



## Features

- 3.3 and 5 VDC voltage supply option
  - Absolute
  - Bushing or servo mount
  - Non-contacting magnetic technology
  - Small size
  - CMOS and TTL compatible
  - Resolution: 1024 positions
  - Long life
  - High operating speed
  - Highly repeatable
  - Sealed option
  - Magnetic technology

# EMS22A - Non-Contacting Absolute Encoder

## Electrical Characteristics

Resolution .....	1024 positions
Insulation Resistance (500 VDC).....	1,000 megohms
Electrical Travel.....	Continuous
Supply Voltage .....	5.0 VDC $\pm$ 10 %, 3.3 VDC $\pm$ 10 %
Supply Current .....	20 mA maximum
Output Voltage	
Low Output Level .....	Vss+0.4 V maximum
High Output Level.....	Vdd-0.5 V minimum
Output Current	
With 4.5 VDC Supply Voltage .....	4 mA maximum
With 3.0 VDC Supply Voltage .....	2 mA maximum
Rise/Fall Time (Incremental Output) .....	500 ns maximum
Shaft RPM (Ball Bearing).....	10,000 rpm maximum
Linearity .....	0.5 %
Accuracy	
Nominal .....	$\pm$ 0.7 ° or better
Worst Case.....	$\pm$ 1.4 °
Output Transition Noise .....	0.12 ° RMS max.

## **Environmental Characteristics**

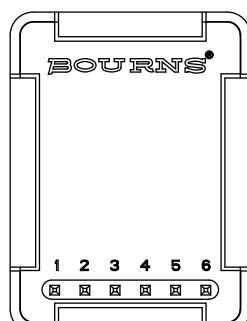
Operating Temperature Range.....	-40 °C to +125 °C (-40 °F to +257 °F)
Storage Temperature Range.....	-55 °C to +125 °C (-67 °F to +257 °F)
Humidity .....	MIL-STD-202, Method 103B, Condition B
Vibration .....	15 G
Shock .....	50 G
Rotational Life	
S Bushing (@1,000 rpm).....	100,000,000 revolutions
T & W Bushings (@1,000 rpm with 250 g side load) .....	50,000,000 revolutions
IP Rating.....	IP 65

## Mechanical Characteristics

## Pin Configuration

<b>Output Type</b>	<b>Pin 1 (DI)</b>	<b>Pin 2 (CLK)</b>	<b>Pin 3</b>	<b>Pin 4 (DO)</b>	<b>Pin 5</b>	<b>Pin 6</b>
Absolute	Digital Input	Clock	GND	Digital Output	VCC*	CS

\* Can be 5 or 3.3 VDC depending on the version.



\*RoHS Directive 2002/95/EC Jan. 27, 2003 including annex and RoHS Recast 2011/65/EU June 8, 2011.

Specifications are subject to change without notice.

The device characteristics and parameters in this data sheet can and do vary in different applications and actual device performance may vary over time.

Users should verify actual device performance in their specific applications.

## Applications

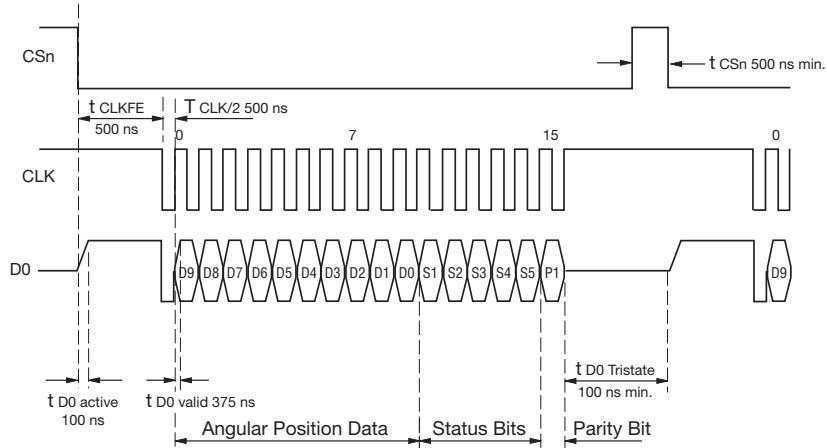
- Material handling equipment
- Brushless DC motor commutation
- Robotics
- Automotive
- Industrial automation
- Petroleum refinery
- Medical
- Office equipment
- Audio and broadcast equipment

## EMS22A - Non-Contacting Absolute Encoder

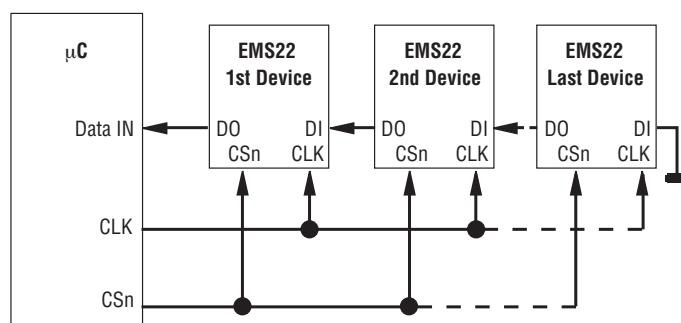
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### Output Type Waveform and Variant Table

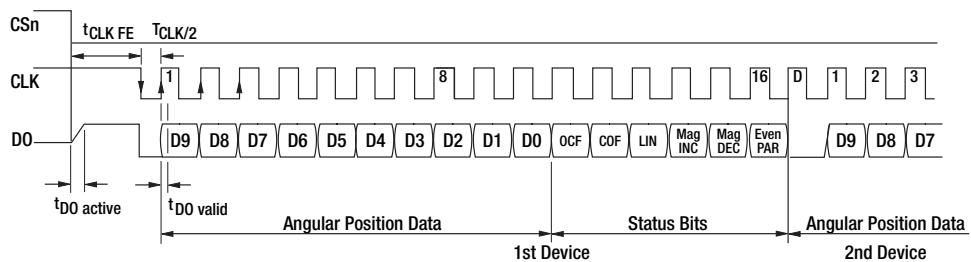
#### Absolute Output



Data Content	Description
D9:D0	Absolute angular position data
S1	End of offset compensation algorithm
S2	Cordic overflow indicating an error in cordic part
S3	Linearity alarm
S4	Increase in magnitude
S5	Decrease in magnitude
P1	Even parity for detecting bits 1-15 transmission error



Daisy Chain Hardware Configuration



Daisy Chain Mode Data Transfer

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Consult factory for options not shown, including:

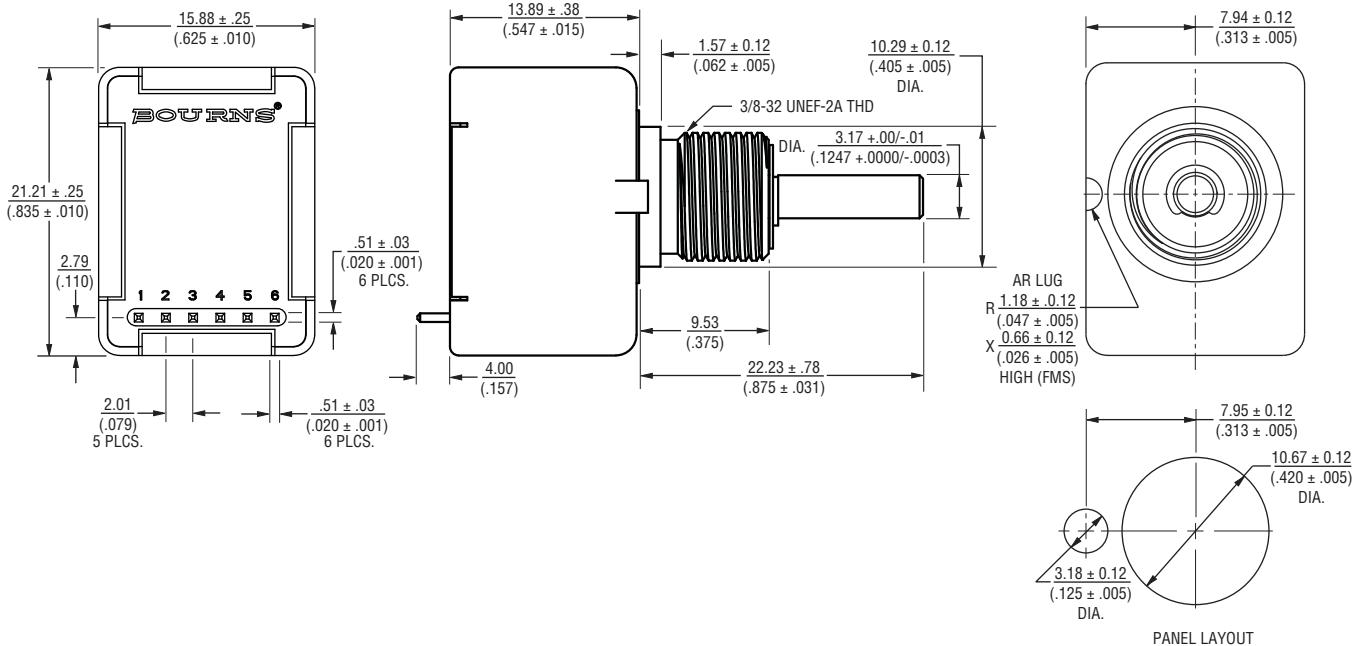
- Wire lead or cable options
- Connectors
- Non-standard resolutions
- Special shaft/bushing sizes and features
- Special performance characteristics
- PCB mounting bracket

## EMS22A - Non-Contacting Absolute Encoder

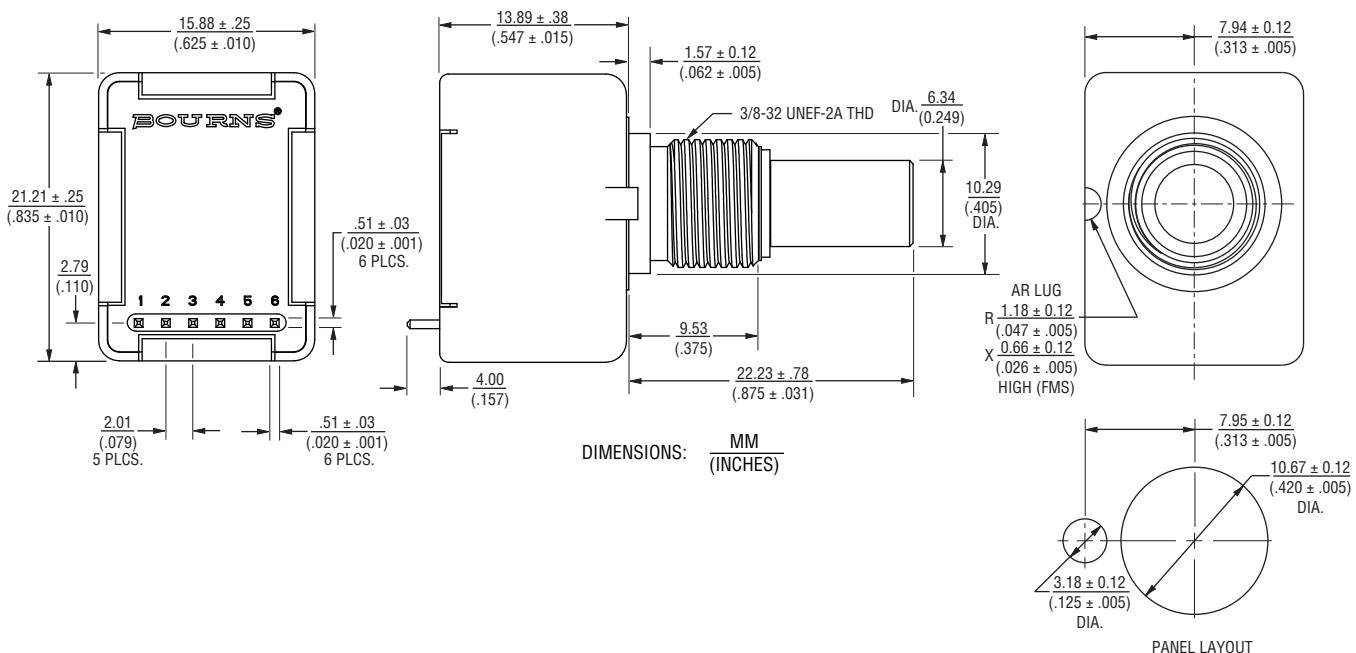
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### Product Dimensions

#### Shaft Style D (Bushing T)



#### Shaft Style B (Bushing S)



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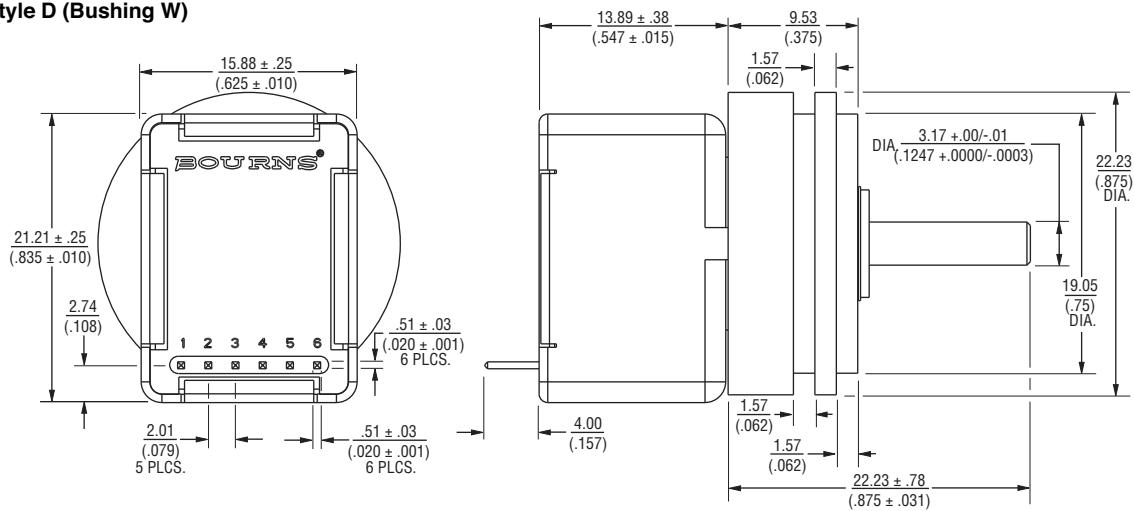
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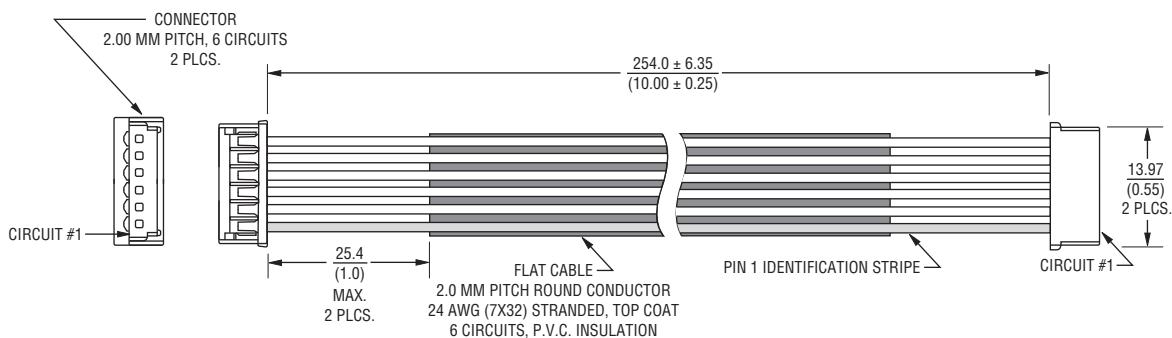
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## Product Dimensions

### Shaft Style D (Bushing W)



## Cable Assembly



DIMENSIONS:  $\frac{\text{MM}}{(\text{INCHES})}$

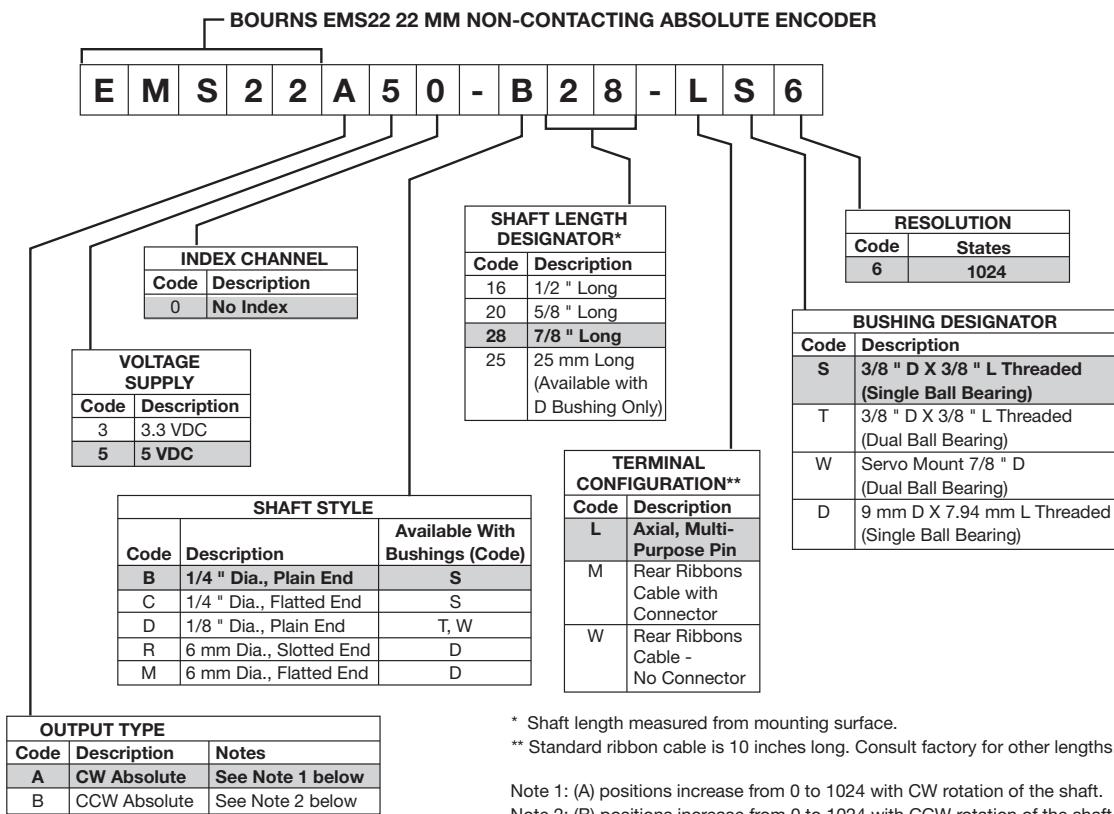
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## How To Order



\* Shaft length measured from mounting surface.

\*\* Standard ribbon cable is 10 inches long. Consult factory for other lengths.

Note 1: (A) positions increase from 0 to 1024 with CW rotation of the shaft.

Note 2: (B) positions increase from 0 to 1024 with CCW rotation of the shaft.