE} = +1.8V$ ,  $T_A = 0^{\circ}C$  to +85°C, unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
REFERENCE	•		•			•
Reference Voltage	VREF		1.23	1.25	1.27	V
Reference Load Regulation		$I_{REF} = 0$ to $50\mu A$			10	mV
Reference Line Regulation		V <sub>CS-</sub> = +2.5V to +5.5V, I <sub>REF</sub> = 50µA			5	mV
Reference Sink Current			10			μA
CVL, CVH REGULATORS						
	Vou	$I_{CVL} = 50 \text{mA}, V_{CS-} = 0$	2.6	2.8	3.1	V
CVL Output Voltage	VCVL	$I_{CVL} = 50 \text{mA}, V_{CS-} = +3.3 \text{V}$		3.2		v
CVL Switchover Threshold		CS- rising, hysteresis = 100mV typical	2.40	2.47	2.55	V
CVH Output Voltage		$V_{IN} = +4V$ , $I_{CVH} = 25mA$		V <sub>IN</sub> - 3.4	V <sub>IN</sub> - 2.8	V
	Vсvн	V <sub>IN</sub> = +12V, I <sub>CVH</sub> = 50mA		V <sub>IN</sub> - 4.2	V <sub>IN</sub> - 3.7	V
CVH Switchover Threshold	VIN	V <sub>IN</sub> rising, hysteresis = 350mV typ		5.5		V
		V <sub>CVL</sub> rising	2.40	2.47	2.55	N/
CVL Undervoltage Lockout		V <sub>CVL</sub> falling	2.30	2.37	2.45	5 V
LOW-VOLTAGE COMPARATOR	S					
Backup Regulator Shutdown	\/	VBKOFF rising	0.51	0.55	0.59	
Threshold	VBKOFF	VBKOFF falling	0.46	0.50	0.54	- V
BKOFF Input Bias Current		$V_{\overline{BKOFF}} = +5.5V$			1	μA
LBI Threshold	V <sub>LBI</sub>	V <sub>LBI</sub> falling, hysteresis = 50mV typical	1.17	1.20	1.23	V
DBI Threshold	V <sub>DBI</sub>	V <sub>DBI</sub> falling, hysteresis = 50mV typical	1.17	1.20	1.23	V
BKUP Low-Input Threshold			0.4			V
LBI, DBI Input Leakage Current		$V_{LBI} = V_{DBI} = +1.3V$			100	nA
LBO, BKUP, ACO, MDRV Output Low		I <sub>SINK</sub> = 1mA			0.4	V
LBO, BKUP, ACO, MDRV Output Leakage Current		$V_{LBI} = +1.3V$ , $V_{ACI} = +12V$ , $V_{\overline{ACO}} = V_{\overline{LBO}} = V_{\overline{BKUP}} = +5.5V$ , $V_{\overline{MDRV}} = +28V$			1.0	μA
ACI Threshold		V <sub>ACI</sub> – V <sub>INS,</sub> ACI falling		0.22	0.35	V
ACI Input Leakage Current		$V_{ACI} = +1.3V$			100	nA
INS Input Leakage Current		$V_{INS} = +3.3V$		1.5	10	μA
LOGIC INPUTS			·			
SHDNM, SHDNC Input Low Voltage					0.4	V
SHDNM, SHDNC Input High Voltage			2.0			V

### **ELECTRICAL CHARACTERISTICS (continued)**

(Figure 1,  $V_{IN} = V_{INS} = +12V$ ,  $V_{INC} = V_{CS-} = V_{CS+} = +3.3V$ ,  $V_{CORE} = +1.8V$ ,  $T_A = 0^{\circ}C$  to +85°C, unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SHDNM, SHDNC Input Low Current		$\overline{\text{SHDNM}} = \overline{\text{SHDNC}} = \text{GND}$	-1		1	μA
SHDNC Input High Current		$V_{\overline{SHDNC}} = +5.5V$			5	μA
SHDNM Input High Current		$V\overline{\text{SHDNM}} = +5V$		2	25	μA

### **ELECTRICAL CHARACTERISTICS**

(Figure 1,  $V_{IN} = V_{INS} = +12V$ ,  $V_{INC} = V_{CS-} = V_{CS+} = +3.3V$ ,  $V_{CORE} = +1.8V$ ,  $T_A = -40^{\circ}C$  to  $+85^{\circ}C$ , unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	MAX	UNITS
Input Voltage	VIN		2.7	28	V
Input Quiescent Supply Current	l <sub>IN</sub>	$V_{FBM} = +1.5V, V_{FBC} = +1.5V, V_{\overline{SHDNM}} = V_{\overline{SHDNC}} = +3.3V$		40	μA
CS- Quiescent Supply Current	I <sub>CS-</sub>	$V_{FBM} = +1.5V, V_{FBC} = +1.5V, V_{\overline{SHDNM}} = V_{\overline{SHDNC}} = +3.3V$		220	μA
Core Regulator Quiescent Supply Current	IINC	$V_{FBM} = +1.5V, V_{FBC} = +1.5V, V_{\overline{SHDNM}} = V_{\overline{SHDNC}} = +3.3V$		105	μA
Backup Mode BIN Quiescent Supply Current	IBIN	$V_{BIN}$ = +3.3V, CS- open $V_{FBM}$ = +1.5V, $V_{\overline{SHDNM}}$ = +3.3V, $V_{\overline{BKOFF}}$ = +1.5V, $\overline{SHDNC}$ = GND		110	μA
IN Shutdown Supply Current		SHDNM = SHDNC = GND		40	μA
MAIN REGULATOR					
Main Output Voltage Adjust Range			1.25	5.5	V
FBM Regulation Threshold	V <sub>FBM</sub>	$V_{(CS+ - CS-)} = 0$ to +60mV, $V_{IN} = +3.5V$ to +28V	1.21	1.29	V
FBM Input Current	IFBM	V <sub>FBM</sub> = +1.3V	-0.1	0.1	μA
Current-Limit Threshold		V <sub>CS+</sub> - V <sub>CS-</sub>	60	100	mV
Minimum Current-Limit Threshold		V <sub>CS+</sub> - V <sub>CS-</sub>	5	25	mV
Valley Current Threshold		V <sub>CS+</sub> - V <sub>CS-</sub>	40	60	mV
Zero Current Threshold		V <sub>CS+</sub> - V <sub>CS-</sub>	0	15	mV
PDRV, NDRV Gate Drive Resistance		$V_{CS-} = +3.3V$ , I <sub>PDRV</sub> , I <sub>NDRV</sub> = 50mA		5.5	Ω
CS- to CVL Switch Resistance		I <sub>CVL</sub> = 50mA		9.5	Ω
Maximum Duty Cycle			100		%
Minimum On-Time			200	650	ns
Minimum Off-Time			200	650	ns



### ELECTRICAL CHARACTERISTICS (continued)

(Figure 1,  $V_{IN} = V_{INS} = +12V$ ,  $V_{INC} = V_{CS+} = V_{CS-} = +3.3V$ ,  $V_{CORE} = +1.8V$ ,  $T_A = -40^{\circ}C$  to  $+85^{\circ}C$ , unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	MAX	UNITS
CORE REGULATOR					
Input Voltage Range	VINC		2.6	5.5	V
		V <sub>INC</sub> rising	2.39	2.55	Ň
INC Undervoltage Lockout		V <sub>INC</sub> falling	2.29	2.45	V
Core Output Voltage Adjust Range			1.0	5.0	V
Maximum Core Load Current		V <sub>CORE</sub> = 1.8V (Note 1)	1		А
FBC Regulation Threshold	V <sub>FBC</sub>	V <sub>INC</sub> = +2.5 to +5.5V, I <sub>OUTC</sub> = 0 to 200mA	0.97	1.03	V
FBC Input Current	IFBC	$V_{FBC} = +1.3V$	-0.1	0.1	μA
Dropout Voltage		I <sub>OUTC</sub> = 400mA		0.25	V
LXC Leakage Current	ILXC	$V_{INC} = +5.5V, V_{LXC} = 0 \text{ to } +5.5V$	-10	10	μA
LXC P-Channel, N-Channel On-Resistance				0.5	Ω
LXC P-Channel Current Limit			1200	3010	mA
LXC P-Channel Minimum Current			100	420	mA
LXC N-Channel Valley Current			880	2450	mA
LXC N-Channel Zero-Crossing Current			40	170	mA
Max Duty Cycle			100		%
Minimum On-Time			160	700	ns
Minimum Off-Time			170	690	ns
BACKUP REGULATOR					
Backup Battery Input Voltage	VBBATT		0.9	5.5	V
LXB N-Channel On Resistance		$V_{CS-} = +3.3V, I_{LXB} = 50mA$		3.5	Ω
LXB Current Limit			200	600	mA
LXB Leakage Current		$V_{LXB} = +5.5V, V_{FBM} = +1.3V$		1	μA
BIN Leakage Current	I <sub>BIN</sub>	$V_{BIN} = +5.5V, CS = \overline{BKOFF} = \overline{SHDNC} = \overline{SHDNM} = GND$		1	μA
BIN, CS- Switch Resistance		$V_{CS-} = +3.3V, \overline{BKOFF} = GND, \overline{SHDNC} = CVL$		15	Ω
BIN Switch Zero-Crossing Threshold		$V_{BIN} = +2.5V, \overline{BKOFF} = \overline{SHDNC} = \overline{SHDNM} = CVL$		35	mV
LXB Maximum On-Time			2.8	9.2	μs
REFERENCE					
Reference Voltage	VREF		1.220	1.275	V
Reference Load Regulation		I <sub>REF</sub> = 0 to 50μA		10	mV
Reference Line Regulation		$V_{CS-} = +2.5V$ to +5.5V, $I_{REF} = 50\mu A$		5	mV
Reference Sink Current			10		μA

### **ELECTRICAL CHARACTERISTICS (continued)**

(Figure 1,  $V_{IN} = V_{INS} = +12V$ ,  $V_{INC} = V_{CS+} = V_{CS-} = +3.3V$ ,  $V_{CORE} = +1.8V$ ,  $T_A = -40^{\circ}C$  to  $+85^{\circ}C$ , unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	МАХ	UNITS
CVL, CVH REGULATORS					
CVL Output Voltage	V <sub>CVL</sub>	$I_{CVL} = 50 \text{mA}, V_{CS-} = 0$	2.6	3.1	V
CVL Switchover Threshold		V <sub>CS-</sub> rising, hysteresis = 100mV typical	2.40	2.55	V
		$V_{IN} = +4V$ , $I_{CVH} = 25mA$		V <sub>IN</sub> - 2.8	
CVH Output Voltage	VCVH	V <sub>IN</sub> = +12V, I <sub>CVH</sub> = 50mA		V <sub>IN</sub> - 3.65	V
		V <sub>CVL</sub> rising	2.40	2.57	Ň
CVL Undervoltage Lockout		V <sub>CVL</sub> falling	2.30	2.47	V
LOW-VOLTAGE COMPARATOR	IS				
Backup Regulator Shutdown		V <sub>BKOFF</sub> rising	0.51	0.59	V
Threshold	VBKOFF	VBKOFF falling	0.46	0.54	v
BKOFF Input Bias Current		$V_{\overline{B}\overline{K}\overline{O}FF} = +5.5V$		1	μA
LBI Threshold	VLBI	V <sub>LBI</sub> falling, hysteresis = 50mV typical	1.17	1.23	V
DBI Threshold	V <sub>DBI</sub>	V <sub>DBI</sub> falling, hysteresis = 50mV typical	1.17	1.23	V
BKUP Low-Input Threshold			0.4		V
LBI, DBI Input Leakage Current		$V_{LBI}, V_{DBI} = +28V$		100	nA
LBO, BKUP, ACO, MDRV Output Low		I <sub>SINK</sub> = 1mA		0.4	V
LBO, BKUP, ACO, MDRV Output Leakage Current		$V_{LBI} = +1.3V$ , $V_{ACI} = V_{IN} = +12V$ , $V_{ACO} = V_{\overline{LBO}} = V_{\overline{BKUP}} = +5.5V$ , $V_{\overline{MDRV}} = +28V$		1.0	μA
ACI Threshold		V <sub>ACI</sub> - V <sub>INS</sub> , ACI falling		0.5	V
ACI Input Leakage Current		$V_{ACI} = +1.3V$		100	nA
MAIN Input Leakage Current		$V_{INS} = +3.3V$		10	μA
LOGIC INPUTS					1
SHDNM, SHDNC Input Low Voltage				0.4	V
SHDNM, SHDNC Input High Voltage			2.0		V
SHDNM, SHDNC Input Low Current		$\overline{\text{SHDNM}} = \overline{\text{SHDNC}} = \text{GND}$	-1	1	μA
SHDNC Input High Current		$V_{\overline{SHDNC}} = +5.5V$		5	μA
SHDNM Input High Current		$V_{\overline{SHDNM}} = +28V$		25	μA

**MAX1774** 

Note 1: This parameter is guaranteed based on the LXC P-channel current limit and the LXC N-channel valley current.

Note 2: Specifications to -40°C are guaranteed by design and not production tested.

**Typical Operating Characteristics** 

(Circuit of Figure 1,  $V_{IN}$  = +5V,  $V_{INC}$  = +3.3V,  $T_A$  = +25°C, unless otherwise noted.)

**CORE EFFICIENCY vs. LOAD** MAIN EFFICIENCY vs. LOAD **BACKUP EFFICIENCY vs. LOAD** 100 100 100 90 90 90 = +2.5VVrratt  $V_{BBATT} = +1.0V$ 80 VIN = 80 +3.3V 80 1/111  $V_{IN} = +5V$ 70 70 70 = +12V VIN : %  $V_{IN} = +2.7V$ EFFICIENCY (%) EFFICIENCY (%) 60 60 60 EFFICIENCY V<sub>IN</sub> = +15V  $V_{IN} = +3.3V$ 50 50 50  $V_{IN} = +5V$  $V_{BBATT} = +0.8V$ 40 40 40  $V_{IN} = +18V$ +18V | | | | 30 30 30 V<sub>CORE</sub> = 1.8V 20 20 20 Vmain = 3.3 10 10 10  $V_{MAIN} = 3.3V$ 0 0 0 1 10 100 1000 10,000 1 10 100 1000 0.01 0.1 1 10 100 LOAD (mA) LOAD (mA) LOAD (mA) **VREF ACCURACY vs. TEMPERATURE REFERENCE LOAD REGULATION** 2.0 0 -0.2 1.5 -0.4 1.0 -0.6 VREF ACCURACY (%) V<sub>REF</sub> ACCURACY (%) 0.5 -0.8 0 -1.0 -1.2 -0.5 -1.4 -1.0 -1.6 -1.5 -1.8 -2.0 -2.0 -20 40 80 100 -40 0 20 60 0 10 20 30 40 50 60 70 80 TEMPERATURE (°C)  $I_{REF}$  ( $\mu A$ ) MAIN SWITCHING WAVEFORMS MAIN SWITCHING WAVEFORMS (LIGHT LOAD 100mA) (HEAVY LOAD 1A) LX 5V/div LX 5V/div 5\ 0 40mV V<sub>MAIN</sub> (AC-COUPLED) 20mV V<sub>MAIN</sub> (AC-COUPLED) 20mV 20mV/div Λ 20mV/div -20mV -20mV 1500mA 500mA I<sub>LI</sub> 500mA/div 1000mA II.1 500mA/div 500mA 5µs/div 5µs/div



100µs/div

100µs/div

### \_Typical Operating Characteristics (continued)

(Circuit of Figure 1,  $V_{IN}$  = +5V,  $V_{INC}$  = +3.3V,  $T_A$  = +25°C, unless otherwise noted.)



### \_Pin Description

PII	PIN		FUNCTION
QSOP	QFN	NAME	FUNCTION
1	30	SHDNM	Shutdown for Main Regulator. Low voltage on $\overline{\text{SHDNM}}$ shuts off the main output. For normal operation, connect $\overline{\text{SHDNM}}$ to IN.
2	31	SHDNC	Shutdown for Core Regulator. Low voltage on SHDNC shuts off the core output. For normal operation, connect SHDNC to CVL.
3	32	BKUP	Open-Drain Backup Input/Output. The device is in backup mode when $\overline{BKUP}$ is low. $\overline{BKUP}$ can be externally pulled low to place the device in backup mode.
4	1	MDRV	Open-Drain Drive Output. MDRV goes low when the ACI voltage drops below the main voltage plus 220mV and device is not in backup. Connect MDRV to the gate of the main battery P-channel MOSFET to switch the battery to IN when the AC adapter voltage is not present.
5	2	PGNDC	Power Ground for the Core Converter. Connect all grounds together close to the IC.
6	3	PGND	Power Ground. Ground for NDRV and core output synchronous rectifier. Connect all grounds together close to the IC.
7	4	NDRV	N-Channel Drive Output. Drives the main output synchronous-rectifier MOSFET. NDRV swings between CVL and PGND.
8	5	CVL	Low-Side Bypass. CVL is the output of an internal LDO regulator. This is the internal power supply for the device control circuitry as well as the N-channel driver. Bypass CVL with a $1.0\mu$ F or greater capacitor to GND. When CS- is above the CVL switchover threshold (2.47V), CVL is powered from the main output.
9	6	IN	Power Supply Input
10	7	PDRV	P-Channel Drive Output. Drives the main output high-side MOSFET switch. PDRV swings between IN and CVH. The voltage at CVH is regulated at $V_{IN}$ - 4.2V unless the input voltage is less than 5.5V.
11	8	CVH	High-Side Drive Bypass. This is the low-side of the P-channel driver output. Bypass with a $1.0\mu$ F capacitor or greater to IN. When the input voltage is less than 5.5V, CVH is switched to PGND.
12	9	LXB	Backup Converter Switching Node. Connect an inductor from LXB to the backup battery and a Schottky diode to BIN to complete the backup converter. In backup mode, this step-up converter powers the main output from the backup battery through BIN.

M/X/W

### Pin Description (continued)

PIN			
QSOP	QFN	NAME	FUNCTION
	10	LXB2	Backup Converter Switching Node. Connect LXB2 to LXB as close to the IC as possible.
13	11	BIN	Backup Battery Input. Connect BIN to the output of the backup boost regulator. Bypass BIN with a $10\mu$ F or greater capacitor to GND. When the MAX1774 is in backup mode, BIN powers the main output.
14	12	BKOFF	Backup Disable Input. Driving BKOFF below +0.5V disables the backup mode. In backup mode, the device enters shutdown when this pin is pulled low. BKOFF can be driven from a digital signal or can be used as a low battery detector to disable the backup converter when the backup battery is low.
15	13	ACI	AC Adapter Low-Voltage Detect Input. Connect to adapter DC input. When the voltage at ACI falls below the voltage at INS plus +0.22V, ACO asserts.
16	14	DBI	Dead Battery Input. Connect DBI to the main battery through a resistive voltage-divider. When DBI drops below +1.20V, no AC adapter is connected (ACO is low, but main output still available), BKUP asserts.
17	15	LBI	Low-Battery Input. Connect LBI to the main battery through a resistive voltage-divider. When the voltage at LBI drops below $+1.20V$ , $\overline{LBO}$ asserts.
18	16	REF	Reference Voltage Output. Bypass REF to GND with a 0.22µF or greater capacitor.
_	17, 25, 29	N.C.	No Connection. Not Internally Connected.
19	18	FBM	Main Output Feedback. Connect FBM to a resistive voltage-divider to set main output voltage between +1.25V to +5.5V.
20	19	CS+	Main Regulator High-Side Current-Sense Input. Connect the sense resistor between CS+ and CS This voltage is used to set the current limit and to turn off the synchronous rectifier when the inductor current approaches zero.
21	20	CS-	Main Regulator Low-Side Current-Sense Input. Connect CS- to the main output.
22	21	FBC	Core Output Feedback. Connect FBC to a resistive voltage-divider to set core output between +1.0V to +5.0V.
23	22	GND	Analog Ground
24	23	INC	Core Supply Input
25	24	ACO	Low AC Output. Open drain ACO asserts when ACI falls below the main output voltage plus 0.22V.
26	26	LBO	Open-Drain Low-Battery Output. LBO asserts when LBI falls below +1.20V.
27	27	INS	Power-Supply Input Voltage Sense Input. Connect INS to the power-supply input voltage.
28	28	LXC	Core Converter Switching Node

### \_Detailed Description

The MAX1774 dual step-down DC-DC converter is designed to power PDA, palmtop, and subnotebook computers. Normally, these devices require two separate power supplies-one for the processor and another higher voltage supply for the peripheral circuitry. The MAX1774 provides an adjustable +1.25V to +5.5V main output designed to power the peripheral circuitry of PDAs and similar devices. The main output delivers up to 2A output current. The lower voltage core converter has an adjustable +1.0V to +5.0V output, providing up to 1.5A output current. Both regulators utilize a proprietary regulation scheme allowing PWM operation at

medium to heavy loads, and automatically switch to pulse skipping at light loads for improved efficiency. Under low-battery conditions, the MAX1774 enters backup mode, making use of a low-voltage backup battery and a step-up regulator to power the output. Figure 1 is the MAX1774 typical application circuit.

#### Operating Modes for the Step-Down Converters

When delivering low output currents, the MAX1774 operates in discontinuous conduction mode. Current through the inductor starts at zero, rises as high as the minimum current limit ( $I_{MIN}$ ), then ramps down to zero during



MAX1774



Figure 1. Typical Application Circuit For Low-Input Voltage Applications

each cycle (see *Typical Operating Characteristics*). The switch waveform may exhibit ringing, which occurs at the resonant frequency of the inductor and stray capacitance, due to the residual energy trapped in the core when the rectifier MOSFET turns off. This ringing is normal and does not degrade circuit performance.

When delivering medium-to-high output currents, the MAX1774 operates in PWM continuous-conduction mode. In this mode, current always flows through the inductor and never ramps to zero. The control circuit

adjusts the switch duty cycle to maintain regulation without exceeding the peak switching current set by the current-sense resistor.

#### **100% Duty Cycle and Dropout**

The MAX1774 operates with a duty cycle up to 100%, extending the input voltage range by turning the MOS-FET on continuously when the supply voltage approaches the output voltage. This services the load when conventional switching regulators with less than





Figure 2. Simplified Control System Block Diagram

100% duty cycle fail. Dropout voltage is defined as the difference between the input and output voltages when the input is low enough for the output to drop out of regulation. Dropout depends on the MOSFET drain-to-source on-resistance, current-sense resistor, and inductor series resistance, and is proportional to the load current:

VDROPOUT = IOUT [RDS(ON) + RSENSE + RL]

#### **Regulation Control Scheme**

The MAX1774 has a unique operating scheme that allows PWM operation at medium and high current, automatically switching to pulse-skipping mode at lower currents to improve light-load efficiency. Figure 2 shows a simplified block diagram.

Under medium and heavy load operation, the inductor current is continuous and the part operates in PWM mode. In this mode, depending on the duty cycle, either the minimum on-time or the minimum off-time sets the switching frequency. The duty cycle is approximately the output voltage divided by the input voltage. If the duty cycle is less than 50%, the minimum on-time controls the frequency, and the frequency is approximately f ~ 2.5MHz × D, where D is the duty cycle. If the duty cycle is greater than 50%, the minimum off-time sets the frequency, and the frequency is approximately f ~ 2.5MHz × (1 - D).

In both cases, the error comparator regulates the voltage. For low duty cycles (<50%), the P-channel MOS-FET is turned on for the minimum on-time, causing fixed-on-time operation. During the MOSFET on-time, the output voltage rises. Once the MOSFET is turned off, the voltage drops to the regulation threshold, when another cycle is initiated. For high duty cycles (>50%), the MOSFET remains off for the minimum off-time, causing fixed-off-time operation. In this case, the MOS-FET remains on until the output voltage rises to the regulation threshold. Then the MOSFET turns off for the minimum off-time, initiating another cycle.

By switching between fixed-on-time and fixed-off-time operation, the MAX1774 can operate at high input-output ratios and still operate up to 100% duty cycle for low dropout. When operating from fixed-on-time operation, the minimum output voltage is regulated, but in fixed-off-time operation, the maximum output voltage is regulated. Thus, as the input voltage drops below approximately twice the output voltage, a decrease in line regulation can be expected. The drop in voltage is approximately VDROP  $\approx$  VRIPPLE. At light output loads, the inductor current is discontinuous, causing the MAX1774 to operate at lower frequencies, reducing the MOSFET gate drive and switching losses. In discontinuous mode, under most circumstances, the on-time will be a fixed minimum on-time of 400ns.



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**MAX1774** 

The MAX1774 features four separate current-limit threshold detectors and a watchdog timer for each of its step-down converters. In addition to the more common peak-current detector and zero-crossing detector, each converter also provides a valley-current detector, and a minimum-current detector. The valley-current detector is used to force the inductor current to drop to a lower level after hitting peak current before allowing the Pchannel MOSFET to turn on. This is a safeguard against inductor current significantly overshooting above the peak current when the inductor discharges too slowly when VOUT/L is small. The minimum-current detector ensures that a minimum current is built up in the inductor before turning off the P-channel MOSFET. This helps the inductor to charge the output near dropout when the dl/dt is small (because (VIN - VOUT) / L is small) to avoid multiple pulses and low efficiency. This feature, however, is disabled during dropout and light-load conditions where the inductor current may take too long to reach the minimum current value. A watchdog timer overrides the minimum current after the P-channel MOS-FET has been on for longer than about 10µs.

#### Main Step-Down Converter

The main step-down converter features adjustable +1.25V to +5.5V output delivering up to 2A from a +2.7V to +28V input (see Setting the Output Voltages). The use of external MOSFETs and current-sense resistor maximizes design flexibility. The MAX1774 offers a synchronous-rectifier MOSFET driver that improves efficiency by eliminating losses through a diode. The two MOSFET drive outputs, PDRV and NDRV, control these external MOSFETs. The output swing of these outputs is limited to reduce power consumption by limiting the amount of injected gate charge (see Internal Linear Regulators section for details). Current-limit detection for all main converter current limits is sensed through a small-sense resistor at the converters' output (see Setting the Current Limit section ). Driving the SHDNM pin low puts the main converter in a low-power shutdown mode. The core regulator, low-voltage detectors, and backup converter are still functional when the main converter is in shutdown. When the MAX1774 enters backup mode, the main converter and its current sensor are shut off.

### **Core Step-Down Converter**

The core step-down converter produces a +1.0V to +5.0V output from a +2.6V to +5.5V input. The low-voltage input allows the use of internal power MOSFETs, taking advantage of their low  $R_{DS(ON)}$ , improving efficiency and reducing board space. Like the main converter, the core regulator makes use of a synchronous-rectifying N-channel MOSFET, improving efficiency and

eliminating the need for an external Schottky diode. Current sensing is internal to the device, eliminating the need for an external sense resistor. The maximum and minimum current limits are sensed through the P-channel MOSFET, while the valley current and zero-crossing current are sensed through the N-channel MOSFET. The core output voltage is measured at FBC through a resistive voltage-divider. This divider can be adjusted to set the output voltage level (see Setting the Output Voltages). The core input can be supplied from the main regulator or an external supply that does not exceed +5.5V (see High-Voltage Configuration and Low-Voltage Configuration sections). The core converter can be shut down independent of the main converter by driving SHDNC low. If the main converter output is supplying power to the core and is shut down, SHDNM controls both outputs. In this configuration, the core converter continues to operate when the MAX1774 is in backup mode.

**Voltage Monitors and Battery Switchover** The MAX1774 offers voltage monitors ACI, LBI, DBI, and BKOFF that drive corresponding outputs to indicate low-voltage conditions. The AC adapter low-voltage detect input, ACI, is typically connected to the output of an AC-to-DC converter. When the voltage at ACI drops below the INS sense input plus 0.22V, the low AC output, ACO, is asserted. Figure 3 shows a simplified block diagram.

The low and dead battery monitors (LBI and DBI) monitor the voltage at MAIN\_BATT through a resistive voltage-divider. When the voltage <u>at LBI</u> falls below +1.20V, the low-battery output flag, LBO, is asserted.

When both VIN\_AC and MAIN\_BATT are present, the MAX1774 chooses one of the two supplies determined by ACI. To facilitate this, the MAX1774 provides an open-drain MOSFET driver output (MDRV). This drives an external P-channel MOSFET used to switch the MAX1774 from the AC input to the battery. MDRV goes low when ACO is low, the main battery is not dead, and the MAX1774 is not in backup mode.

The MAX1774 enters backup mode when the voltage at DBI is below +1.20V and VIN\_AC is not present to the board. Under these conditions, the BKUP output is asserted (low), and the device utilizes its boost converter and a low-voltage backup battery to supply the main output. The BKUP pin can be driven low externally, forcing the MAX1774 to enter backup mode. If the voltage at BKOFF is less than 0.5V, the backup converter is disabled. BKOFF can be driven from a digital signal, or can be used as a low-battery detector to disable the backup converter when the backup battery is low.





Figure 3. Simplified Block Diagram

<u>Place 1M</u> $\Omega$  pullup resistors from the main output to <u>ACO</u>, <u>LBO</u>, and <u>BKUP</u>. Use a 1M $\Omega$  pullup resistor from <u>MDRV</u> to IN.

When not in backup mode, the backup regulator is isolated from the main output by an internal switch. When the MAX1774 is in backup mode, the main converter is disabled, and the output of the backup regulator is connected to the main output. The core converter is still operable while in backup mode. The backup step-up converter cannot drive the typical main load current. The load at main must be reduced before entering backup mode.

If  $\overline{\text{BKUP}}$  is de-asserted (goes high), the MAX1774 exits backup mode and resumes operation from the main battery or the AC adapter input. If  $\overline{\text{BKOFF}}$  goes low, or the backup battery discharges where it cannot sustain the main output load, the backup converter shuts off. To restart the main converter, apply power to VIN\_AC or MAIN\_BATT.

The backup converter uses an external Schottky diode and internal power NMOS switch. Since this converter shares the same output as the main buck converter, it shares the same feedback network. This automatically sets the backup converter output voltage to that of the main converter. The backup converter generates an output between +1.25V and +5.5V from a +0.9V to +5.5V input, and provides a load current up to 20mA. When the MAX1774 is in backup mode, the main current- sense circuit is turned off to conserve power.

When the output is out of regulation, the maximum inductor current limit and zero-current detectors regulate switching. The N-channel MOSFET is turned on until the maximum inductor current limit is reached, and shuts off until the inductor current reaches zero. When the output is within regulation, switching is controlled by the maximum pulse width, LXB, switch current limit, zero crossing, and the feedback voltage.

#### **Internal Linear Regulators**

There are two internal linear regulators in the MAX1774. A high-voltage linear regulator accepts inputs up to +28V, reducing it to +2.8V at CVL to provide power to the MAX1774. If the voltage at CS- is greater than +2.47V, CVL is switched to CS-, allowing it to be driven from the main converter, improving efficiency. CVL supplies the internal bias to the IC and power for the NDRV gate driver.

The CVH regulator output provides the low-side voltage for the main regulator's PDRV output. The voltage at CVH is regulated at 4.2V below  $V_{IN}$  to limit the voltage swing on PDRV, reducing gate charge and improving efficiency (Figure 3).

#### Reference

The MAX1774 has a trimmed internal +1.25V reference at REF. REF can source no more than  $50\mu$ A. Bypass REF to GND with a 0.22µF capacitor.

### Design Procedure

#### **Low-Voltage Configuration**

To improve efficiency and conserve board space, the core regulator operates from low input voltages, taking advantage of internal low-voltage, low-on-resistance MOSFETs. When the input voltage remains below 5.5V, run the core converter directly from the input by connecting INC to IN (Figure 1). This configuration takes advantage of the core's low-voltage design and improves efficiency.

#### **High-Voltage Configuration**

For input voltages greater than 5.5V, cascade the main and core converters by connecting INC to the main output voltage (Figure 4). In this configuration, the core converter is powered from the main output. Ensure that the main output can simultaneously supply its load and the core input current.

#### **Backup Converter Configuration**

The MAX1774 provides a backup step-up converter to power the device and provide the main output voltage when other power fails. The backup converter operates from a +0.9V to +5.5V battery. For most rechargeable batteries, such as NiCd or NiMH, the simple circuit of Figure 5 can be used to recharge the backup battery. In this circuit, the backup battery is charged through R1 and D10. Consult the battery manufacturer for charging requirements. To prevent the backup battery from overdischarging, connect <u>a resistive voltagedivider</u> from the backup battery to <u>BKOFF</u>. Resistor values can be calculated through the following equation:

where  $V_{BKOFF} = 0.5V$ , and  $V_{BU}$  is the minimum acceptable backup battery voltage. Choose R13 to be less than 150k $\Omega$ .

#### **Setting the Output Voltages**

The main output voltage is set from +1.25V and +5.5V with two external resistors connected as a voltagedivider to FBM (Figure 1). Resistor values can be calculated by the following equation:

#### R10 = R11 × [(VOUTM / VFBM) - 1]

where  $V_{FBM}$  = +1.25V. Choose R11 to be 40k $\Omega$  or less.

The core regulator output is adjustable from +1.0V to +5.0V through two external resistors connected as a





Figure 4. Typical Application Circuit (Cascaded)

voltage-divider to FBC (Figure 1). Resistor values can be calculated with the following equation:

$$R8 = R9 \times [(V_{OUTC} / V_{FBC}) - 1]$$

where  $V_{FBC} = +1.0V$ . Choose R9 to be  $30k\Omega$  or less.

### **Setting the Current Limit**

The main regulator current limit is set externally through a small current-sense resistor,  $R_{CS}$  (Figure 1). The value of  $R_{CS}$  can be calculated with the following equation:



### $R_{CS} = V_{CLM} / (1.3 \times I_{OUT})$

where  $V_{CLM} = 80mV$  is the current-sense threshold, and  $I_{OUT}$  is the current delivered to the output. The core and backup converter current limits are set internally and cannot be modified.

Careful layout of the current-sense signal traces is imperative. Place R<sub>CS</sub> as close to the MAX1774 as possible. The two traces should have matching length and width, be as far as possible from noisy switching sig-

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Figure 5. Typical Application Circuit (with Recharge)

nals, and be close together to improve noise rejection. These traces should be used for current-sense signal routing only and should not carry any load current. Refer to the *MAX1774 evaluation kit* for layout examples.

#### **Setting the Voltage Monitor Levels**

The low battery and dead battery detector trip points can be set by adjusting the resistor values of the divider string (R1, R2, and R3) in Figure 1 according to the following equations:

$$R1 = (R2 + R3) \times [(V_{BD} / V_{TH}) - 1]$$

$$R2 = R3 \times [(V_{BL} / V_{BD}) - 1]$$

where V<sub>BL</sub> is the low battery voltage, V<sub>BD</sub> is the dead battery voltage, and V<sub>TH</sub> = +1.20V. Choose R3 to be less than  $250k\Omega$ .



#### **Inductor Selection**

The essential parameters for inductor selection are inductance and current rating. The MAX1774 operates with a wide range of inductance values.

Calculate the inductance value for either CORE or MAIN,  $\ensuremath{\mathsf{L}}_{MIN}$  :

 $L(MIN) = (VIN - VOUT) \times (tON(MIN) / IRIPPLE)$ 

where tonmin is typically 400ns, and IRIPPLE is the continuous conduction peak-to-peak IRIPPLE current.

In continuous conduction, I<sub>RIPPLE</sub> should be chosen to be 30% of the maximum load current. With high inductor values, the MAX1774 begins continuous-conduction operation at a lower fraction of full load (see *Detailed Description*).

The inductor's saturation current must be greater than the peak switching current to prevent core saturation. Saturation occurs when the inductor's magnetic flux density reaches the maximum level the core can support and inductance starts to fall. The inductor heating current rating must be greater than the maximum load current to prevent overheating. For optimum efficiency, the inductor series resistance should be less than the current-sense resistance.

#### **Capacitor Selection**

Choose the output filter capacitors to service input and output ripple current with acceptable voltage ripple. ESR in the output capacitor is a major contributor to output ripple. For the main converter, low-ESR capacitors such as polymer or ceramic capacitors are recommended. For the core converter, choosing a low-ESR tantalum capacitor with enough ESR to generate about 1% ripple voltage across the output is helpful in ensuring stability.

Voltage ripple is the sum of contributions from ESR and the capacitor value:

VRIPPLE ≈ VRIPPLE,ESR + VRIPPLE,C

For tantalum capacitors, the ripple is determined mostly by the ESR. Voltage ripple due to ESR is:

VRIPPLE,ESR ≈ (RESR) × IRIPPLE

For ceramic capacitors, the ripple is mostly due to the capacitance. The ripple due to the capacitance is approximately:

VRIPPLE,C ≈ L IRIPPLE<sup>2</sup>COUT VOUT

where  $V_{OUT}$  is the average output voltage.

These equations are suitable for initial capacitor selection. Final values should be set by testing a prototype or evaluation kit. When using tantalum capacitors, use good soldering practices to prevent excessive heat from damaging the devices and increasing their ESR.



Also, ensure that the tantalum capacitors' surge-current ratings exceed the startup inrush and peak switching currents.

The input filter capacitor reduces peak currents drawn from the power source and reduces noise and voltage ripple at IN, caused by the circuit's switching. Use a low-ESR capacitor. Two smaller value low-ESR capacitors can be connected in parallel if necessary. Choose input capacitors with working voltage ratings higher than the maximum input voltage.

#### **MOSFET Selection**

The MAX1774 drives an external enhancement-mode Pchannel MOSFET and a synchronous-rectifier N-channel MOSFET. When selecting the MOSFETs, important parameters to consider are on-resistance ( $R_{DS(ON)}$ ), maximum drain-to-source voltage ( $V_{DS(MAX)}$ ), maximum gate-to-source voltage ( $V_{GS(MAX)}$ ), and minimum threshold voltage ( $V_{TH(MIN)}$ ).

### **Chip Information**

TRANSISTOR COUNT: 4545 PROCESS: BICMOS

#### TOP VIEW SHDNM 28 LXC SHDNC 27 INS 2 26 LBO BKUP 3 MDRV 4 25 ACO MAXIM PGNDC 5 24 INC MAX1774 PGND 6 23 GND NDRV 7 22 FBC CVL 8 21 CS-20 CS+ IN 9 19 FBM PDRV 10 18 REF CVH 11 17 LBI LXB 12 16 DBI BIN 13 BKOFF 14 15 ACI **28 QSOP**

### Pin Configurations (continued)

### **Package Information**



M/IXI/M

### Package Information (continued)



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