AKM

AK9813B 12ch 8bit D/A Converter with EEPROM

General Description

The AK9813B includes 12 channel, 8bit D/A converters with on-chip output buffer amps and it is capable to store the input digital data of each DAC by on-chip non-volatile CMOS EEPROM. The AK9813B is optimally designed for various circuit adjustments for consumer and industrial equipments and it is ideally suited for replacing mechanical trimmers.



Analog section : 4.5V to 5.5V, 2.7V to 3.6V

□ 24pin VSOP



Block Diagram

Ordering Guide

| Model | Temp. Range | Package |
|----------|--------------|-------------|
| AK9813BF | -40 to +85°C | 24-pin VSOP |

Pin Layout



24pin VSOP

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| No. | Pin Name | I/O | Function |
|-----|---------------|-----|--|
| 20 | DI | Ι | Serial Data Input Pin SEL=High : 16bit data input format SEL=Low : 14bit data input format |
| 17 | DO | 0 | (SEL=High: CS I/F) AK9813B reads out the data with LSB first in the 16bit shift register to DO pin synchronously with falling edge of CLK. When the \overline{CS} pin is high level, the DO pin becomes high impedance. In STATUS mode, the DO pin outputs Ready/Busy status. |
| | | | (SEL=Low: LD I/F) AK9813B reads out the data with MSB first in the 14bit shift register to DO pin synchronously with falling edge of CLK. In WRITE mode, the DO pin outputs Ready/Busy status. |
| 19 | CLK | Ι | Shift Clock Input Pin (Schmitt-trigger input) AK9813B takes in the data from DI pin synchronously with rising edge of the CLK pin. The data are transferred to the internal shift register. |
| 18 | <u>C</u> S/LD | Ι | Chip Select Input Pin (Schmitt-trigger input) The CS/LD is internally pulled up to VCC. (SEL=High: CS I/F) After the CS pin changes from high level to low level while the CLK pin is high level, the AK9813B can input the data to the internal shift register and takes in the data from the DI pin synchronously with the rising edge of the CLK pin. After the CS pin changes from high level to low level while the CLK pin is low level, the AK9813B becomes the status mode and reads out the Ready/Busy status to the DO pin. When the CS pin changes from low level to high level regardless of Low/High level of the CLK pin, the AK9813B removes from the status mode to the normal mode. The CS pin usually should be kept at high level. |
| | | | (SEL=Low: LD I/F) When the LD pin receives high pulse, the data of the internal shift register is transferred to the internal decoder or the register for D/A. The LD pin usually should be kept at low level. |

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Pin Description (2)

| No. | Pin Name | I/O | Function | | | | |
|--------------|------------------|-----|---|--|--|--|--|
| 1 12 | AO1 AO12 | 0 | 8bit D/A outputs with OP-AMP | | | | |
| 14 | VCC | | Digital section Power Supply Pin | | | | |
| 23 | GND | _ | Digital section Ground Pin | | | | |
| 13 | VDD | | OP-AMP and D/A section Power Supply | | | | |
| 24 | VSS | — | OP-AMP and D/A section Ground | | | | |
| 21 22 | EA0 EA1 | I | (SEL=High: CS I/F) In AUTO READ operation and ECL operation, the address of EEPROM is selected by the EA0 and the EA1 pins. (SEL=Low: LD I/F) The address of EEPROM is selected by the EA0 and the EA1 pins. | | | | |
| 16 | ECL | I | When the ECL pin receives high pulse, the data in EEPROM is automatically loaded to each corresponding D/A, starting from AO1 to AO12 in order. Then each D/A output is settled to pre-determined value. | | | | |
| 15 | SEL | Ι | Input Data Format Select Pin SEL=High : CS I/F SEL=Low : LD I/F After power-up, this pin should be kept either at "high" or "Low." | | | | |

Data Configuration

AK9813B have a shift register in order to control the chip.

When the SEL pin is "H"(CS I/F), the shift register becomes 16bit configuration and the data on the DI pin should be loaded with LSB first. When the SEL pin is "L"(LD I/F), the shift register becomes 14bit configuration and the data on the DI pin is loaded with MSB first.

The following description shows the configuration of the shift register.

The data set consist of 2-bits for the control of the internal EEPROM, 2-bits for the address of the EEPROM (CS I/F only), 4-bits for select of D/A converter and 8-bits for the digital input data of the 8bit D/A converter and total data set is 16bits or 14bits.

① Shift register configuration: SEL=High (CS I/F)

| MSB Last | | | | | | | | | | | | | | \longrightarrow | LSB First |
|--------------|----|--------------------------|----|-----|---------|----|----|----|----|-----------------|------------------|----|----|-------------------|--------------|
| A1 | A0 | CL | WR | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| EEPR ADDF | | EEPF CON ⁻ | | | LECTION | | | < | | DIGIT/ FOR [| AL INP D/A CC | | | | |

OUTPUT VOLTAGE FOR D/A CONVERTER

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | OUTPUT VOLTAGE FOR D/A |
|----|----|----|----|----|----|----|----|---------------------------|
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | ≒ GND=VSS |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | ≒ VDD/255 x 1 |
| 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | ≒ VDD/255 x 2 |
| | | | | | | | | |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | ≒ VDD/255 x 254 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | ≒ VDD |

| A1 | A0 | EEPROM ADDRESS |
|----|----|----------------|
| 0 | 0 | ADDRESS: 0 |
| 0 | 1 | ADDRESS: 1 |
| 1 | 0 | ADDRESS: 2 |
| 1 | 1 | ADDRESS: 3 |

D/A CONVERTER CHANNEL SELECTION

| D11 | D10 | D9 | D8 | D/A CHANNEL |
|-----|-----|----|----|-------------|
| 0 | 0 | 0 | 0 | Don't Care |
| 0 | 0 | 0 | 1 | AO1 |
| 0 | 0 | 1 | 0 | AO2 |
| 0 | 0 | 1 | 1 | AO3 |
| 0 | 1 | 0 | 0 | AO4 |
| 0 | 1 | 0 | 1 | AO5 |
| 0 | 1 | 1 | 0 | AO6 |
| 0 | 1 | 1 | 1 | AO7 |

| D11 | D10 | D9 | D8 | D/A CHANNEL |
|-----|-----|----|----|-------------|
| 1 | 0 | 0 | 0 | AO8 |
| 1 | 0 | 0 | 1 | AO9 |
| 1 | 0 | 1 | 0 | AO10 |
| 1 | 0 | 1 | 1 | AO11 |
| 1 | 1 | 0 | 0 | AO12 |
| 1 | 1 | 0 | 1 | Can't use |
| 1 | 1 | 1 | 0 | Can't use |
| 1 | 1 | 1 | 1 | Don't Care |

(NOTE) Above "Don't Care" state is valid only when AK9813B is in DAC mode or WRITE mode. Refer to the following section "Instruction Set" about mode.

② Shift register configuration: SEL=Low (LD I/F)

| LSB Last | | 5 | | | | , | | | | | | | MSI > Firs | |
|-------------|----|----|------------------|----|----|----|----|----|----|----------------|-----|--------------------------|---------------|--|
| D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 | D8 | D9 | D10 | D11 | WR | CL | |
| < | | | al INF D/a CC | | | | > | | | ON FC VERTE | | EEPF CON ⁻ | | |

OUTPUT VOLTAGE FOR D/A CONVERTER

| D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 | OUTPUT VOLTAGE FOR D/A |
|----|----|----|----|----|----|----|----|---------------------------|
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | ≒ GND=VSS |
| 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | ≒ VDD/255 x 1 |
| 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | ≒ VDD/255 x 2 |
| | | | | | | | | |
| 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | ≒ VDD/255 x 254 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | ≒ VDD |

| EA1 | EA0 | EEPROM ADDRESS |
|-----|----------|----------------|
| 0 | 0 | ADDRESS: 0 |
| 0 | 1 | ADDRESS: 1 |
| 1 | 0 | ADDRESS: 2 |
| 1 | 1 | ADDRESS: 3 |
| | ` | |

NOTE)

EEPROM ADDRESS is selected by the EA0 and EA1 pins.

D/A CONVERTER CHANNEL SELECTION

| D8 | D9 | D10 | D11 | D/A CHANNEL |
|----|----|-----|-----|-------------|
| 0 | 0 | 0 | 0 | Don't Care |
| 0 | 0 | 0 | 1 | AO1 |
| 0 | 0 | 1 | 0 | AO2 |
| 0 | 0 | 1 | 1 | AO3 |
| 0 | 1 | 0 | 0 | AO4 |
| 0 | 1 | 0 | 1 | AO5 |
| 0 | 1 | 1 | 0 | AO6 |
| 0 | 1 | 1 | 1 | AO7 |

| D8 | D9 | D10 | D11 | D/A CHANNEL |
|----|----|-----|-----|-------------|
| 1 | 0 | 0 | 0 | AO8 |
| 1 | 0 | 0 | 1 | AO9 |
| 1 | 0 | 1 | 0 | AO10 |
| 1 | 0 | 1 | 1 | AO11 |
| 1 | 1 | 0 | 0 | AO12 |
| 1 | 1 | 0 | 1 | Can't use |
| 1 | 1 | 1 | 0 | Can't use |
| 1 | 1 | 1 | 1 | Don't Care |

(NOTE) Above "Don't Care" state is valid only when AK9813B is in DAC mode or WRITE mode. Refer to the following section "Instruction Set" about mode. Instruction Set

The AK9813B can be controlled for the following mode. The following mode is common to the LD I/F and the CS IF. When LD I/F is selected, "A1" and "A0" are set by the external pins (EA0 pin and EA1 pin).

(1) DAC mode (External DI pin \rightarrow D/A converter)

| A1 | A0 | CL | WR | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | Function |
|----|----|----|----|-----|------|------|----|----|----|------|--------|--------|-----|----|----|------------|
| Х | Х | 0 | 0 | D | A CH | ANNE | ΞL | | | Digi | tal Da | ta for | D/A | | | D/A output |

②CALL mode (Internal EEPROM -> D/A converter)

| A1 | A0 | CL | WR | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | | Function |
|-----|------|----|----|-----|------|------|----|----|----|----|----|----|----|----|----|------|----------|
| ADD | RESS | 1 | 0 | D | A CH | ANNE | EL | Х | Х | Х | Х | Х | Х | Х | Х | READ | |

• The output of D/A converter is set by the data in the internal EEPROM.

③ALL CALL mode (Internal EEPROM -> D/A converter)

| A1 | A0 | CL | WR | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | Function |
|------|------|----|----|-----|-----|----|----|----|----|----|----|----|----|----|----|------------------|
| ADDF | RESS | 1 | 0 | 0 | 0 | 0 | 0 | Х | Х | Х | Х | Х | Х | Х | Х | ALL CHANNEL READ |

• The outputs of all D/A converters are set by the data in the internal EEPROM.

...Internal ECL function

[X: Don't Care]

(4) WRITE ENABLE mode (Internal EEPROM WRITE ENABLE)

| A1 | A0 | CL | WR | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | Function |
|----|----|----|----|-----|-----|----|----|----|----|----|----|----|----|----|----|--------------|
| Х | Х | 1 | 1 | 0 | 0 | 0 | 0 | Х | Х | Х | Х | Х | Х | Х | Х | WRITE ENABLE |

•After WRITE ENABLE mode is executed, the programming to the internal EEPROM is enabled. Upon power-up and after the execution of the ECL function, the AK9813B is in the programming disable state.

(5) WRITE DISABLE mode (Internal EEPROM WRITE DISABLE)

| A1 | A0 | CL | WR | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | Function |
|----|----|----|----|-----|-----|----|----|----|----|----|----|----|----|----|----|---------------|
| Х | Х | 1 | 1 | 1 | 1 | 1 | 1 | Х | Х | Х | Х | Х | Х | Х | Х | WRITE DISABLE |

•After WRITE DISABLE mode is executed, the programming to the internal EEPROM is disabled.

6 WRITE mode (External DI pin -> Internal EEPROM)

| A1 | A0 | CL | WR | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | Function |
|-----|------|----|----|-----|-------|------|----|----|----|------|--------|--------|-----|----|----|----------|
| ADD | RESS | 0 | 1 | D/ | /A CH | ANNE | ΞL | | | Digi | tal Da | ta for | D/A | | | WRITE |

• The digital data for D/A (D0 to D7) is written into the specified address in the internal EEPROM. The state of the internal EEPROM must be the programming enable state.

⑦READ mode (Internal EEPROM -> External DO pin)

| A1 | A0 | CL | WR | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | Function |
|-----|------|----|----|-----|------|------|----|----|----|----|----|----|----|----|----|--------------------|
| ADD | RESS | 1 | 1 | D/ | A CH | ANNE | ΞL | Х | Х | Х | Х | Х | Х | Х | Х | EEPROM DATA output |

• The DO pin outputs the data in the internal EEPROM synchronously with the falling edge of the input pulse of the CLK pin.

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[AK9813B]

[X: Don't Care]

| | Functional Description |
|----------|---|
| | Diagram for CS I/F (SEL="H") ode: The internal EEPROM is not used. |
| DI | (D0) D1) D2) D3) D4) D5) D6) D7) D8) D9) D10) D11) WR CL (A0) A1 |
| CLK | |
| CS/LD | |
| DO | |
| AO1 - 12 | X |

2. WRITE ENABLE/DISABLE mode: The programming state of the internal EEPROM is set.



3. CALL mode: The output of the D/A is set by the data in the internal EEPROM.



4. ALL CALL mode: The outputs of the all D/As are set by the data in the internal EEPROM.



•The D/A outputs are set from AO1 to AO12 in order.

5. WRITE mode: The digital input data for D/A converter is written into the internal EEPROM.



6. READ mode: The data in the internal EEPROM is read from the DO pin.



7. STATUS mode: The DO pin outputs the Ready/Busy status from the DO pin.



8. ECL function: For "H" pulse to the ECL pin, the data in the selected address in the internal EEPROM is automatically loaded. Then each D/A converter output is settled to pre-determined value.



9. Transfer mode for the cascade connection

In case that AK9813B devices are connected in cascade, the AK9813B under programming cycle can transfer the data to the other AK9813B. The some AK9813B devices can be operated by the common \overline{CS} signal at the same time.

Please note that the input data into to the AK9813B under programming cycle should be all "0" when the \overline{CS} pin is changed from "L" to "H". If data except all "0" is input into the AK9813B under programming cycle, accidental data disturbance may occur.



②Timing Diagram for LD I/F (SEL ="L")1. DAC mode: The internal EEPROM is not used.



2. WRITE ENABLE/DISABLE mode: The programming state of internal EEPROM is set.

| | "1111"=WRITE DISABLE |
|-------|--|
| DI | CL WR (D11 D10 D9 D8) D7 (D6) D5) D4 (D3) D2) D1 (D0 |
| | "0000"=WRITE ENABLE |
| CLK | |
| CS/LD | |

3. CALL mode: The output of the D/A is set by the data in the internal EEPROM.

| DI | CL WR (D11 (D10) D9) D8 (D7) D6 (D5) D4 (D3) D2 (D1) D0 |
|----------|---|
| CLK | |
| EA0, EA1 | χ |
| CS/LD | |
| DO | |
| AO1 - 12 | X |

| DI | CL WR D11 D10 D9 D8 (D7) D6) D5) D4) D3) D2) D1) D0 |
|----------|---|
| CLK | |
| EA0, EA1 | X |
| CS/LD | |
| DO | |
| AO1 - 12 | X |

4. ALL CALL mode: The outputs of the all D/As are set by the data in the internal EEPROM.

•The D/A outputs are set from AO1 to AO12 in order.

5. WRITE mode: The digital input data for D/A converter is written into the internal EEPROM.

| DI | CL / WR (D11 (D10) D9 (D8 (D7) D6 (D5) D4 (D3) D2 (D1) D0 |
|----------|---|
| CLK | |
| EA0, EA1 | χ |
| CS/LD | |
| DO | |
| | |

(NOTE)

- * In case that AK9813B devices are connected in cascade, when a AK9813B device is under programming cycle, the AK9813B device under programming cycle can not transfer the data to the other AK9813B device and some AK9813B devices can not be operated by the common CS signal at the same time.
- * While programming cycle, the \overline{CS}/LD pin should be "L".
- * When the Ready/Busy signal from the DO pin is verified, the CS pin should be changed from "H" to "L" and kept at "L". If the CS pin is kept at "H", the Ready/Busy signal does not output correctly.

6. READ mode: The data in the internal EEPROM is read from the DO pin.

| DI | CL WR (D11) (D10) (D9) (D8) (D7 ·· D1) (D0) (D4 Data for next mode or all "0" |
|----------|---|
| CLK | $\begin{array}{c} \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\$ |
| EA0, EA1 | |
| CS/LD | · |
| DO | |
| | INVALID DATA VALID DATA (8bit: MSB first) |
| AO1 - 12 | Not change |

7. ECL function:

When the ECL pin received high pulse, the data in EEPROM is automatically loaded to each corresponding D/A, and starting from AO1 to AO12 in order. Then each D/A output is settled to pre-determined value.

| EA0, EA1 | EEPROM ADDRESS X |
|----------|---|
| ECL | |
| AO1 - 12 | |
| | * Analog outputs are set from AO1 to AO12 in order. |

Absolute Maximum Ratings

| Parameter | Symbol | Spec. | Unit |
|---------------------|--------|-----------------|------|
| Power Supply | VCC | -0.6 to +7.0 | V |
| Input Voltage | VIO | -0.6 to VCC+0.6 | V |
| Ambient Temperature | Та | -40 to +85 | °C |
| Storage Temperature | Tst | -65 to +150 | С° |

Recommended Operating Conditions

| Parameter | Symbol | Conditions | Min | Тур | Max | Units |
|-------------------------------------|--------|------------------|-----|-----|-----|-------|
| Power Supply 1 (Digital section) | VCC | | 2.7 | | 5.5 | V |
| Power Supply 2 | VDD1 | | 4.5 | | 5.5 | V |
| (DAC, AMP sections) | VDD2 | | 2.7 | | 3.6 | V |
| Analog Output Source Current 1 | IAL | | | | 1 | mA |
| Analog Output Sink Current 1 | IAH | VDD=4.5V to 5.5V | | | 1 | mA |
| Analog Output Source Current 2 | IAL | VDD=2.7V to 3.6V | | | 500 | μA |
| Analog Output Sink Current 2 | IAH | 2.7 0 10 5.00 | | | 500 | μΑ |
| Analog Output Load Capacitance | AOC | | | | 1.0 | μF |

Electrical Characteristics

DC Characteristics

(1) Digital Section

(VCC=2.7V to 5.5V, VDD=4.5V to 5.5V or 2.7V to 3.6V, GND, VSS=0V, Ta=-40°C to +85°C)

| Parameter | Symbol | Pin | Conditions | Min | Max | Units |
|-------------------------------------|--------|--|-----------------------------|---------|----------|-------|
| Power Supply (Digital Section) | VCC | | | 2.7 | 5.5 | V |
| Operating Current (READ) (1) (2) | ICC | VCC | CLK=1MHz | | 1.1 | mA |
| Leakage Current | ILI | <u>CL</u> K, DI CS/LD EA0, EA1 ECL, SEL | VIN=VCC | -1.0 | 1.0 | μA |
| High Level Input Voltage 1 | VIH | DI EA0, EA1 | | 0.5xVCC | | V |
| Low Level Input Voltage 1 | VIL | ECL, SEL | | | 0.2xVCC | V |
| High Level Input Voltage 2 | VIH | CS/LD CLK | | 0.6xVCC | | V |
| Low Level Input Voltage 2 | VIL | | | | 0.15xVCC | V |
| High Level Output Voltage | VOH1 | DO | 4.5V≤VCC≤5.5V IOH=-400µA | VCC-0.4 | | V |
| Output voltage | VOH2 | | 2.7V≤VCC<4.5V IOH=-200µA | 0.7xVCC | | V |
| Low Level Output Voltage | VOL1 | | 4.5V≤VCC≤5.5V IOH=1.0mA | | 0.4 | V |
| | VOL2 | | 2.7V≤VCC<4.5V IOH=1.0mA | | 0.4 | V |

(1) All input pins are connected to either VCC or GND.

(2) DO=OPEN

(2) Analog Section

(2-1) VDD=4.5V to 5.5V

(VCC=2.7V to 5.5V, VDD=4.5V to 5.5V, GND, VSS=0V, Ta=-40°C to +85°C)

| Parameter | Symbol | Pin | Conditions | Min | Тур | Max | Units |
|---|-----------------|----------|---------------------------|---------|-----|---------|-------|
| Power Supply 1 (Analog Section) | VDD1 | VDD | | 4.5 | 5.0 | 5.5 | V |
| Power Dissipation 1 (Analog Section) | IDD1 | | AOx=OPEN | | | 7.0 | mA |
| Resolution | Res | | | | 8 | | bits |
| Integral (3) Non-Linearity: INL | LE | AO1 | AOx=OPEN 0.05V≤AO | -1.5 | | 1.5 | LSB |
| Differential Non-Linearity: DNL | D _{LE} | AO12 | ≤VDD-0.1V | -1.0 | | 2.0 | LSB |
| Buffer-AMP Minimum Output Voltage 1 | VAOL1 | | IAL=0µA Data=00(Hex) | GND | | 0.05 | V |
| Buffer-AMP Minimum Output Voltage 2 | VAOL2 | | IAL=500µA Data=00(Hex) | -0.1 | | 0.1 | V |
| Buffer-AMP Minimum Output Voltage 3 | VAOL3 | | IAH=500µA Data=00(Hex) | GND | | 0.1 | V |
| Buffer-AMP Minimum Output Voltage 4 | VAOL4 | | IAL=1mA Data=00(Hex) | -0.2 | | 0.2 | V |
| Buffer-AMP Minimum Output Voltage 5 | VAOL5 | AO1 | IAH=1mA Data=00(Hex) | GND | | 0.2 | V |
| Buffer-AMP Maximum Output Voltage 1 | VAOH1 | AO12 | IAH=0µA Data=FF(Hex) | VDD-0.1 | | VDD | V |
| Buffer-AMP Maximum Output Voltage 2 | VAOH2 | | IAL=500µA Data=FF(Hex) | VDD-0.2 | | VDD | V |
| Buffer-AMP Maximum Output Voltage 3 | VAOH3 | | IAH=500µA Data=FF(Hex) | VDD-0.2 | | VDD+0.2 | V |
| Buffer-AMP Maximum Output Voltage 4 | VAOH4 | | IAL=1mA Data=FF(Hex) | VDD-0.3 | | VDD | V |
| Buffer-AMP Maximum Output Voltage 5 | VAOH5 | | IAH=1mA Data=FF(Hex) | VDD-0.3 | | VDD+0.3 | V |

(3) Integral Non-Linearity is the error between the actual line and the ideal line. The ideal line exhibits a perfect linear D/A converter output characteristic between the input digital data"00" and the input digital data"FF".

(2-2) VDD=2.7V to 3.6V

(VCC=2.7V to 3.6V, VDD=2.7V to 3.6V, GND, VSS=0V, Ta=-40°C to +85°C)

| Parameter | Symbol | Pin | Conditions | Min | Тур | Max | Units | | | | | | | |
|---|-----------------|------|---------------------------|---------|------|---------|-------|--|--|---------------------------|------|--|-----|---|
| Power Supply 2 (Analog Section) | VDD2 | VDD | | 2.7 | | 3.6 | V | | | | | | | |
| Power Dissipation 2 (Analog Section) | IDD2 | | AOx=OPEN | | | 4.0 | mA | | | | | | | |
| Resolution | Res | | | | 8 | | bits | | | | | | | |
| Integral (4) Non-Linearity: INL | LE | | AOx=OPEN 0.15V≤AO | -1.5 | | 1.5 | LSB | | | | | | | |
| Differential Non-Linearity: DNL | D _{LE} | AO1 | ≤VDD-0.15V | -1.0 | | 2.0 | LSB | | | | | | | |
| Output Voltage for Input Data "05" | | AO12 | AOx=OPEN | | 0.1 | 0.15 | V | | | | | | | |
| Output Voltage for Input Data "FA" | | | VDD=3.3V | 3.15 | 3.25 | | V | | | | | | | |
| Buffer-AMP Minimum Output Voltage 6 | VAOL6 | | IAL=0µA Data=00(Hex) | GND | | 0.05 | V | | | | | | | |
| Buffer-AMP Minimum Output Voltage 7 | VAOL7 | | IAL=250µA Data=00(Hex) | -0.1 | | 0.1 | V | | | | | | | |
| Buffer-AMP Minimum Output Voltage 8 | VAOL8 | | IAH=250µA Data=00(Hex) | GND | | 0.1 | V | | | | | | | |
| Buffer-AMP Minimum Output Voltage 9 | VAOL9 | | | | | | | | | IAL=500µA Data=00(Hex) | -0.2 | | 0.2 | V |
| Buffer-AMP Minimum Output Voltage 10 | VAOL10 | AO1 | IAH=500µA Data=00(Hex) | GND | | 0.2 | V | | | | | | | |
| Buffer-AMP Maximum Output Voltage 6 | VAOH6 | AO12 | IAH=0µA Data=FF(Hex) | VDD-0.1 | | VDD | V | | | | | | | |
| Buffer-AMP Maximum Output Voltage 7 | VAOH7 | | IAL=250µA Data=FF(Hex) | VDD-0.2 | | VDD | V | | | | | | | |
| Buffer-AMP Maximum Output Voltage 8 | VAOH8 | | IAH=250µA Data=FF(Hex) | VDD-0.2 | | VDD+0.2 | V | | | | | | | |
| Buffer-AMP Maximum Output Voltage 9 | VAOH9 | | IAL=500µA Data=FF(Hex) | VDD-0.3 | | VDD | V | | | | | | | |
| Buffer-AMP Maximum Output Voltage 10 | VAOH10 | | IAH=500µA Data=FF(Hex) | VDD-0.3 | | VDD+0.3 | V | | | | | | | |

(4) Integral Non-Linearity is the error between the actual line and the ideal line. The ideal line exhibits a perfect linear D/A converter output characteristic between the input digital data"05" and the input digital data"FA".

AC Characteristics

(1) CS I/F, LD I/F: Common Timing

| () | VCC=2.7V to 5.5V. | VDD=4.5V to 5.5V | ' or 2.7V to 3.6V. G | GND. VSS=0V. T | a=-40°C to +85°C) |
|-------|-------------------|------------------|---|----------------|-------------------|
| · · · | | | ••••••••••••••••••••••••••••••••••••••• | | |

| - | | | | | |
|------------------------------|--------|-------------|-----|-----|-------|
| Parameter | Symbol | Conditions | Min | Max | Units |
| VCC Rise Time | tVCR | | | 50 | ms |
| Auto Address Hold Time | tVAH | | 3.5 | | ms |
| Auto Read Time | tPOR | Test Load 2 | | 3.5 | ms |
| ECL "H" Pulse Width | tECW1 | *1 | 100 | | ns |
| | tECW2 | *2 | 250 | | ns |
| External Call Time | tECL | Test Load 2 | | 3.5 | ms |
| Address Set Up Time | tESU1 | *1 | 50 | | ns |
| | tESU2 | *2 | 100 | | ns |
| ECL Address Hold Time | tEAH | | 3.5 | | ms |
| Repeat Call Prohibition Time | tECC1 | *1 | 20 | | ns |
| | tESCC2 | *2 | 100 | | ns |

*1: 4.5V≤VCC≤5.5V

*2: 2.7V ≤ VCC < 4.5V

<AUTO READ>



<ECL FUNCTION>



(2) CS I/F Timing

| Parameter | Symbol | Conditions | Min | Max | Units |
|-------------------------|--------|--------------------|-------|-----|-------|
| Clock "L" Pulse Width | tCKL1 | * | 5 200 | | ns |
| | tCKL2 | * | 5 500 | | ns |
| Clock "H" Pulse Width | tCKH1 | * | 5 200 | | ns |
| | tCKH2 | * | 500 | | ns |
| Clock Rising Time | tCr | | | 200 | nc |
| Clock Falling Time | tCf | | | 200 | ns |
| Data Set Up Time | tDSU1 | * | 5 30 | | ns |
| | tDSU2 | * | | | ns |
| Data Hold Time | tDHD1 | * | | | ns |
| | tDHD2 | *(| | | ns |
| CS Set Up Time | tCSU1 | *; | | | ns |
| | tCSU2 | * | | | ns |
| CS Hold Time | tCCH | | 200 | | ns |
| CS "H" Hold Time | tCSH | DAC etc. *3, *4, * | | | ns |
| | | *3, *4, * | | | ns |
| | | WRITE * | - | | ms |
| | | CALL, READ | 15 | | μs |
| | | ALL CALL | 3.5 | | ms |
| Data Output Enable Time | tDOD1 | * | - | 200 | ns |
| | tDOD2 | * | | 500 | ns |
| Data Output Float Delay | tDOZ1 | * | - | 200 | ns |
| | tDOZ2 | * | - | 500 | ns |
| Data Output Delay | tDOC1 | Test Load 1 * | - | 170 | ns |
| | tDOC2 | * | - | 300 | ns |
| D/A Output Setting Time | tCSD | DAC Test Load | | 200 | μs |
| | | CALL Test Load 2 | | 250 | μs |
| | | ALL CALL Test Load | | 3.5 | ms |
| Status Set Up Time | tSSU | | 100 | | ns |
| Status Hold Time | tSHD1 | * | | | ns |
| | tSHD2 | * | 6 250 | | ns |

*3: Please refer to "DAC etc" regarding \overline{CS} "H" Hold Time before status mode execute.

*4: If READY/BUSY="H" is confirmed in status mode in the WRITE mode, the $\overline{\text{CS}}$ pin can be changed to "L" shorter than the values specified on above. Please refer to "DAC etc" regarding $\overline{\text{CS}}$ "H" Hold Time in case that AK9813B to be

connected in cascade is under programming cycle (READY/BUSY="L").

*5: 4.5V ≤ VCC ≤ 5.5V

*6: 2.7V≤VCC<4.5V

<Input / Output Waveform>



<STATUS Output>



(3) LD I/F Timing

| Parameter | Symbol | Conditions | Min | Max | Units |
|--------------------------|--------|----------------------|-----|-----|-------|
| Clock "L" Pulse Width | tCKL1 | *5 | 200 | | ns |
| | tCKL2 | *6 | 500 | | ns |
| Clock "H" Pulse Width | tCKH1 | *5 | 200 | | ns |
| | tCKH2 | *6 | 500 | | ns |
| Clock Rising Time | tCr | | | 200 | |
| Clock Falling Time | tCf | | | 200 | ns |
| Data Set Up Time | tDCH1 | *5 | 30 | | ns |
| • | tDCH2 | *6 | 150 | | ns |
| Data Hold Time | tCHD1 | *5 | 60 | | ns |
| | tCHD2 | *6 | 150 | | ns |
| Load Set Up Time | tCHL | | 200 | | ns |
| Load Hold Time | tLDC1 | *5 | 100 | | ns |
| | tLDC2 | *6 | 250 | | ns |
| Load "H" Pulse Width | tLDH1 | modes except *5 | 100 | | ns |
| | tLDH2 | READ mode *6 | 250 | | ns |
| | tLDH3 | READ mode | 5 | | μs |
| Data Output Delay | tDO1 | Test Load 1 *5 | | 170 | ns |
| | tDO2 | Test Load 1 *6 | | 300 | ns |
| D/A Output Setting Time | tLDD | DAC Test Load 2 | | 200 | μs |
| | | CALL Test Load 2 | | 250 | μs |
| | | ALL CALL Test Load 2 | | 3.5 | ms |
| Address Set Up Time | tASU1 | *5 | 100 | | ns |
| | tASU2 | *6 | 200 | | ns |
| Write Address Hold Time | tWAHD1 | *5 | 20 | | ns |
| | tWAHD2 | *6 | 100 | | ns |
| Programming Cycle | tWRT | *7 | | 7 | ms |
| Ready Signal Delay | tRYD | Test Load 1 | | 0.8 | μs |
| Repeat Write Prohibition | tRYH1 | Test Load 1 *5 | 20 | | ns |
| Time | tRYH2 | Test Load 2 *6 | 100 | | ns |
| Read Hold Time | tRHD | CALL, READ mode | 15 | | μs |
| | | ALL CALL mode | 3.5 | | ms |
| Read Address Hold Time | tRAHD | CALL, READ mode | 15 | | μs |
| | | ALL CALL mode | 3.5 | | ms |

*7: If READY/BUSY="L" is confirmed in status mode in the WRITE mode, the next operation can be started.

<Input / Output Waveform>

<Data Timing>



<WRITE mode>



* Please refer to the data timing regarding the input timing for the DI pin.

<CALL mode> <ALL CALL mode> <READ mode>



* Please refer to the data timing regarding the input timing for the DI pin.



Test Load 1





•AC test point

| Digital Input / Output Level | : | 50% / 20% of VCC |
|------------------------------|---|------------------|
| Analog Output Level | : | 90% / 10% of VCC |

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